Testing for spatial autocorrelation: the regressors that make the power disappear

Martellosio, Federico

University of Reading

September 2008
Abstract

We show that for any sample size, any size of the test, and any weights matrix outside a small class of exceptions, there exists a positive measure set of regression spaces such that the power of the Cliff-Ord test vanishes as the autocorrelation increases in a spatial error model. This result extends to the tests that define the Gaussian power envelope of all invariant tests for residual spatial autocorrelation. In most cases, the regression spaces such that the problem occurs depend on the size of the test, but there also exist regression spaces such that the power vanishes regardless of the size. A characterization of such particularly hostile regression spaces is provided.

Keywords: Cliff-Ord test; point optimal tests; power; spatial error model; spatial lag model; spatial unit root.

JEL Classification: C12, C21.
1 Introduction

In recent years, applied economists have become increasingly aware of the consequences of incorrectly ignoring spatial autocorrelation in cross-sectional regression studies. One of these consequences, for instance, is that the OLS estimator of the slope parameters may be inefficient or inconsistent, depending on how the spatial autocorrelation enters the regression model; see, e.g., Anselin (1988). Moreover, even in cases when the OLS estimator of the slope parameters is consistent and does not involve a serious loss of efficiency compared to (a feasible version of) the best linearly unbiased estimator, neglecting spatial autocorrelation may lead to poor assessment of the estimator precision; see, e.g., Cordy and Griffith (1993). To avoid faulty inferences, testing for spatial autocorrelation is now common practice in many economic applications; e.g., Case (1991), De Long and Summers (1991), Besley and Case (1995).

The power of tests for spatial autocorrelation depends, among other things, on the regressors included in the model. In this paper, we are concerned with the impact of regressors on the limiting power achieved by tests of spatial autocorrelation as the spatial autocorrelation increases. The study of power as the autocorrelation increases is important for several reasons. Firstly, there are many empirical applications where unobservable factors lead to large spatial autocorrelation in a regression model; see, e.g., Militino et al. (2004) and Parent and LeSage (2007). Secondly, the properties of inferential procedures that neglect spatial autocorrelation can be very poor if the autocorrelation is large. Thirdly, the case of large spatial autocorrelation has an intrinsic theoretical interest for econometricians, because it is similar to the near unit root case in time series; see, e.g., Fingleton (1999) and Lee and Yu (2008).

The key contribution on the limiting power of tests for spatial autocorrelation is Krämer (2005). Krämer focuses on a Gaussian spatial error model with symmetric weights matrix, and on test statistics that can be expressed as a ratio of quadratic forms in regression errors. The main message of Krämer (2005) is that, for some combinations of the matrix of regressors and of the spatial weights matrix, the power of such tests may vanish as the autocorrelation increases. That is, there are circumstances in which it may be very difficult to detect spatial autocorrelation when the autocorrelation is in fact large. Martellosio (2008) shows that Krämer’s results can be extended to any test for spatial autocorrelation, and to other models, including a spatial lag model. Such extensions stem from the fact that any first-order simultaneous autoregressive (SAR(1)) model tends, as the autocorrelation parameter goes to the right boundary of the parameter space, to a degenerate model. More precisely, any SAR(1) model tends to a family of improper distributions supported on a subspace of the sample space. It is then clear that the limiting power of a test for spatial autocorrelation must disappear if the associated critical region does not intersect that subspace.

This paper aims to investigate the issue, raised in Krämer (2005), of whether there always are regression spaces (i.e., column spaces of the regressor matrix) such that the power vanishes as the autocorrelation increases. For simplicity, we focus on a spatial error model, and on the following tests: the Cliff-Ord test, which is the most popular test for residual spatial autocorrelation, and point optimal invariant tests, which define
the Gaussian power envelope of invariant tests. Our main result is that for any fixed sample size, any fixed size of the tests, and any fixed weights matrix outside a small class of exceptions, the vanishing of the power is an event with positive probability (according to a suitable measure), in the sense that there exists a positive measure set of regression spaces such that the limiting power disappears.

What is more, and somewhat surprisingly, there are also regression spaces such that the limiting power vanishes for all values of the size of the test. We provide a characterization of such regression spaces, which are particularly “hostile” from the point of view of testing for large spatial autocorrelation. The characterization is interesting from an interpretative point of view, and is similar in nature to characterizations of the regressor matrix that minimizes the efficiency of the OLS estimator; see Watson (1955).

The rest of the paper is organized as follows. Section 2 introduces the set-up. Section 3 contains our main results. Section 4 presents the characterization of the particularly hostile regression spaces. Section 5 concludes and indicates possible extensions of our analysis. Proofs and auxiliary lemmata are collected in the appendices.

2 The Testing Problem

We consider a linear regression model

\[ y = X\beta + u, \]  

where \( X \) is a fixed \( n \times k \) matrix of rank \( k < n \), \( \beta \) is a \( k \times 1 \) vector of unknown parameters, and the error vector \( u \) follows a SAR(1) process

\[ u = \rho W u + \varepsilon \]  

(e.g., Whittle, 1954; Cliff and Ord, 1981). Here, \( \rho \) is a scalar unknown parameter; \( W \) is a fixed \( n \times n \) matrix of weights chosen to reflect a priori information on the spatial relations among the \( n \) observational units; \( \varepsilon \) is an \( n \times 1 \) vector of innovations with

\[ \mathbb{E}(\varepsilon) = 0, \quad \text{var}(\varepsilon) = \sigma^2 V, \]

where \( \sigma^2 \) is an unknown positive scalar parameter and \( V \) is a fixed \( n \times n \) symmetric and positive definite matrix.

The results in this paper require only minimal additional restrictions on the above model. As far as \( u \) is concerned, we assume that its density is positive everywhere on \( \mathbb{R}^n \), is larger at 0 than anywhere else, and is continuous in both \( y \) and the parameters \( \sigma^2 \) and \( \rho \). As for \( W \), we assume, for simplicity, that it has at least one (real) positive eigenvalue, and that the largest of the positive eigenvalues of \( W \), to be denoted by \( \lambda_{\text{max}} \), has geometric multiplicity one. Such an assumption is virtually always satisfied in applications of spatial autoregressions.\(^1\)

\(^1\)In particular, by the Perron-Frobenius theorem (e.g., Horn and Johnson, 1985, Ch. 8), our assumption is certainly satisfied if \( W \) is entrywise nonnegative and irreducible (see Section 3.3). Extensions of our set-up to the cases when \( \lambda_{\text{max}} \) is not defined (e.g., \( W \) is nilpotent) or has geometric multiplicity larger than one are straightforward.
In the context of model (1)-(2), we are concerned with testing the null hypothesis of no residual spatial autocorrelation, i.e.,

$$H_0 : \rho = 0.$$ 

The alternative commonly employed is

$$H_a : 0 < \rho < \lambda_{\text{max}}^{-1},$$

which represents positive spatial autocorrelation when, as it is usually the case, all the entries of $W$ are nonnegative.\footnote{Values of $\rho$ that are less than 0 or greater than $\lambda_{\text{max}}^{-1}$ are possible, but rare in applications if the model is correctly specified. Also, note that, in order for model (2) to be invertible (so that $u = (I_n - \rho W)^{-1} \varepsilon$), $\rho$ must be different from the reciprocal of the nonzero real eigenvalues of $W$. All such non-admissible values of $\rho$ are outside $H_a$.}

From now on, we set $V = I_n$, the identity matrix of order $n$, because this does not involve any loss of generality when testing $H_0$ against $H_a$ (if $V \neq I_n$, just premultiply $y$ by $V^{-1/2}$).

One nice property of the above testing problem is that it is unchanged under the transformations $y \rightarrow \gamma y + X\delta$, with $\gamma \in \mathbb{R}\{0\}$ and $\delta \in \mathbb{R}^k$. Accordingly, it is natural to require that a test for that problem is \textit{invariant}, that is, is based on a statistic that is invariant under the same transformations; see, e.g., Lehmann and Romano (2005). It is simple to show that any invariant test for our testing problem is free of nuisance parameters both under $H_0$ (that is, the tests are similar) and under $H_a$; see, e.g., King (1980).

Model (1)-(2) is often referred to as a \textit{spatial error model}. An alternative model, which is popular in economics, is the so-called \textit{spatial lag model} $y = \rho W y + X\beta + \varepsilon$ (see, e.g., Anselin, 2002, for a comparison of the two models). In the latter model, contrary to what happens in the former, $\rho$ affects also $E(y)$. Because this changes the problem of testing $\rho = 0$ quite significantly, all formal results in this paper are confined to the spatial error model. Extensions to the spatial lag model are discussed in Section 5.

A few, mainly notational, remarks are in order. We denote the size of a test by $\alpha$, and, to avoid trivial cases, we assume $0 < \alpha < 1$. Note that, because of the invariance with respect to the transformations $y \rightarrow y + X\delta$, the power of any invariant test depends on $X$ only through its column space $\text{col}(X)$, often referred to as the regression space. All matrices considered in this paper are real. For a $q \times q$ symmetric matrix $Q$, we denote by $\lambda_1(Q) \leq \lambda_2(Q) \leq ... \leq \lambda_q(Q)$ its eigenvalues; by $f_1(Q),...,f_q(Q)$ a set of corresponding orthonormal eigenvectors; by $E_i(Q)$ the eigenspace associated to $\lambda_i(Q)$; by $m_i(Q)$ the (algebraic and geometric) multiplicity of $\lambda_i(Q)$.

## 3 Main Results

In this section we discuss the existence of pairs $(W, X)$ such that the limiting power of tests for residual spatial autocorrelation vanishes. We shall see that such pairs always exist, provided that $W$ is outside a small class of exceptions. Most importantly, the zero
limiting power is a positive probability event, in a sense to be made clear below. Section 3.1 is devoted to the Cliff-Ord test. Section 3.2 shows that the results concerning the Cliff-Ord test extend to point optimal tests, with only a minor modification. Section 3.3 discusses the exceptions to our main results.

Before we proceed, it is important to point out that the analysis to follow is not directly relevant if \( W \) is row-standardized, or, more generally, has constant row-sums. Indeed, if \( W \) has constant row-sums, the limiting power of any invariant test cannot vanish as long as an intercept is included in the regression; see Section 3.2.2 of Martellosio (2008). A discussion of the possible consequences of our results for the important case of a row-standardized \( W \) is deferred to Section 5. For now, we point out that in some applications it may be preferable to work with non-row-standardized weights matrices, because row-standardization may lead to misspecification; see, e.g., Bell and Bockstael (2000), p. 74, and Kelejian and Prucha (2007).

### 3.1 The Cliff-Ord Test

The most popular test for residual spatial autocorrelation is the Cliff-Ord test. It consists of rejecting \( H_0 \) for large values of

\[
I := \frac{y'M_x W M y}{y'M_x y},
\]

where \( M_x := I_n - X(X'X)^{-1}X' \); see Cliff and Ord (1981) and Kelejian and Prucha (2001).\(^3\) When the distribution of \( u \) is elliptically symmetric, the Cliff-Ord test is locally best invariant for our testing problem (see King, 1980 and 1981). Critical values for the test can be obtained from the exact null distribution of \( I \), or from the asymptotic null distribution of a suitably normalized version of \( I \).

The issue of the existence of pairs \((W, X)\) such that the limiting power of the Cliff-Ord test vanishes is considered in Krämer (2005). Theorem 1 in Krämer (2005) states that, in a spatial error model, “given any matrix \( W \) of weights, and independently of sample size, there is always some regressor \( X \) such that for the Cliff–Ord test the limiting power disappears”. The statement is formulated under the assumptions that the model is Gaussian, and that \( W \) is symmetric. Unfortunately, Krämer’s proof contains an incorrect argument, which has the consequence that the pairs \((W, X)\) constructed in that proof do not need to cause the limiting power to vanish.\(^4\) We now aim to settle the issue and place it in a more general context.

Let \( f_{\text{max}} \) be one of the two normalized (so that \( f'_{\text{max}} f_{\text{max}} = 1 \)) eigenvectors of \( W \) associated to \( \lambda_{\text{max}} \).\(^5\) We need the following definition.

---

\(^3\)Note that \( y'M_x y = 0 \) if and only if \( y \) belongs to the set \( \{0\} \cup \text{col}(X) \), which, since \( k < n \), has zero measure. Hence, \( I \) is defined almost surely.

\(^4\)The problem lies in inequality (12) in Krämer (2005). In most cases, the critical value \( d_1 \) in that inequality can be positive or negative depending on \( \alpha \), and hence Krämer’s proof holds only for sufficiently small \( \alpha \). In addition, there are weights matrices such that \( d_1 < 0 \) for any \( \alpha \); e.g., a \( W \) with constant off-diagonal entries. For such matrices, inequality (12) is incorrect for all values of \( \alpha \).

\(^5\)Throughout the paper, it is irrelevant which eigenvector is chosen. Also, the normalization of \( f_{\text{max}} \) is made only for convenience, and will not be relevant until Section 4.
**Definition 3.1** \( C \) is the class of weights matrices \( W \) such that \( m_1(W + W') = n - 1 \) and \( f_{\text{max}} \) is an eigenvector of \( W' \).

The class \( C \) contains the exceptions to Lemma 3.2 below. The weights matrices used in applications are generally not in \( C \); possibly, the only members of \( C \) that have some empirical relevance are those with \( (W)_{ij} \) equal to some constant positive scalar if \( i \neq j \), to 0 if \( i = j \). We refer to such matrices as *equal weights* matrices. Recently, equal weights matrices have attracted some attention in the spatial econometric literature; see Kelejian and Prucha (2002), Kelejian et al. (2006), Baltagi (2006) and Smith (2008). More details about the class \( C \) are in Section 3.3.

**Lemma 3.2** Consider testing \( \rho = 0 \) in the context of a spatial error model. For any weights matrix \( W \not\in C \), any number of regressors \( k > 0 \), and any size \( \alpha \), there exists at least one \( k \)-dimensional regression space \( \text{col}(X) \) such that the limiting power of the Cliff-Ord test vanishes.

Lemma 3.2 establishes that the statement from Krämer (2005) reported above is correct if \( W \not\in C \), for any \( n, k \) and \( \alpha \), and generalizes it to nonsymmetric \( W \) and to non-Gaussian models.

Although it holds for any \( W \not\in C \), Lemma 3.2 has little practical relevance when \( W \) is row-standardized, or more generally, has constant row-sums. As we mentioned above, in that case—and only in that case—the restriction that \( \text{col}(X) \) contains an intercept is sufficient to circumvent the zero limiting power problem. In other words, when \( W \) has constant row-sums, the regression spaces identified by Lemma 3.2 cannot contain an intercept, and hence typically do not occur in applications.

Given any \( W \) with non-constant row-sums, Lemma 3.2 says that, for any \( n, k \) and \( \alpha \), there is at least one possibility that the Cliff-Ord test is unable to reject the null hypothesis. This is a negative and unusual feature of a statistical test. It is therefore natural to wonder whether the set of regression spaces causing the limiting power to vanish has *zero measure*. In that case, Lemma 3.2, which only says that such a set is *nonempty*, would be immaterial for applications. We denote by \( G_{k,n} \) the set—usually called a Grassmann manifold—of all \( k \)-dimensional subspaces of \( \mathbb{R}^n \). We refer to the unique rotationally invariant measure on \( G_{k,n} \); see Section 4.6 of James (1954) for details.\(^6\)

**Theorem 3.3** Consider testing \( \rho = 0 \) in the context of a spatial error model. For any weights matrix \( W \not\in C \), any number of regressors \( k > 0 \), and any size \( \alpha \), the set of \( k \)-dimensional regression spaces such that the limiting power of the Cliff-Ord test vanishes has positive measure.

Theorem 3.3 says that, as \( X \) is free to vary without restrictions (in the sense that \( \text{col}(X) \) has positive density almost everywhere on \( G_{k,n} \)), the zero limiting power has a

\(^6\)Of course, \( X \) is assumed to be nonstochastic when constructing the Cliff-Ord test. We are now equipping \( G_{k,n} \) with a probability measure only as a device to assess the practical relevance of the zero limiting power problem. One may think of an experiment where \( W \) is fixed, \( X \) is random, and the Cliff-Ord test is constructed for each realization of \( X \).
positive probability of occurring. The main practical consequence of this result is that
the zero limiting power is always a threat in applications, regardless of how large \( n-k \) or \( \alpha \) are (provided that \( W \notin \mathcal{C} \)).

How likely it is in a given application to run into the regression spaces causing the
limiting power to vanish will depend to a very large extent on \( W, n-k, \) and \( \alpha \). Some
simulation exercises analyzing this issue are reported in Krämer (2005) and Martellosio
(2008). Here, we stress that Theorem 3.3 implies that in any simulation study of the
power properties of the Cliff-Ord test for a fixed \( W \notin \mathcal{C} \) and when \( X \) is drawn from
a distribution supported on the whole \( \mathbb{R}^{n \times k} \), there must be repetitions such that the
limiting power vanishes, provided only that the number of repetitions is large enough.

3.2 The Point Optimal Invariant Tests

Martellosio (2008) shows that the zero limiting power problem is not due to the form
of a particular test statistic, but to the fact that, as \( \rho \to \lambda_{\text{max}}^{-1} \), a SAR(1) model tends
to a distribution concentrated on the eigenspace of \( W \) associated to \( \lambda_{\text{max}} \). If a critical
region does not intersect such an eigenspace (except possibly on a zero-measure set),
its limiting power is bound to vanish. This interpretation suggests that the results in
the previous section can be extended to any other test of spatial autocorrelation. Here
we focus on the tests that, under the assumption of elliptical symmetry, define the
power envelope of all invariant tests.

Consider testing \( \rho = 0 \) against the specific alternative that \( \rho = \bar{\rho} \), for some fixed
\( 0 < \bar{\rho} < \lambda_{\text{max}}^{-1} \). When the distribution of \( u \) is elliptically symmetric, the Neyman-
Pearson lemma implies that the most powerful invariant test rejects \( \rho = 0 \) for small
values of

\[
P_{\bar{\rho}} := \frac{y'C'[C\Sigma(\bar{\rho})C']^{-1}Cy}{y'MXy},
\]

(4)

where \( \Sigma(\bar{\rho}) := \text{var}(y) = [(I_n - \rho W')(I_n - \rho W)]^{-1} \), and \( C \) is an \((n-k) \times n\) matrix
such that \( CC' = I_{n-k} \) and \( C'C = MX \) (see King, 1980 and 1988). In econometrics,
tests constructed as above to be the most powerful against a specific alternative are
usually called point optimal invariant (POI) tests. With an abuse of language, we shall
refer to a test based on (4) as a POI test, irrespective of whether the distribution of
\( u \) is elliptically symmetric. Under elliptical symmetry, the POI tests define the power
envelope of invariant tests. Of course it can be argued that, if the distribution of \( u \) is
not far from being elliptically symmetric, then the power function of a test based on
(4) must be close to the power envelope.

In order to state the analog of Theorem 3.3 for POI tests, we need to define a
slightly modified class of exceptions.

**Definition 3.4** \( \mathcal{C}^* \) is the class of weights matrices \( W \in \mathcal{C} \) such that \( m_1(W'W) = n-1 \).

**Theorem 3.5** Consider testing \( \rho = 0 \) in the context of a spatial error model. For any
weights matrix \( W \notin \mathcal{C}^* \), any number of regressors \( k > 0 \), and any size \( \alpha \), there is a
positive measure set of $k$-dimensional regression spaces such that the limiting power of a POI test vanishes.

Theorem 3.5 is even more surprising than the corresponding result for the Cliff-Ord test. To see why this is the case, consider, under the assumption of elliptical symmetry, the extreme case of a POI test when $\bar{\rho}$ is close to $\lambda_{\text{max}}^{-1}$ and the size $\alpha$ is very large. Since a very large $\alpha$ means that the critical region covers almost the whole sample space, one might expect the limiting power to be large. In fact, Theorem 3.5 asserts that even in this extreme case regressors can be found such that the probability content of the critical region vanishes as $\rho \to \lambda_{\text{max}}^{-1}$.

### 3.3 Exceptions and Equal Weights Matrices

The reason why the weights matrices in $C$ (resp. $C^*$) constitute exceptions to our theorems above is that, in their presence, the limiting power of the Cliff-Ord (resp. a POI) test can never be zero. This is established in the following proposition.

**Proposition 3.6** Consider testing $\rho = 0$ in the context of a spatial error model. For any $W \in C$ (resp. $W \in C^*$), any $X$, and any $\alpha$, the limiting power of the Cliff-Ord (resp. a POI) test is 1 if $f_{\text{max}} \notin \text{col}(X)$, $\alpha$ if $f_{\text{max}} \in \text{col}(X)$.

The most important part of Proposition 3.6 is the one concerning the case $f_{\text{max}} \in \text{col}(X)$. This is because the eigenvector $f_{\text{max}}$ of most matrices $W \in C$ is a vector of identical entries, and hence is in $\text{col}(X)$ as long as the regression contains an intercept. To be more precise, consider the two following conditions.

**Condition 1** $(W)_{ij} \geq 0$ with $(W)_{ii} = 0$, for $i, j = 1, \ldots, n$.

**Condition 2** $W$ is irreducible.

Condition 1 is virtually always satisfied in applications. For the definition of an irreducible matrix, see e.g. Horn and Johnson (1985). Irreducibility requires the graph with adjacency matrix $W$ (that is, the graph with $n$ vertices and an edge from vertex $i$ to vertex $j$ if and only if $(W)_{ij} \neq 0$) to have a path from any vertex $i$ to any vertex $j$. This condition is often met in applications. We have the following result.

**Proposition 3.7** Assume that Conditions 1 and 2 hold. Then, if $W \in C$, $f_{\text{max}}$ is a vector of identical entries.

We are now in a position to also explain why, as mentioned in Section 3.1, the equal weights matrices are particularly important members of $C$. Consider the following condition.

**Condition 3** All the eigenvalues of $W$ are real.

---

7Note that the power at $\bar{\rho}$ of the most powerful test against $\rho = \bar{\rho}$ must be larger than $\alpha$, by the Neyman-Pearson Lemma. Thus, in the extreme case when both $\bar{\rho}$ and $\alpha$ are large, the power function must drop to 0 very quickly after $\rho = \bar{\rho}$.
Condition 3 is certainly satisfied when \( W \) is symmetric or a row-standardized version of a symmetric matrix, whereas it may not be satisfied in applications to directed networks.\(^8\)

**Proposition 3.8** Assume that Conditions 1, 2 and 3 hold. Then, \( W \) is in \( \mathcal{C} \) if and only if it is an equal weights matrix.

We conclude this section with three remarks that further emphasize the special role of the weights matrices in \( \mathcal{C} \) or \( \mathcal{C}^* \) in the context of testing for spatial autocorrelation, and provide some links to previous work.

**Remark 3.9** In the proof of Proposition 3.6 it is established that when \( f_{\text{max}} \in \text{col}(X) \) and \( W \in \mathcal{C} \) (resp. \( W \in \mathcal{C}^* \)) the power function of a Cliff-Ord (resp. POI) test is flat (that is, the power is \( \alpha \) for any \( 0 \leq \rho < \lambda_{\text{max}}^{-1} \), not only as \( \rho \to \lambda_{\text{max}}^{-1} \)). This is a generalization of results in Arnold (1979) and Kariya (1980b).

**Remark 3.10** Under the assumption of an elliptical symmetric distribution, when \( f_{\text{max}} \in \text{col}(X) \) and \( W \in \mathcal{C}^* \) the Cliff-Ord test and the POI test are uniformly most powerful invariant (UMPI). This is a straightforward generalization of the argument in the last paragraph of King (1981). Thus, by the previous remark and somewhat ironically, in a spatial error model the Cliff-Ord and POI tests are UMPI when their power function is flat.

**Remark 3.11** The part of Proposition 3.6 relative to the Cliff-Ord test when \( f_{\text{max}} \in \text{col}(X) \) represents also a generalization of Proposition 5 in Smith (2008). That result asserts that when \( W \) is an equal weights matrix and the regression contains an intercept, the Cliff-Ord statistic is degenerate, in the sense that its distribution does not depend on \( y \).

### 4 The Particularly Hostile Regression Spaces

Suppose that for a certain pair \((W, X)\), the limiting power of an invariant critical region \( \Phi \in \mathbb{R}^n \) vanishes. By Lemma A.1, a zero limiting power occurs if \( f_{\text{max}} \) is outside \( \Phi \). One obvious way to try and increase the power is to increase the size of \( \Phi \), because, again by Lemma A.1, the limiting power becomes positive if \( f_{\text{max}} \) falls in \( \Phi \). However, the minimum size \( \alpha \) such that the limiting power does not vanish may be very large. What is more, there are cases when \( f_{\text{max}} \) remains outside \( \Phi \) for all values of \( \alpha \) (less than 1), so that the limiting power vanishes irrespective of \( \alpha \). In this section, we characterize the regression spaces such that, for a fixed \( W \), the limiting power of the Cliff-Ord test or of a POI test vanishes regardless of \( \alpha \). Such regression spaces are referred to as particularly hostile.

Let us start by formalizing the notion of a particularly hostile \( \text{col}(X) \). For a given \( W \) and \( \alpha \), and for the Cliff-Ord test or a POI test, let \( H_k(\alpha) \) denote the set of \( k \)-dimensional regression spaces that cause the limiting power to disappear. The set of

\(^8\)An example of a \( W \in \mathcal{C} \) that does not satisfy Condition 3 is \([0, 1, 2], [2, 0, 1], [1, 2, 0]\).
particularly hostile $k$-dimensional regression spaces is the intersection of all sets $H_k(\alpha)$, for $\alpha \in (0, 1)$. Recall from Section 3 that any set $H_k(\alpha)$ is nonempty, provided that $W$ is outside a class of exceptions ($C$ for for the Cliff-Ord test, $C^*$ for a POI test). It follows that the set of particularly hostile regression spaces is nonempty, for any $k$ and any $W$ not in $C$ or $C^*$.

The following theorem provides some information on the particularly hostile col$(X)$'s. This is achieved by making the simplifying assumption that $W$ is symmetric, and by confining attention to the case when $k$ is not greater than the multiplicity $m_1(W)$ of the smallest eigenvalue of $W$. The most common value of $m_1(W)$ in applications to irregular spatial configurations is 1. \(^9\) For the case $k = m_1(W) = 1$, the theorem provides a complete characterization of the particularly hostile col$(X)$'s. Some consequences of nonsymmetry of $W$ will be discussed later, by means of an example.

**Theorem 4.1** Consider a spatial error model with symmetric weights matrix $W$ such that $m_1(W) = 1$, and with a single regressor ($k = 1$) that is a scalar multiple of the vector $f_1(W) + \omega f_{\text{max}}$, for some $\omega \in \mathbb{R}$. Let

$$
\omega_1 := \left[ \frac{\lambda_{\text{max}} - \lambda_2(W)}{\lambda_2(W) - \lambda_1(W)} \right]^{\frac{1}{2}} ; \quad \omega_2 := \frac{1 - \bar{\rho}\lambda_1(W)}{1 - \bar{\rho}\lambda_{\text{max}}} \left[ \frac{2 - \bar{\rho}(\lambda_{\text{max}} + \lambda_2(W))}{2 - \bar{\rho}(\lambda_2(W) + \lambda_1(W))} \right]^{\frac{1}{2}}.
$$

Then, the limiting power of the Cliff-Ord test vanishes for all values of $\alpha$ if $|\omega| \geq \omega_1$, and the limiting power of a POI test vanishes for all values of $\alpha$ if $|\omega| \geq \omega_1\omega_2$.

More generally, consider a spatial error model with a symmetric $W$ different from an equal weights matrix, and with $k \leq m_1(W)$. For any $k$ linearly independent eigenvectors $g_1, \ldots, g_k \in E_1(W)$, let $\Theta$ be the set of hyperplanes in $\text{span}(g_1, \ldots, g_k, f_{\text{max}})$ that do not contain $f_{\text{max}}$ and are not in $E_1(W)$. Then, for the Cliff-Ord test or a POI test, any set $\Theta$ contains regression spaces such that the limiting power vanishes for all values of $\alpha$.

The result in Theorem 4.1 suggests the following interpretation. For a fixed symmetric $W$, let

$$I_0 := \frac{v'Wv}{v'v},$$

where $v$ is a realization of an $n$-dimensional random vector $z$. \(^{10}\) The statistic $I_0$ is the particular case of the Cliff-Ord statistic $I$ when $E(z) = 0$. Suppose that, as it is typically the case in applications, $W$ has zero diagonal entries. Then, $\lambda_1(W) < 0$, because $\lambda_{\text{max}} > 0$ by definition and $\text{tr}(W) = \sum_{i=1}^{n} \lambda_i(W) = 0$. If we regard $I_0$ as a measure of autocorrelation, then, by Lemma A.2, any $v \in E_1(W)$ represents a strongly negatively autocorrelated vector, whereas $v = f_{\text{max}}$ represents a strongly positively

\(^9\)In general, $m_1(W) > 1$ requires $W$ to satisfy some symmetries; see Biggs (1993), Ch. 15. The case of an equal weights matrix is emblematic: a such matrix has $m_1(W) = n - 1$ and is invariant with respect to the whole symmetric group on $n$ elements.

\(^{10}\)Here, for clarity and contrary to what is done in the rest of the paper, we use different notation for a random variable and its realizations.
For simplicity, let us now focus on the case $k = m_1(W) = 1$, so that there is a single regressor, to be denoted by $x$. Theorem 4.1 asserts that it is particularly difficult to detect large positive spatial autocorrelation when $x$ can be written as the sum of a strongly positively autocorrelated component (according to $I_0$) and a strongly negatively autocorrelated component (according to $I_0$). One could say that the tests get confused in the presence of such an $x$.

There are similarities between Theorem 4.1 and contributions in the time-series literature concerning the so-called Watson’s $X$ matrix (see, in particular, Watson, 1955). This is the regressor matrix that minimizes the efficiency of the OLS estimator of $\beta$ relative to the best linear unbiased estimator. The similarities are not surprising, in view of results in Tillman (1975) indicating that, in the presence of Watson’s $X$ matrix, the Durbin-Watson test has low power as the autocorrelation coefficient of an AR(1) process approaches 1.

Next, we provide a graphical representation of the hostile regression spaces. Such a representation is helpful to better understand the characterization in Theorem 4.1, and to appreciate what happens when $W$ is nonsymmetric.

We take $n = 3$ and $k = 1$, so that the regression spaces are lines in $\mathbb{R}^3$ through the origin. Without loss of generality, we normalize the regressors to have fixed length, so that they are points on a sphere in $\mathbb{R}^3$ (of arbitrary radius). We consider the weights matrix

$$W = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}. \quad (5)$$

Figure 1 displays 5000 random points from each of the three regions $H_1(0.9) \subset H_1(0.3) \subset H_1(0.1)$, for the Cliff-Ord test. We only plot the positive octant in the coordinate system of the eigenvectors of $W$, because the symmetry of $W$ implies that all regions $H_1(\alpha)$ are symmetric with respect to the coordinate planes in the coordinate system. It can be seen from Figure 1 that, as stated in Theorem 4.1, the particularly hostile regressors (that is, the regressors in $H_1^*$) belong to the plane spanned by $f_1(W)$ and $f_{\max}$, and are between the vector $h := f_1(W) + \omega_1 f_{\max}$ and $f_{\max}$.

Let us now turn our attention to nonsymmetric weights matrices. Figure 2 is the analog of Figure 1 for the weights matrix

$$Q = \begin{bmatrix} 0 & 1 & 0 \\ 4 & 0 & 1 \\ 0 & 4 & 0 \end{bmatrix}. \quad (6)$$

The coordinate system for Figure 2 is the same as for Figure 1.\footnote{Since $Q$ is nonsymmetric, the regions $H_1(\alpha)$ are no longer symmetric with respect to the coordinate}
planes (but are still symmetric with respect to the origin), so we now focus on an emisphere rather than on an octant as in Figure 1. We do not plot $H_k(0.1)$, as this region would cover almost the whole emisphere (note that it makes sense to consider large values of $\alpha$, as we have only 2 degrees of freedom).

The characterization in Theorem 4.1 requires symmetry of $W$. Figure 2 suggests that a similar characterization should hold when $W$ is nonsymmetric. Indeed, the particularly hostile regressors are still between $h$ and the eigenvector $f_n(Q)$ associated to the largest eigenvalue of $Q$. However, contrary to the case of (5), they do not lie on the plane spanned by $h$ and $f_n(Q)$. Because of this reason, a characterization similar to that in Theorem 4.1 for the case of nonsymmetric $W$ is likely to be more complicated. To see exactly what happens when we move from a symmetric to a nonsymmetric $W$, let us replace the two 4’s in matrix (6) with a general scalar $a$. For any $a$, the particularly hostile regressors are between $h$ and $f_n(Q)$. When $a = 1$ (the case of Figure 1) they belong to span$(h, f_n(Q))$. As $a$ moves away from 1, $f_n(Q)$ moves away from $f_{\max} = f_n(Q + Q')$, and the curve described on the sphere by the particularly hostile regression spaces moves away from span$(h, f_n(Q))$.

5 Discussion

This paper has addressed the question, touched upon in Krämer (2005), of whether it is always possible to run into regressors such that the power of tests for spatial autocorrelation vanishes as the autocorrelation increases. The answer is positive, implying
that in an applications there is always a possibility that detecting large autocorrelation by means of a certain test is extremely difficult. Since the regression spaces that cause the problem depend on the test, a practical recommendation is not to rely on a single test, but to check that the decision of rejecting or not rejecting is robust over a number of tests.

For simplicity, we have confined attention to the spatial error model. In applications, one is also often interested in testing for a spatially lagged dependent variable in a spatial lag model, or in testing for residual autocorrelation in a spatial autoregressive model with autoregressive disturbances.\textsuperscript{13} Such testing problems have a more complicated structure than the one considered in this paper: first, they are not invariant under the group of transformations $y \rightarrow \gamma y + X\delta$; second, the distributions of the test statistics for those problems generally depend on nuisance parameters. While these complications would certainly make an extension of the results concerning the spatial error model more involved analytically, there is no reason to believe that they would impede it.

At the beginning of Section 3, we have mentioned that the limiting power of an invariant test must be positive in the context of a spatial error model with a row-standardized $W$, provided that the regression contains an intercept. It is worth noting that the limiting power may be very small, albeit positive. An obvious extension of our analysis would be to establish whether, when $W$ is row-standardized and in the presence of an intercept, there exist regression spaces such that the limiting power is

\textsuperscript{13}A modification of the Cliff-Ord test for the latter testing problem has been proposed by Kelejian and Prucha (2001).
smaller than some given positive number. It should also be noted that, in the context of a spatial lag model or a spatial autoregressive model with autoregressive disturbances, the power of a test for autocorrelation can vanish even when $W$ is row-standardized and an intercept is included among the regressors (see Martellosio, 2008, for details).

Acknowledgements

I am grateful to Grant Hillier, Tony Smith, and participants at the ESRC Econometrics Study Group, Bristol, 2008, for discussions and encouragement.

Appendix A  Auxiliary Lemmata

The first lemma, stated here for convenience, is Corollary 3.4 of Martellosio (2008). In that paper, the result was derived under the assumption that $W$ is nonnegative and irreducible, but it is clear from its proof that it also holds under the weaker assumption maintained in the present paper that $\lambda_{\text{max}}$ has geometric multiplicity one. We denote by int$(S)$, bd$(S)$ and cl$(S)$, the interior, the boundary, and the closure of a set $S$, respectively.

Lemma A.1 (Martellosio, 2008) In a spatial error model, the limiting power of an invariant critical region $\Phi$ for testing $\rho = 0$ against $\rho > 0$ is:

- 1 if $f_{\text{max}} \in \text{int}(\Phi)$;
- in $(0,1)$ if $f_{\text{max}} \in \text{bd}(\Phi)$;
- 0 if $f_{\text{max}} \notin \text{cl}(\Phi)$.

The next lemma is proved, for instance, in Horn and Johnson (1985).

Lemma A.2 (Rayleigh-Ritz Theorem) For a $q \times q$ symmetric matrix $Q$,

$$\lambda_1(Q)x'x \leq x'Qx \leq \lambda_q(Q)x'x,$$

for all $x \in \mathbb{R}^q$. The equalities on the left and on the right are attained if and only if $x$ is an eigenvector of $Q$ associated to, respectively, $\lambda_1(Q)$ and $\lambda_q(Q)$.

Lemma A.3 For any $n \times n$ symmetric matrix $Q$, and for any $k \geq 1$, $\lambda_{n-k}(CQC') = \lambda_1(Q)$ if and only if col$(X)$ contains all eigenvectors of $Q$ associated to the eigenvalues different from $\lambda_1(Q)$.

Proof. Consider the spectral decomposition $Q = \sum_{i=2}^{s} \eta_i(Q)G_i$, where $\eta_1(Q) < \eta_2(Q) < \ldots < \eta_s(Q)$ are the $s \leq n$ distinct eigenvalues of $Q$, and $G_1, \ldots, G_s$ are the corresponding eigenprojectors. Since $\sum_{i=1}^{s} G_i = I_n$,

$$Q = \eta_1(Q)\left(I_n - \sum_{i=2}^{s} G_i\right) + \sum_{i=2}^{s} \eta_i(Q)G_i = \eta_1(Q)I_n + \sum_{i=2}^{s} (\eta_i(Q) - \eta_1(Q))G_i,$$

13
and hence

\[ CQC' = \eta_1(Q)I_{n-k} + \sum_{i=2}^{s}(\eta_i(Q) - \eta_1(Q))CG_iC'. \] (7)

Observe that if \(\lambda_{n-k}(CQC') = \lambda_1(Q)\) then \(CQC' = \lambda_1(Q)I_{n-k}\), which in turn implies, by (7), that \(CQC' = O_n\), for \(i = 2, \ldots, s\). The necessity of the condition in the proposition is thus established. To prove the sufficiency, suppose that \(\text{col}(X)\) contains all eigenvectors of \(Q\) associated to the eigenvalues different from \(\lambda_1(Q)\). Then \(M_X\) has an eigenspace spanned by \(k\) orthogonal eigenvectors of \(Q\) that are in \(\text{col}(X)\), and an eigenspace spanned by \(n-k\) orthogonal eigenvectors of \(Q\) that are not in \(\text{col}(X)\). The former eigenspace is associated to the eigenvalue \(0\) and the latter to the eigenvalue \(1\). Hence, \(M_XQ\) has the eigenvalue \(0\) with multiplicity \(k\) and the eigenvalue \(\lambda_1(Q)\) with multiplicity \(n-k\). But, since the nonzero eigenvalues of the product of two matrices are independent of the order of the factors (e.g., Theorem 1.3.20 in Horn and Johnson, 1985), the eigenvalues of of \(M_XQ\) are the same as those of \(CQC'\), except for \(k\) zeros. Thus, we must have \(\lambda_{n-k}(CQC') = \lambda_1(Q)\), and the proof is completed. \(\blacksquare\)

**Lemma A.4** Any \(W \in \mathcal{C}\) is normal.

**Proof.** Since \(W\) is real, we need to show that \(WW' = W'W\), for any \(W \in \mathcal{C}\). Write \(W = A + B\), where \(A := (W + W')/2\) is symmetric and \(B := (W - W')/2\) is antisymmetric. For any \(W \in \mathcal{C}\), \(A\) has only two eigenvalues: one of them is \(\lambda_{\text{max}}\), associated to the eigenvector \(f_{\text{max}}\). Letting \(\theta\) be the other eigenvalue, and \(G\) the corresponding eigenprojector, we have the spectral decomposition

\[ A = \lambda_{\text{max}}f_{\text{max}}f_{\text{max}}' + \theta G. \]

Since \(G = I_n - f_{\text{max}}f_{\text{max}}'\), \(A = \theta I_n + (\lambda_{\text{max}} - \theta)f_{\text{max}}f_{\text{max}}'\). Observe that, for any \(W \in \mathcal{C}\), \(Bf_{\text{max}} = (W - A)f_{\text{max}} = 0\). Then,

\[ WW' = (\theta I_n + (\lambda_{\text{max}} - \theta)f_{\text{max}}f_{\text{max}}' + B)(\lambda_{\text{max}} - \theta)f_{\text{max}}f_{\text{max}}' - B) \]
\[ = \theta^2 I_n + (2(\lambda_{\text{max}} - \theta)\theta + (\lambda_{\text{max}} - \theta)^2)f_{\text{max}}f_{\text{max}}' - B^2 = W'W. \]

\(\blacksquare\)

**Lemma A.5** For any \(W \in \mathcal{C}\) and any \(X\) such that \(f_{\text{max}} \notin \text{col}(X)\), the Cliff-Ord test statistic evaluated at \(y = f_{\text{max}}\) is

\[ I(f_{\text{max}}) = \frac{1}{2}\lambda_{n-k}(C(W + W')C'). \]

**Proof.** For any \(W \in \mathcal{C}\), the matrix \(A := (W + W')/2\) admits the spectral decomposition \(\lambda_1(A)G_1 + \lambda_n(A)G_n\) where \(G_1\) and \(G_n\) are the spectral projectors associated with \(\lambda_1(A)\) and \(\lambda_n(A)\), respectively. Since \(f_{n}(A) = f_{\text{max}}\) for any \(W \in \mathcal{C}\), and the spectral projectors must sum to \(I_n\), we can write

\[ A = \lambda_1(A)I_n + (\lambda_n(A) - \lambda_1(A))f_{\text{max}}f_{\text{max}}'. \] (8)
Assume that \( f_{\text{max}} \notin \text{col}(X) \), and consider an arbitrary vector \( v \in \mathbb{R}^{n-k} \) that is orthogonal to \( Cf_{\text{max}} \). From (8) we have

\[
CAC'v = \lambda_1(A)CC'v + (\lambda_n(A) - \lambda_1(A))Cf_{\text{max}}f_{\text{max}}'C'v,
\]
and hence, since \( CC' = I_n \) and \( f_{\text{max}}'C'v = 0 \),

\[
CAC'v = \lambda_1(A)v.
\]

Thus, \( CAC' \) has an \((n-1)\)-dimensional eigenspace (the orthogonal complement of \( Cf_{\text{max}} \)). But, since \( CAC' \) is symmetric because \( A \) is, the other eigenspace of \( CAC' \) must be spanned by \( Cf_{\text{max}} \). The eigenvalue of \( CAC' \) pertaining to such an eigenspace cannot be smaller than \( \lambda_1(A) \) by the Poincaré separation Theorem (e.g., Horn and Johnson, 1985). It follows that

\[
CAC'Cf_{\text{max}} = \lambda_{n-k}(CAC')Cf_{\text{max}},
\]
which in turn implies that \( I(f_{\text{max}}) = \lambda_{n-k}(CAC') \).

**Lemma A.6** For any \( W \in C^* \) and any \( X \) such that \( f_{\text{max}} \notin \text{col}(X) \), the POI test statistic evaluated at \( y = f_{\text{max}} \) is

\[
P_\rho(f_{\text{max}}) = \frac{1}{\lambda_{n-k}(C\Sigma(\bar{\rho})C')}.
\]

**Proof.** For any \( W \in C^* \), the matrices \( W + W' \) and \( W'W \) are simultaneously diagonalizable, because they are diagonalizable and, by Lemma A.4, they commute (e.g., Horn and Johnson, 1985, Theorem 1.3.12). Recall that \( \Sigma(\bar{\rho}) = (I_n - \rho(W + W') + \rho^2W'W)^{-1} \) and that, for any \( W \in C^* \), \( m_1(W + W') = m_1(W'W) = n - 1 \). Then, for any \( W \in C^* \), \( m_1(\Sigma(\bar{\rho})) = n - 1 \). We can now proceed similarly to the proof of Lemma A.5. More specifically, on replacing \( A \) in that proof with \( \Sigma^{-1}(\bar{\rho}) \) expression (9) becomes

\[
C\Sigma(\bar{\rho})C'Cf_{\text{max}} = \lambda_{n-k}(C\Sigma(\bar{\rho})C')Cf_{\text{max}},
\]
or, equivalently,

\[
(C\Sigma(\bar{\rho})C')^{-1}Cf_{\text{max}} = \lambda_1((C\Sigma(\bar{\rho})C')^{-1})Cf_{\text{max}}.
\]

Using the last expression, we obtain

\[
P_\rho(f_{\text{max}}) = \frac{f_{\text{max}}'C[C\Sigma(\bar{\rho})C']^{-1}Cf_{\text{max}}}{f_{\text{max}}'M_Xf_{\text{max}}} = \lambda_1((C\Sigma(\bar{\rho})C')^{-1}) = \lambda_{n-k}(C\Sigma(\bar{\rho})C'),
\]
which is the desired conclusion.
Appendix B  Proofs

Proof of Lemma 3.2. Consider some arbitrary \( n, k, \alpha, \text{ and } W \notin C \). Let \( \Phi = \{ y \in \mathbb{R}^n : I > c \} \) be the critical region associated to the Cliff-Ord test. It is readily established that the closure of \( \Phi \) is \( \text{col}(X) \cup \{ y \in \mathbb{R}^n : I \geq c \} \). Hence, by Lemma A.1, the limiting power of the Cliff-Ord test vanishes if \( f_{\max} \notin \text{col}(X) \) and \( I(f_{\max}) < c \), where \( I(f_{\max}) \) denotes the Cliff-Ord test statistic evaluated at \( y = f_{\max} \). Letting \( A := (W + W')/2 \), we obtain from Lemma A.2 that \( I \geq \lambda_1(A) \), for all \( y \in \mathbb{R}^n \) and all \( X \in \mathbb{R}^{n \times k} \). Let \( C \) be an \( (n - k) \times n \) matrix such that \( CC' = I_{n-k} \) and \( C' C = M_X \). On writing \( I = t'C W C' t/t' t \), where \( t := Cy \), Lemma A.2 also implies that \( I \leq \lambda_{n-k}(CAC') \) for all \( y \in \mathbb{R}^n \). Thus, in order to prove the theorem, it suffices to show that there exists at least one \( \text{col}(X) \) such that the following three properties are satisfied: (i) \( f_{\max} \notin \text{col}(X) \); (ii) \( I(f_{\max}) \) is arbitrarily close to \( \lambda_1(A) \); (iii) \( \lambda_{n-k}(CAC') \) does not arbitrarily close to \( \lambda_1(A) \). Note that we do not need to prove the existence of a \( \text{col}(X) \) such that \( I(f_{\max}) = \lambda_1(A) \), because we are assuming \( \alpha < 1 \). Also, observe that condition (iii) is necessary, because without it the limiting power could be 1 even if there exists a \( \text{col}(X) \) that satisfies (ii).

Consider now, for some \( g \in E_1(A) \), a sequence \( \{X_l\}_{l=1}^{\infty} \) such that the vector \( (M_{X_l} f_{\max})^\star \) converges to \( g^\star \), in the sense that
\[
\lim_{l \to \infty} \|(M_{X_l} f_{\max})^\star - g^\star\| = 0,
\]
where \( \|\cdot\| \) is an arbitrary norm on \( \mathbb{R}^n \), and a ‘\( \ast \)’ indicates that a vector \( v \in \mathbb{R}^n \) has been normalized with respect to \( \|\cdot\| \), i.e., \( v^\star := v/\|v\| \) (the arbitrariness of the norm follows from the fact that the convergence of a sequence of vectors in \( \mathbb{R}^n \) is independent of the choice of the norm; see Corollary 5.4.6 of Horn and Johnson, 1985). By Lemma A.2,
\[
\lim_{l \to \infty} I(f_{\max}) = \lim_{l \to \infty} \frac{f'_{\max} M_{X_l} A M_{X_l} f_{\max}}{f'_{\max} M_{X_l} f_{\max}} = \lambda_1(A). \tag{10}
\]
Expression (10) implies the existence of at least one \( \text{col}(X) \) that satisfies (i) and (ii). In order to establish that there exists at least one \( \text{col}(X) \) that satisfies (i), (ii) and (iii), we need to show that it is possible to choose \( g \in E_1(A) \) in such a way that
\[
\lim_{l \to \infty} \lambda_{n-k}(C_l A C_l') \neq \lambda_1(A). \tag{11}
\]

This is trivial if \( m_1(A) < n-k \) (because in that case (11) is satisfied for any \( g \in E_1(A) \), by the Poincaré separation Theorem; e.g., Horn and Johnson, 1985), but not more generally. Observe, however, that, as long as \( W \notin C \), it is always possible to find a sequence \( \{X_l\}_{l=1}^{\infty} \) such that the following two properties are satisfied: (a) \( \lim_{l \to \infty} \text{col}(X_l) \) does not contain all eigenvectors of \( A \) associated to the eigenvalues other than \( \lambda_1(A) \); (b) \( \lim_{l \to \infty} \|(M_{X_l} f_{\max})^\star - g^\star\| = 0 \) for some \( g \in E_1(A) \). The existence of a \( g \in E_1(A) \) such that (11) holds then follows from Lemma A.3. \[ \square \]

Proof of Theorem 3.3. Consider some arbitrary \( n, k, \alpha, \text{ and } W \notin C \). In the proof of Lemma 3.2 it is shown that a \( \text{col}(X) \) that minimizes \( I(f_{\max}) \), regarded as a function
from \( G_{k,n} \) to \( \mathbb{R} \), always exists and causes a zero limiting power of the Cliff-Ord test to vanish. Since \( I(f_{\max}) \) is continuous at its points of minimum, it follows that (for any \( \alpha < 1 \), it is possible to find a neighborhood, defined according to some arbitrary distance on \( G_{k,n} \), of the points of minimum such that any \( \text{col}(X) \) in this neighborhood causes the limiting power of the size-\( \alpha \) Cliff-Ord test to disappear. Since any such neighborhood has nonzero invariant measure on \( G_{k,n} \) (see James, 1954), the proof is completed. \hfill \blacksquare

**Proof of Theorem 3.5.** The proof is similar to the proofs of Lemma 3.2 and Theorem 3.3. First, we establish some bounds on \( P_\rho \). By Lemma A.2, for all \( \text{col}(X) \in G_{k,n} \) and all \( y \in \mathbb{R}^n \),

\[
P_\rho \leq \lambda_{n-k}(C\Sigma(\bar{\rho})C')^{-1}.
\]

Noting that \( \lambda_{n-k}(C\Sigma(\bar{\rho})C')^{-1} = \lambda_1^{-1}(C_1\Sigma(\bar{\rho})C'_1) \) and that, by Poincaré separation Theorem (e.g., Horn and Johnson, 1985), \( \lambda_1(C_1\Sigma(\bar{\rho})C'_1) \geq \lambda_1(\Sigma) \), we have

\[
P_\rho \leq \lambda_1^{-1}(\Sigma(\bar{\rho})).
\]

On writing \( I = t'(C\Sigma(\bar{\rho})C')^{-1}t/|t|t \), where \( t := Cy \), Lemma A.2 also implies that \( P_\rho \geq \lambda_{n-k}(C\Sigma(\bar{\rho})C') \), for all \( y \in \mathbb{R}^n \). On the basis of the above bounds on \( P_\rho \), and following the same reasoning as in the proof of Lemma 3.2, we now need to show that there exists at least one \( \text{col}(X) \) such that: (i) \( f_{\max} \notin \text{col}(X) \); (ii) the POI statistic evaluated at \( y = f_{\max} \) to be denoted by \( P_\rho(f_{\max}) \), is arbitrarily close to \( \lambda_1^{-1}(\Sigma(\bar{\rho})) \); (iii) \( \lambda_{n-k}(C\Sigma(\bar{\rho})C') \) is not arbitrarily close to \( \lambda_1^{-1}(\Sigma(\bar{\rho})) \).

Consider a sequence \( \{X_t\}_{t=1}^\infty \) defined as in the proof of Lemma 3.2, but with \( A \) replaced by \( \Sigma(\bar{\rho}) \). We have

\[
\lim_{t \to \infty} \Sigma(\bar{\rho})M_{X_t}f_{\max} = \lambda_1(\Sigma(\bar{\rho}))M_{X_t}f_{\max}.
\]  

Premultiplying both sides of (12) by \( C_t \), we obtain

\[
\lim_{t \to \infty} (C_t\Sigma(\bar{\rho})C'_t)C_t f_{\max} = \lambda_1(\Sigma(\bar{\rho}))C_t f_{\max},
\]

and hence

\[
\lim_{t \to \infty} (C_t\Sigma(\bar{\rho})C'_t)^{-1}C_t f_{\max} = \lambda_1^{-1}(\Sigma(\bar{\rho}))C_t f_{\max}.
\]

It follows that, by Lemma A.2,

\[
\lim_{t \to \infty} P_\rho(f_{\max}) = \lim_{t \to \infty} f_{\max}' C_t(C_t\Sigma(\bar{\rho})C'_t)^{-1}C_t f_{\max} = \lambda_1^{-1}(\Sigma(\bar{\rho})). \tag{13}
\]

Expression (13) implies the existence of at least one \( \text{col}(X) \) that satisfies (i) and (ii). In order to establish that there exists at least one \( \text{col}(X) \) that satisfies (i), (ii) and (iii), we need to show that it is possible to choose \( g \in \mathcal{E}_1(\Sigma(\bar{\rho})) \) in such a way that

\[
\lim_{t \to \infty} \lambda_{n-k}(C_t\Sigma(\bar{\rho})C'_t) \neq \lambda_1(\Sigma(\bar{\rho})). \tag{14}
\]
But, as long as \( W \notin \mathcal{C}^* \), it is possible to find a sequence \( \{X_i\}_{i=1}^\infty \) such that \( \lim_{l \to \infty} \text{col}(X_i) \) does not contain all eigenvectors of \( \Sigma(\hat{\rho}) \) associated to the eigenvalues of \( \Sigma(\hat{\rho}) \) different from \( \lambda_1(\Sigma(\hat{\rho})) \) and \( \lim_{l \to \infty} \| (M X_i f_{\text{max}}) - g^* \| = 0 \) for some \( g \in E_1(\Sigma(\hat{\rho})) \). The existence of a \( g \in E_1(\Sigma(\hat{\rho})) \) such that (14) holds then follows from Lemma A.3. We have thus established that there exists a nonempty set of \( k \)-dimensional regression spaces such that the limiting power of a POI test vanishes. That such a set has positive invariant measure on \( G_{k,n} \) follows by the same argument used in the proof of Theorem 3.3 for the Cliff-Ord test.

### Proof of Proposition 3.6

We start from the Cliff-Ord test. Write \( I = t' C A C' t/t' t \), with \( t := Cy \) and \( A := (W + W')/2 \). Then, by Lemma A.2,

\[
I \leq \lambda_{n-k}(C A C'),
\]

(15)

for all \( y \in \mathbb{R}^n \). Consider some arbitrary \( \alpha \), \( X \) and \( W \in \mathcal{C} \). Suppose first that \( f_{\text{max}} \notin \text{col}(X) \). By Lemma A.5, \( I(f_{\text{max}}) = \lambda_{n-k}(C A C') \), which implies that \( f_{\text{max}} \) is in the interior of the Cliff-Ord critical region. The limiting power of the Cliff-Ord test is thus 1, by Lemma A.1. Let us now suppose that \( f_{\text{max}} \in \text{col}(X) \). For any \( W \in \mathcal{C} \), \( m_1(A) = n - 1 \), and hence the application of Lemma A.3 with \( Q = A \) yields \( \lambda_{n-k}(C A C') = \lambda_1(A) \). Then, \( I \leq \lambda_1(A) \) by (15). But, by Lemma A.2, \( I \geq \lambda_1(A) \), for all \( y \in \mathbb{R}^n \) and all \( X \). So, when \( f_{\text{max}} \in \text{col}(X) \), \( I \) does not depend on \( y \), and, as a consequence, the power function of the Cliff-Ord test equals \( \alpha \) for any \( 0 \leq \rho < \lambda_{\text{max}}^{-1} \).

The proof for a POI test is similar. By Lemma A.2,

\[
P_\rho \geq \lambda_{n-k}^{-1}(C \Sigma(\hat{\rho}) C').
\]

(16)

If \( f_{\text{max}} \notin \text{col}(X) \), then, by Lemma A.6, \( P_\rho(f_{\text{max}}) = \lambda_{n-k}^{-1}(C \Sigma(\hat{\rho}) C') \), and hence the limiting power of a POI test is 1, by Lemma A.1. Recall that \( \Sigma(\hat{\rho}) = (I_n - \rho(W + W') + \rho^2 W'W)^{-1} \) and that, for any \( W \in \mathcal{C}^* \), \( m_1(W + W') = m_1(W'W) = n - 1 \). When \( W \in \mathcal{C}^* \), \( W + W' \) and \( W'W \) commute, by Lemma A.4, and hence they are simultaneously diagonalizable. It follows that, for any \( W \in \mathcal{C}^* \), \( m_1(\Sigma(\hat{\rho})) = n - 1 \). Thus, when \( f_{\text{max}} \notin \text{col}(X) \) we can apply Lemma A.3 with \( Q = \Sigma(\hat{\rho}) \), to obtain \( \lambda_{n-k}(C \Sigma(\hat{\rho}) C') = \lambda_1(\Sigma(\hat{\rho})) \). But then, using again Lemma A.2 as for the Cliff-Ord test, we reach the conclusion that \( P_\rho \) does not depend on \( y \) if \( f_{\text{max}} \in \text{col}(X) \), which completes the proof.

### Proof of Proposition 3.7

For any \( W \in \mathcal{C} \), the symmetric matrix \( W + W' \) admits the spectral decomposition

\[
W + W' = 2\lambda_{\text{max}} f_{\text{max}} f_{\text{max}}' + \lambda_1(W + W')(I_n - f_{\text{max}} f_{\text{max}}').
\]

(17)

Since \( (W)_{ii} = 0 \), for \( i = 1, ..., n \), \( W + W' \) has zero trace. Hence the sum of the eigenvalues of \( W + W' \) must be zero, which implies that \( 2\lambda_{\text{max}} = -(n-1)\lambda_1(W + W') \). From (17) we then obtain

\[
(W + W')_{i,i} = \lambda_1(W + W') \left[ (1-n)(f_{\text{max}})_i^2 + (1 - (f_{\text{max}})_i^2) \right]
= \lambda_1(W + W')(1-n(f_{\text{max}})_i^2).
\]
This is 0 for all \( i \) if and only if \((f_{\text{max}})^2 = 1/n\) for all \( i \). But, since \( W \) is a nonnegative irreducible matrix, it follows by the Perron-Frobenius theorem (e.g., Horn and Johnson, 1985, Ch. 8), that \( f_{\text{max}} \) is entrywise positive or entrywise negative. Hence, for a \( W \in \mathcal{C} \), \((f_{\text{max}})\) is independent of \( i \), which is the desired conclusion.

**Proof of Proposition 3.8.** For any \( c > 0 \), the matrix \( c(J_n - I_n) \), where \( J_n \) denotes the \( n \times n \) matrix of all ones, has the simple eigenvalue \((n - 1)c \) and the eigenvalue \(-c\) with multiplicity \( n - 1 \). Hence, any such matrix is a weights matrix in \( \mathcal{C} \), establishing the sufficiency of the condition in the lemma. To prove the necessity, we start by observing that if a real normal matrix has only real eigenvalues, then it is symmetric (Horn and Johnson, 1985, p. 109). Thus, by Lemma A.4, we only need to show that if \( W \in \mathcal{C} \) is symmetric and has zero diagonal entries, then it has identical and positive off-diagonal entries. If \( W \in \mathcal{C} \) is symmetric, we can write

\[
W = \lambda_1(W)I_n + (\lambda_n(W) - \lambda_1(W))f_{\text{max}}f'_{\text{max}}. 
\]  

(18)

Such an expression shows that if \((W)_{ii} = 0\), for \( i = 1, \ldots, n \), then \((f_{\text{max}})^2\) is independent of \( i \). Since \( W \) is nonnegative and irreducible, it follows, by the same argument used at the end of the proof of Proposition 3.7, that \( f_{\text{max}} \) is independent of \( i \). Then, by (18), the off-diagonal entries of \( W \) are identical and positive, which completes the proof.

**Proof of Theorem 4.1.** We start from the part of the theorem relative to the Cliff-Ord test, when \( k \leq m_1(W) \). The first step in the proof is a simplification of the first part of the proof of Lemma 3.2, for the case when \( W \) is symmetric. By replacing the bound \( I \geq \lambda_1(A) \) (that holds for all \( y \in \mathbb{R}^n \) and all \( X \in \mathbb{R}^{n \times k} \)) with the bound \( I \geq \lambda_1(CWC') \) (that holds for all \( y \in \mathbb{R}^n \) and for a fixed \( X \in \mathbb{R}^{n \times k} \)), we obtain that the limiting power of the Cliff-Ord test vanishes for all values of \( \alpha \) if (i) \( f_{\text{max}} \notin \text{col}(X) \), (ii) \( I(f_{\text{max}}) = \lambda_1(CWC') \), and (iii) \( \lambda_1(CWC') \neq \lambda_{n-k}(CWC') \).

Any \( \text{col}(X) \in \Theta \) satisfies (i) by definition. We are now going to show that there are \( \text{col}(X) \in \Theta \) such that \( Cf_{\text{max}} \in E_1(CWC') \), which is equivalent to (ii). Since \( W \) is symmetric, its eigenvectors \( f_i(W), i = 1, \ldots, n \), are pairwise orthogonal. Thus, if \( \text{col}(X) \in \Theta \), \( M_X f_i(W) = f_i(W) \), for \( i = m_1(W) + 1, \ldots, n - 1 \). It follows that, for any \( \text{col}(X) \in \Theta \) and for \( i = m_1(W) + 1, \ldots, n - 1 \),

\[
CWC'Cf_i(W) = CW M_X f_i(W) = CW f_i(W) = \lambda_i Cf_i(W).
\]

That is, the \((n-k) \times (n-k)\) matrix \( CWC' \) admits the \( n - m_1(W) - 1 \) eigenpairs \((\lambda_i(W), Cf_i(W))\), \( i = m_1(W) + 1, \ldots, n - 1 \). But then, by the symmetry of \( CWC' \) and the fact that the vectors \( Cf_i(W), i = m_1(W) + 1, \ldots, n - 1 \) are pairwise orthogonal (because the \( f_i(W) \)’s are), the remaining eigenvectors of \( CWC' \) must be in the subspace spanned by \( Cf_1(W), \ldots, Cf_{m_1(W)}(W), Cf_{\text{max}} \). Observe that, for any \( \text{col}(X) \in \Theta \) and for any \( g \in E_1(W) \cap \text{col}(X) \), \( Cf_{\text{max}} \) and \( Cg \) are linearly dependent. Thus, \( Cf_{\text{max}} \) must be an eigenvector of \( CWC' \), i.e.,

\[
CW M_X f_{\text{max}} = \tilde{\lambda} Cf_{\text{max}},
\]

(19)

for some eigenvalue \( \tilde{\lambda} \). The condition \( Cf_{\text{max}} \in E_1(CWC') \) is satisfied if and only if

\[
\tilde{\lambda} \leq \lambda_{m_1(W)+1}(W).
\]

(20)
As \( \text{col}(X) \in \Theta \) approaches a subspace orthogonal to \( E_1(W) \), \( M_x f_{\text{max}} \) tends to a vector in \( E_1(W) \), which implies, by (19), that \( \lambda \rightarrow \lambda_1(W) \) (note that, by the definition of \( \Theta \), no \( \text{col}(X) \in \Theta \) can be orthogonal to \( E_1(W) \)). Thus, by the continuity of the eigenvalues of a matrix \( (CW') \) in the entries of the matrix, plus the fact that \( \lambda_1(W) < \lambda_{m_1(W)+1}(W) \), there always are \( \text{col}(X) \in \Theta \) that satisfy (20) and hence condition (ii). Such regression spaces satisfy also condition (iii): in order for \( \lambda_1(CW') = \lambda_{n-k}(CW') \) we should have that all the eigenvalues of \( CW' \) are identical, but this is impossible when \( W \notin C \). Note that, since \( W \) is symmetric, the only \( W \in C \) are the equal weights matrices, by Proposition 3.8.

So far, we have established the part of the theorem relative to the case \( k \leq m_1(W) \), for the Cliff-Ord test. The extension to a POI test is straightforward, by relying precisely on the same modifications necessary to move from the proof of Lemma 3.2 to the proof of Theorem 3.5. We now turn to the part of the theorem concerned with the particular case \( k = m_1(W) = 1 \). Let \( X \) be a scalar multiple of \( f_1(W) + \omega f_{\text{max}} \), so that \( \text{col}(X) \in \Theta \) as long as \( \omega \neq 0 \). For the Cliff-Ord test, we need to establish which values of \( \omega \) satisfy (20). When \( m_1(W) = 1 \), (20) reads

\[
\tilde{\lambda} \leq \lambda_2(W),
\]

where \( \tilde{\lambda} \) is the eigenvalue of \( Cf_{\text{max}} \) associated to the eigenvector of \( CW' \). Observe that

\[
M_x f_{\text{max}} = \left[ I_n - \frac{1}{1+\omega^2}(f_1(W) + \omega f_{\text{max}})(f_1(W) + \omega f_{\text{max}})' \right] f_{\text{max}}
\]

\[
= f_{\text{max}} - \frac{\omega}{1+\omega^2}(f_1(W) + \omega f_{\text{max}}) = \frac{1}{1+\omega^2}(f_{\text{max}} - \omega f_1(W)),
\]

where we have used the fact that \( f_1(W) \) and \( f_{\text{max}} \) are normalized and orthogonal. Plugging the above expression for \( M_x f_{\text{max}} \) in (19) gives

\[
\frac{1}{1+\omega^2} \left[ \lambda_{\text{max}} C f_{\text{max}} - \omega \lambda_1(W) C f_1(W) \right] = \tilde{\lambda} C f_{\text{max}}.
\]

Now, since \( CX = O_n, C f_1(W) = -\omega C f_{\text{max}} \). Hence, from (22) we obtain \( \tilde{\lambda} = [\lambda_{\text{max}} + \omega^2 \lambda_1(W)]/(1 + \omega^2) \). This expression can be used to solve (21) in terms of \( \omega \), which yields \( |\omega| \geq [\lambda_{\text{max}} - \lambda_2(W)]^{1/2} / [\lambda_2(W) - \lambda_1(W)]^{1/2} \). The extension to a POI test can be performed by replacing \( W \) with \( \Sigma(\rho) = (I_n - \rho W)^{-2} \). We then need to establish which values of \( \omega \) yield

\[
\tilde{\lambda} \leq \lambda_2(\Sigma(\rho)),
\]

where \( \tilde{\lambda} \) is the eigenvalue of \( C f_{\text{max}} \) associated to the eigenvector of \( C \Sigma(\rho) C' \), with \( \Sigma(\rho) = (I_n - \rho W)^{-2} \). Proceeding exactly as for the Cliff-Ord test, (23) yields

\[
|\omega| \geq [\lambda_{\text{n}}(\Sigma(\rho)) - \lambda_2(\Sigma(\rho))]^{1/2} / [\lambda_2(\Sigma(\rho)) - \lambda_1(\Sigma(\rho))]^{1/2}.
\]

Using \( \lambda_i(\Sigma(\rho)) = (1 - \rho \lambda_i(W))^{-2} \), and after some straightforward algebra, from (24) we obtain \( |\omega| \geq \omega_1 \omega_2 \), which completes the proof.
REFERENCES


