

# A tale of two Rawlsian criteria

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19 August 2019

Online at https://mpra.ub.uni-muenchen.de/102996/ MPRA Paper No. 102996, posted 28 Sep 2020 10:31 UTC

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## 18th September 2020

#### ABSTRACT

This work considers optimization problems under Rawls and maximin with multiple discount factors criteria. It proves that though these criteria are different, they have the same optimal value and solution.

Keywords: Rawls criterion, Maximin principle, multiple discount rates.

**JEL** classification numbers: C61, D11, D90.

#### 1 Introduction

Consider the following classical question: given a stock of a renewable resource, what would be the best inter-temporal exploitation of it, considering the welfare of both current and future generations?

The famous Ramsey criterion, which uses a constant discount rate and is used largely in research into economic dynamics, is criticized for its weak weighting

<sup>\*</sup>The author would like to thank Stefano Bosi, for many helpful comments. He is also grateful to the LABEX MME-DII (ANR-11-LBX-0023-01) for supports during the writing of this article. This article is finished during the period the author worked as  $d\acute{e}l\acute{e}gu\acute{e}$  in the Theoretical Economics Team UMR 8545 at CNRS, Paris School of Economics (campus Jourdan). He acknowledges the members of PSE and CNRS for the warm welcome and excellent working conditions.

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parameters for generations in the distant future. The evaluation of each utilities stream is quasi-determined by a finite number of generations. This raises the concerns that following the Ramsey criterion, the economy does not leave enough resource for the future generation.

In the classical work "Theory of justice", Rawls [17] assumes that if one is hidden behind a *veil of ignorance*, with total lack of information about the condition into which she/he will be born, the economic agent should choose the maximization of the least favoured generation. Specifically, given a inter-temporal consumption streams, her evaluation criterion of inter-temporal utilities streams should be

$$U(c_0, c_1, c_2, \dots) = \inf_{s \ge 0} u(c_s),$$

where  $u(c_t)$  is the utility of the  $t^{th}$  generation, given  $c_t$  as the consumed resource. We can consider the Rawls's question in another way: the economic agent may be ambiguous about what is the "good" discount factor to choose in evaluating utilities streams. Her set of possible discount factors is (0,1). Having total lack of information, for a given consumption stream  $\{c_s\}_{s=0}^{\infty}$ , she/he should evaluate it as<sup>1</sup>

$$U(c_0, c_1, c_2, \dots) = \inf_{\delta \in (0,1)} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^s u(c_s) \right].$$

This criterion can also be considered as an application of Rawls's spirit in the configuration where disagreements exists between people in the economy about how to discount the future. The social planer choose a criterion that maximizes the least favoured person.

Naturally, this raises the question of the behaviour of the economy under the Rawls criteria. The first Rawls criterion is well studied in the seminar contributions of Arrow [2], Solow [15] and Calvo [4]. The result is clear: the behaviour of the

<sup>&</sup>lt;sup>1</sup>For the axiomatic foundation and discussion about the importance of the normalizing term  $1-\delta$ , see Chambers and Echenique [5] and Drugeon *et al* [9]. Observe that for any  $0<\delta<1$ , we have  $(1-\delta)\sum_{s=0}^{\infty}\delta^s=1$ .

economy depends strongly on the initial stock. If the stock of a renewable resource is below the *golden rule* (the level of stock allowing a maximal level of constant consumption), the optimal exploitation strategy is to ensure that the stock remains constant over time. In the case of abundant stock of a renewable resource, which is higher than the *golden rule*, there is an infinite number of solutions and every optimal path converges decreasingly to this level.

The purpose of this work is to study the same question under the second Rawls criterion. We prove that for a low level of resource stock (under the golden rule), the unique solution is to keep the stock constant through time. Moreover, the solutions under the two criteria coincide. For the case where the resource is abundant, the solution under the first criterion is the one under the second, and the value functions are equal.

This work is organized as follows. Section 2 introduces the two Rawlsian problems and the main properties of the first one and solves the second one. Section 3 discusses different criteria studied in the literature.

## 2 THE TWO RAWLSIAN CRITERIA

#### 2.1 Fundamentals

Denote by u the instantaneous utility function and f the regeneration function of the renewable resource. These two functions are supposed to be strictly increasing and concave. Assume further that the concavity of utility function is strict and  $f'(0) > \frac{1}{\delta}$  and  $f'(\infty) < 1$ .

Let  $x_s$  be the stock at time s, the agent divides the production  $f(x_s)$  into two parts: the consumptions  $c_s$  and the investment for tomorrow,  $x_{s+1}$ . For any date s, we have  $c_s + x_{s+1} \le f(x_s)$ .

For any given capital stock  $x_0 \ge 0$ , denote by  $\Pi(x_0)$  the set of feasible paths of stock  $\{x_s\}_{s=0}^{\infty}$ : for any s,  $0 \le x_{s+1} \le f(x_s)$ .

Denote by  $\overline{x}$  the golden rule, the capital accumulation corresponding to the maximum level of constant consumption<sup>2</sup>:  $\overline{x} = \operatorname{argmax}(f(x) - x)$ . By the concavity of f, this value  $\overline{x}$  is solution to the equation f'(x) = 1.

The dynamic programming literature, culminating in Stokey and Lucas (with Prescott) [16] considers the following problem. For given  $x_0 \geq 0$  and discount factor  $0 < \delta < 1$ , the agent solve the optimization program, well-known under the name the Ramsey problem:

$$v(x_0) = \max_{\Pi(x_0)} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^s(c_s) \right],$$
  
s.t  $0 \le c_s + x_{s+1} \le f(x_s)$ , for all  $s \ge 0$ .

It is well-known in dynamic programming literature<sup>3</sup> that, under suitable conditions, such as the concavity of functions u and f, the value function v is solution to the following functional equation:

$$v(x) = \max_{0 \le y \le f(x)} [u(f(x) - y) + \delta v(y)],$$

for every  $x \geq 0$ .

Under the strict concavity of the utility function and the regeneration function, there exists unique optimal path  $\{x_s\}_{s=0}^{\infty}$ , satisfying

$$v(x_s) = u(f(x_s) - x_{s+1}) + \delta v(x_{s+1}),$$

for every  $s \geq 0$ .

The optimal capital accumulation path corresponding to  $\delta$  is monotonic and converges to  $x^{\delta}$ , the solution to the equation  $f'(x) = \frac{1}{\delta}$ .

As the functions u and f satisfy the standard conditions in growth theory, for each discount factor  $\delta$ , the optimal path of the Ramsey problem corresponding to

<sup>&</sup>lt;sup>2</sup>The constant sequence  $(\overline{x}, \overline{x}, \dots)$  generates a constant sequence of consumption  $(\overline{c}, \overline{c}, \dots)$ , where  $\overline{c} = f(\overline{x}) - \overline{x}$ .

<sup>&</sup>lt;sup>3</sup>See Stokey and Lucas (with Prescott) [16], chapter 4.

 $\delta$  converges monotonically to  $x^{\delta}$  the solution to

$$f'(x) = \frac{1}{\delta}.$$

Moreover, we can verify that

$$\lim_{\delta \to 0} x^{\delta} = 0,$$

$$\lim_{\delta \to 1} x^{\delta} = \overline{x}.$$

We will use these properties in Section 2.3.

#### 2.2 The classical Rawls criterion

The famous Rawls criterion, embedded in the optimal growth context, can be considered as the following optimization problem. The economic agent solves:

$$\max\left[\inf_{s\geq 0}u(c_s)\right],$$

under the constraint  $c_t + x_{s+1} \le f(x_s)$  for all s, with  $x_0 > 0$  given.

For each feasible stock path  $\mathbf{x} = \{x_s\}_{s=0}^{\infty}$ , the inter-temporal evaluation of the corresponding consumption path  $\{c_s\}_{s=0}^{\infty}$  with  $c_s = f(x_s) - x_{s+1}$  for any  $s \geq 0$ , is given as

$$\nu(\mathbf{x}) = \inf_{s \ge 0} u(c_s).$$

This problem is well studied in Arrow [2], Solow [15] and Calvo [4] whose results can be resumed in Lemma 2.1 and Proposition 2.1.

Lemma 2.1 sets forth the foundation for the existence of optimal solution and fundamental properties of the value function.

LEMMA 2.1. i) For any  $x_0 \ge 0$ , the set of feasible paths  $\Pi(x_0)$  is compact in product topology.

- ii) Value function  $\nu$  is upper semi-continuous with respect to the product topology.
- iii) There exists  $\mathbf{x}^* \in \Pi(x_0)$  such that

$$uig(oldsymbol{x}^*ig) = \max_{oldsymbol{x}\in\Pi(x_0)}
uig(oldsymbol{x}ig).$$

Proposition 2.1 gives the behaviour of the optimal path, which depends strongly on the initial condition, with the golden rule  $\overline{x}$  as the critical threshold.

PROPOSITION 2.1. i) Consider the case  $0 \le x_0 \le \overline{x}$ . The problem has unique solution  $\mathbf{x}^* = (x_0, x_0, \ldots)$  and

$$\max_{\boldsymbol{x} \in \Pi(x_0)} \nu(\boldsymbol{x}) = \nu(\boldsymbol{x}^*)$$
$$= u \left( f(x_0) - x_0 \right).$$

ii) Consider  $x_0 > \overline{x}$ . The problem has an infinite number of solutions which all converge to  $\overline{x}$ . And

$$\max_{\boldsymbol{x} \in \Pi(x_0)} \nu(\boldsymbol{x}) = u\left(f(\overline{x}) - \overline{x}\right).$$

For initial capital stock  $x_0$  smaller than  $\overline{x}$ , the optimal choice is to remain in the status quo. The unique solution  $\mathbf{x}^*$  satisfies  $x_s^* = x_0$  for any  $s \geq 0$ . The optimal value is  $u(f(x_0) - x_0)$ . For  $x_0$  bigger than  $\overline{x}$ , there exists an infinite number of solution, every optimal stock path converges to  $\overline{x}$  and the optimal value is  $u(f(\overline{x}) - \overline{x})$ .

# 2.3 THE SECOND RAWLSIAN CRITERION AND THE EQUIVALENCE BETWEEN THE TWO CRITERIA

This section is devoted to the study of the second Ralws criterion. For each feasible stock path  $\mathbf{x} = \{x_s\}_{s=0}^{\infty}$ , let

$$\hat{\nu}(\mathbf{x}) = \inf_{\delta \in (0,1)} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^s u(c_s) \right].$$

In [9], Drugeon *et al* consider the optimization problem with multiple discount factors under the *maximin* criteria<sup>4</sup>. Let  $\mathfrak{D} = [\underline{\delta}, \overline{\delta}]$  represent the set of possible discount factors, the economic agent solves:

$$\max \min_{\delta \in \mathfrak{D}} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^{s} u(c_{s}) \right]$$
  
s.c  $c_{s} + x_{s+1} \leq f(x_{s})$  for any  $s$ ,  
 $x_{0}$  is given.

By technical difficulties relying with the fixed point arguments, Drugeon *et al* [9] assume that  $\mathfrak{D}$  is a closed set belonging to (0,1):  $0 < \underline{\delta} \leq \overline{\delta} < 1$ . Proposition 2.2, proven in Drugeon *et al* [9], gives a detailed description of the optimal path under the maximin criteria with multiple discount factors.

Proposition 2.2. Assume that  $0 < \underline{\delta} \leq \overline{\delta} < 1$ . Let  $\chi^*$  denote the unique optimal path for the maximin problem.

- i) For  $x_0 \leq x^{\underline{\delta}}$ ,  $\chi^*$  coincides with the optimal path of the Ramsey problem with discount factor  $\underline{\delta}$ , is increasing and converges to  $x^{\underline{\delta}}$ .
- ii) For  $x^{\underline{\delta}} \leq x_0 \leq x^{\overline{\delta}}$ , for any  $s, x_s^* = x_0$ . The optimal path  $\chi^*$  coincides with the optimal solution of Ramsey problem with discount factor  $\delta$  satisfying  $x^{\delta} = x_0$ .
- iii) For  $x_0 \geq x^{\overline{\delta}}$ ,  $\chi^*$  coincides with the optimal path of the Ramsey problem with

<sup>&</sup>lt;sup>4</sup>The axiomatic foundation can be found in the work of Chambers and Echenique [5].

discount factor  $\overline{\delta}$ , is decreasing and converges to  $x^{\overline{\delta}}$ .

Proposition 2.2 provides us an illustration how optimal paths depend in initial condition under the the maximin criterion.

Naturally, under the result in Proposition 2.2 we can guess that for  $\mathfrak{D} = (0,1)$  (the under bound  $\underline{\delta}$  converges to zero, and the upper bound  $\overline{\delta}$  converges to 1), the two Ralwsian problems have the same value function: we hope to get

$$\max_{\mathbf{x} \in \Pi(x_0)} \nu(\mathbf{x}) = \max_{\mathbf{x} \in \Pi(x_0)} \hat{\nu}(\mathbf{x}).$$

Propositions 2.3 confirms this conjecture, and represents the main result of this article.

Proposition 2.3. For any  $x_0 \ge 0$ , we have

$$\max_{\chi \in \Pi(x_0)} \inf_{s \ge 0} u(f(x_s) - x_{s+1}) = \max_{\chi \in \Pi(x_0)} \left[ \inf_{\delta \in (0,1)} (1 - \delta) \sum_{s=0}^{\infty} u(f(x_s) - x_{s+1}) \right].$$

*Proof.* To facilitate the exposition, for each  $0 < \delta < 1$ , denote by  $\{x_s(\delta)\}_{s=0}^{\infty}$  the optimal path of Ramsey problem corresponding to the discount factor  $\delta$ .

Observe that for any feasible path of stock  $\{x_s\}_{s=0}^{\infty}$  belonging to  $\Pi(x_0)$ :

$$\inf_{s \ge 0} u(f(x_s) - x_{s+1}) \le \inf_{\delta \in (0,1)} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^s u(f(x_s) - x_{s+1}) \right].$$

This implies

$$\max_{\chi \in \Pi(x_0)} \min_{s \ge 0} u(f(x_s) - x_{s+1}) \le \max_{\chi \in \Pi(x_0)} \left[ \inf_{\delta \in (0,1)} (1 - \delta) \sum_{s=0}^{\infty} \delta^s u(f(x_s) - x_{s+1}) \right].$$

Now we will prove the converse inequality.

Consider first the case  $0 < x_0 < \overline{x}$ . Fix  $0 < \underline{\delta} < \overline{\delta} < 1$  such that  $x^{\underline{\delta}} < x_0 < x^{\overline{\delta}}$ .

Define  $\chi^* = (x_0, x_0, \dots)$ , which is the unique optimal path for the *maximin* criterion with the set of discount rates  $\mathfrak{D} = [\underline{\delta}, \overline{\delta}]$ . For any feasible path  $\chi \neq \chi^*$ ,

following Drugeon et al [9], we have

$$\inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} u(f(x_s) - x_{s+1}) \right] \leq \inf_{\underline{\delta} \leq \delta \leq \overline{\delta}} \left[ (1-\delta) \sum_{s=0}^{\infty} u(f(x_s) - x_{s+1}) \right]$$

$$< \inf_{\underline{\delta} \leq \delta \leq \overline{\delta}} \left[ (1-\delta) \sum_{s=0}^{\infty} u(f(x_s^*) - x_{s+1}^*) \right]$$

$$= u(f(x_0) - x_0)$$

$$= \max_{\chi \in \Pi(x_0)} \left[ \inf_{s \geq 0} u(f(x_s) - x_{s+1}) \right].$$

This implies that the two Rawlsian problems have the same maximum value and unique solution  $\chi^*$ .

Now consider the case  $x_0 > \overline{x}$ . The idea of the proof is that for any  $\delta$ , the sequence  $\{x_s(\delta)\}_{s=0}^{\infty}$  converges to  $x^{\delta}$  with a speed that is sufficiently high and independent with the choice of  $\delta$ .

We prove that for any  $\epsilon > 0$ , there exists  $T(\epsilon)$  such that for any  $T \geq T(\epsilon)$ , any  $0 < \delta < 1$ , we have

$$x^{\delta} < x_T(\delta) < \overline{x} + \epsilon.$$

For each  $0 < \delta < 1$ , consider a time s satisfying  $x_0 \ge x_1(\delta) \ge \cdots \ge x_{s+1}(\delta) \ge \overline{x} + \epsilon$ . Observe that  $f'(\overline{x} + \epsilon) < 1$ . Let  $f'(\overline{x} + \epsilon) = 1 - \epsilon_1$ , with  $\epsilon_1 > 0$ .

By Euler equations, we have

$$u'(f(x_{s}(\delta)) - x_{s+1}(\delta)) = \delta u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta))f'(x_{s+1}(\delta))$$

$$\leq u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta))f'(x_{s+1}(\delta))$$

$$\leq u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta))f'(\overline{x} + \epsilon)$$

$$\leq u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta)) - \epsilon_{1}u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta))$$

$$\leq u'(f(x_{s+1}(\delta)) - x_{s+2}(\delta)) - \epsilon_{2},$$

for  $\epsilon_2 = \epsilon_1 u'(f(x_0))$ , since  $f(x_0) \ge f(x_{s+1}(\delta)) - x_{s+2}(\delta)$ . Observe that  $\epsilon_2$  does not

depend on  $\delta$ .

We then deduce

$$\epsilon_{2} \leq u' \big( f(x_{s+1}(\delta)) - x_{s+2}(\delta) \big) - u' \big( f(x_{s}(\delta)) - x_{s+1}(\delta) \big)$$

$$= u''(\xi) \left[ \big( f(x_{s+1}(\delta)) - x_{s+2}(\delta) \big) - \big( f(x_{s}(\delta)) - x_{s+1}(\delta) \big) \right]$$

$$= (-u''(\xi)) \left[ \big( f(x_{s}(\delta)) - x_{s+1}(\delta) \big) - \big( f(x_{s+1}(\delta)) - x_{s+2}(\delta) \big) \right],$$

with some  $f(x_{s+1}(\delta)) - x_{s+2}(\delta) \le \xi \le f(x_s(\delta)) - x_{s+1}(\delta)$ . This implies

$$x_{s+1}(\delta) - x_{s+2}(\delta) \le f(x_s(\delta)) - f(x_{s+1}(\delta)) - \frac{\epsilon_2}{-u''(\xi)}.$$

As  $x_{s+1}(\delta) \geq \overline{x} + \epsilon$ , it is easy to verify that

$$f(\overline{x}) - \overline{x} \le f(x_{s+1}(\delta)) - x_{s+2}(\delta)$$

$$\le \xi$$

$$\le f(x_s(\delta)) - x_{s+1}(\delta)$$

$$\le f(x_0).$$

Let

$$a = \sup_{f(\overline{x}) - \overline{x} \le \xi \le f(x_0)} (-u''(\xi)),$$

and

$$\epsilon_3 = \frac{\epsilon_2}{a}$$
.

The value  $\epsilon_3$  is strictly positive and is independent with respect to  $\delta$ . Moreover,

$$x_{s+1}(\delta) - x_{s+2}(\delta) \le f(x_s(\delta)) - f(x_{s+1}(\delta)) - \epsilon_3$$
  
$$\le f'(x_{s+1}(\delta))(x_s(\delta) - x_{s+1}(\delta)) - \epsilon_3$$
  
$$\le x_s(\delta) - x_{s+1}(\delta) - \epsilon_3.$$

Hence for  $T(\epsilon)$  big enough such that  $x_0 - T(\epsilon)\epsilon_3 < 0$ , we have  $x_T(\delta) < \overline{x} + \epsilon$  for any  $T \ge T(\epsilon)$  and for any  $0 < \delta < 1$ . Otherwise we will have  $x_T(\delta) - x_{T+1}(\delta) \le 0$  for some  $T \ge T(\epsilon)$ : a contradiction<sup>5</sup>.

By the independence of  $T(\epsilon)$  in respect to  $\delta$ , combining with result that for  $s \ge T(\epsilon)$ , we have  $x^{\delta} \le x_s(\delta) \le \overline{x} + \epsilon$ , we get the following inequality:

$$\lim_{\delta \to 1} \left[ (1 - \delta) \sum_{s=0}^{\infty} \delta^{s} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$= \lim_{\delta \to 1} \left[ (1 - \delta) \sum_{s=0}^{T(\epsilon)} \delta^{s} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$+ \lim_{\delta \to 1} \left[ \delta^{T(\epsilon)+1} (1 - \delta) \sum_{s=T(\epsilon)+1}^{\infty} \delta^{s-T(\epsilon)-1} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$= \lim_{\delta \to 1} \left[ \delta^{T(\epsilon)+1} (1 - \delta) \sum_{s=T(\epsilon)+1}^{\infty} \delta^{s-T(\epsilon)-1} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$\leq \lim_{\delta \to 1} u \left( f(\overline{x} + \epsilon) - x^{\delta} \right)$$

$$= u \left( f(\overline{x} + \epsilon) - \overline{x} \right).$$

For any feasible path  $\chi \in \Pi(x_0)$ ,

$$\inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^{s} u \left( f(x_{s}) - x_{s+1} \right) \right] \leq \inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^{s} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$\leq \lim_{\delta \to 1} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^{s} u \left( f(x_{s}(\delta)) - x_{s+1}(\delta) \right) \right]$$

$$\leq u \left( f(\overline{x} + \epsilon) - \overline{x} \right).$$

Since  $\epsilon > 0$  is chosen arbitrarily, this implies

$$\inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^s u (f(x_s) - x_{s+1}) \right] \le u (f(\overline{x}) - \overline{x}).$$

 $<sup>^{5}\</sup>mathrm{It}$  is well known that the solution of Ramsey problem converges monotonically to the steady state.

We then have

$$\max_{\mathbf{x} \in \Pi(x_0)} \nu(\mathbf{x}) = \max_{\mathbf{x} \in \Pi(x_0)} \hat{\nu}(\mathbf{x}) = u(f(\overline{x}) - \overline{x}).$$

For a solution of the problem with the second Rawlsian criterion, take for example the sequence  $\hat{\chi} \in \Pi(x_0)$  such that  $\hat{x}_s = \overline{x}$  for any  $s \geq 1$ . For each  $\delta$ ,

$$(1 - \delta) \sum_{s=0}^{\infty} \delta^{s} u \left( f(\hat{x}_{s}) - \hat{x}_{s+1} \right) = (1 - \delta) u \left( f(x_{0}) - \overline{x} \right) + \delta u \left( f(\overline{x}) - \overline{x} \right).$$

Since  $x_0 > \overline{x}$ , the function  $(1 - \delta)u(f(x_0) - \overline{x}) + \delta u(f(\overline{x}) - \overline{x})$  is strictly decreasing in respect to  $\delta$ . This implies

$$\inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^s u \left( f(\hat{x}_s) - \hat{x}_{s+1} \right) \right] = \lim_{\delta \to 1} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^s u \left( f(\hat{x}_s) - \hat{x}_{s+1} \right) \right]$$
$$= u \left( f(\overline{x}) - \overline{x} \right).$$

The proof is completed.

**QED** 

For the case  $x_0$  is smaller than the *the golden rule*, the solutions of two problems coincide. The stock remains constant over time. For the other case, we are ensured that every solution of the problem under the first Ralws criterion is solution under the second one.

COROLLARY 2.1. For any  $x_0 \ge 0$ ,

- i) For  $0 \le x_0 \le \overline{x}$ , the two Rawlsian problems have the same solution  $x^* = (x_0, x_0, x_0, \dots)$ .
- ii) For  $x_0 > \overline{x}$ , every solution under the first Rawlsian criterion is a solution under the second one.

*Proof.* (i) This property is proven using the same the arguments as in the proof of Proposition 2.3.

(ii) Consider some feasible path  $\mathbf{x}^*$  which is a solution of the problem under first Rawls criterion. Since  $u(f(x_s^*) - x_{s+1}^*) \ge u(f(\overline{x}) - \overline{x})$  for any  $s \ge 0$ , for any  $0 < \delta < 1$ ,

$$(1 - \delta) \sum_{s=0}^{\infty} \delta^s u \left( f(x_s^*) - x_{s+1}^* \right) \ge u \left( f(\overline{x}) - \overline{x} \right).$$

This implies

$$\inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^s u \left( f(x_s^*) - x_{s+1}^* \right) \right] \ge u \left( f(\overline{x}) - \overline{x} \right)$$

$$= \max_{\mathbf{x} \in \Pi(x_0)} \inf_{\delta \in (0,1)} \left[ (1-\delta) \sum_{s=0}^{\infty} \delta^s u \left( f(x_s) - x_{s+1} \right) \right].$$

Hence  $\mathbf{x}^*$  is a solution of the problem under second Rawls criterion. QED

### 3 DISCUSSIONS

#### 3.1 RAWLS CRITERIA AND AMBIGUITY AVERSION

In recent decades, a large body of literature has risen in decision theory, enlarging the world of Savage [18], where the famous sure-thing princple is not satisfied. The seminar contribution of Gilboa and Schmeidler [11] considers the behaviour under which the economic agent maximizes the worst scenario. This allows us to make a link to the Rawlsian criteria. Assume that the economic agent must choose a time discounting system to evaluate the inter-temporal consumption streams. The set of possible time discounting is  $\Delta = (\pi_0, \pi_1, \pi_2, ...)$  such that  $\pi_s > 0$  for any s and  $\sum_{s=0}^{\infty} \pi_s = 1$ . Behind the veil of ignorance, every time discounting system is possible. Hence, the criterion under ambiguity aversion is

$$U(c_0, c_1, c_2, \dots) = \inf_{\pi \in \Delta} \left[ \sum_{s=0}^{\infty} \pi_s u(c_s) \right]$$
$$= \inf_{s \ge 0} u(c_s),$$

which is the first Ralws criterion.

Now assume that the economic agent is just ambiguous about the set of time discounting systems satisfying the usual properties as *impatience*, and *stability*. Let  $\mathfrak{D}$  be that set. In Chambers and Echenique [5], we found that:

$$\mathfrak{D} = \{ \pi \in \Delta \text{ such that } \exists \delta \in (0,1) : \pi_s = (1-\delta)\delta^s \text{ for all } s \geq 0 \}.$$

The criterion is then the second Rawlsian one.

#### 3.2 Disussion about some criteria

The Ramsey criterion is criticized about putting privileges for the generations in present and close future. In another way, other criteria, for example the liminf take into account only the distant future. As a way to reconcile these to extremes, Chichilnisky in [6], [7] proposes a criterion satisfying her *No-dictatorship* of present and of future. Her criterion is a convex combination of a Ramsey part and a liminf part<sup>6</sup>. However, because the path optimizing the Ramsey part converges to  $\frac{1}{\beta}$ , otherwise the path optimizing the liminf part converges to the *golden rule*, the capital level that maximizes f(x) - x, solution under non-dictatorship criteria may not exists. It is always difficult taking into account at the same time the efficiency and the equality.

As a response for this challenge, Alvarez-Cuadrado and Van Long [1] consider the convex combination between a Ramsey part and a Rawlsian part, in the continuous time configuration. They give a detailed description of the behaviour of the economy <sup>7</sup>. Another approach is due to Asheim and Ekeland [3], who consider the linear markovian solutions of the problem under Chichilnisky's criterion, and conclude that the liminf part has no effect on the optimal choice.

The overtaking criterion of Gale satisfies the two non-dictatorship properties of Chichilnisky, but this criterion is not complete. If we focus only on the good

<sup>&</sup>lt;sup>6</sup>For a discussion about Chichilnisky's criterion, see Alvarez-Cuadrado and Van Long [1].

<sup>&</sup>lt;sup>7</sup>An analysis for the discrete time configuration is presented in Ha-Huy and Nguyen [12].

programs, the set of feasible paths which differ not too much from the golden rule, as in Dana and Le Van [8], the optimal path converges to the golden rule. As an attempt to avoid the non-completeness problem, Le Van and Morhaim [14] consider the Ramsey problem and study the properties of the solution when the discount rate converges to 1. They prove that the sequence of solutions converge to the solution of problem under Gale's criterion.

#### 3.3 TECHNICAL CONCERNS

The result for the first Rawlsian criterion is based only on the concavity of the function f, and does and we can obtain Lemma 2.1 and Proposition 2.1 without imposing concavity on the utility function u. However, in order to apply results in dynamic programming literature, for solving the problem under the second Rawlsian criterion, we must assume the concavity property for utility function.

And, consider the case where  $f'(\infty) \geq 1$ . Under this assumption,  $\overline{x} = \infty$ . For the two Rawlsian criteria, the only solution is to remain constant. The only remark is that, since the feasible paths could be unbounded, we must assume conditions ensuring the determination of value function and its continuity. For the details, curious readers can refer to the article of Le Van and Morhaim [13], with the most important condition being tail insensitivity property.

And, if  $f'(0) \leq 1$ , every feasible path converges to zero, the two problems become trivial.

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