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Empirically Based Modeling in the Social Sciences and Spurious Stylized Facts

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Abstract

The discovery of the dynamics of a time series requires construction of the transition density, 1-point densities and scaling exponents provide no knowledge of the dynamics. Time series require some sort of statistical regularity, otherwise there is no basis for analysis. We state the possible tests for statistical regularity in terms of increments. The condition for stationary increments, not scaling, determines long time pair autocorrelations. An incorrect assumption of stationary increments generates spurious stylized facts, fat tails and a Hurst exponent \( H_s = 1/2 \), when the increments are nonstationary, as they are in FX markets. The nonstationarity arises from systematic unevenness in noise traders’ behavior. Spurious results arise mathematically from using a log increment with a ‘sliding window’. The
Hurst exponent $H_s$ generated by the using the sliding window technique on a time series plays the same role as Mandelbrot’s Joseph exponent. Mandelbrot originally assumed that the ‘badly behaved second moment of cotton returns is due to fat tails, but that nonconvergent behavior provides instead direct evidence for nonstationary increments.

1. Introduction

The finance and physics literature contains many papers claiming scaling via Hurst exponents on the one hand, and fat tailed distributions on the other. The expectations of Hurst exponent scaling, fat tailed distributions, and exponent universality have played a central in econophysics. The question what are the underlying market dynamics has remained controversial, but we provide strong evidence for a martingale [1], i.e., diffusive dynamics.

This paper explains in more detail our recent foreign exchange (FX) data analysis [2]. The main expectations of econophysics, Hurst exponent scaling, universality, and fat tails are not exhibited by FX markets when nonstationary the increments are correctly treated. Correspondingly, we explain why most existing data analysis claiming fat tails and scaling are wrong, including the original paper on reporting fat tails in cotton returns.

The analysis of this paper can be understood as a tale told by two different variables: First, there is what we define [1,2] as the log return

$$x(t) = \ln p(t) / p_c(t)$$ (1)
where $p(t)$ is the price of a stock, bond, or foreign exchange at time $t$, and $p_c(t)$ can be understood as ‘value’ \[3\], the most probable price, the price that locates the peak of the 1-point returns density $f_1(x,t)$ at time $t$. Then, there is what most other theorists (beginning with Osborne) mean by log returns,

$$x(t,T) = x(t+T) - x(t) = \ln p(t+T)/p(t),$$

but which is clearly an *increment* of the log return. The log return $x(t)$ is always a ‘good’ variable both in theory and data analysis, but the use of the log increment $x(t,T)$ in data analysis leads to spurious stylized facts, to spurious scaling with exponent $H_s=1/2$ and spurious fat tails in a wrongly extracted 1-point returns density $f_s$, where the subscript “s” denotes ‘sliding window’. The two variables will yield identical results iff. a data set or model generates stationary increments $x(t,T)=x(T)$. We show correspondingly that the 1-point returns density $f_1(x,t)$ correctly extracted from FX market time series gives evidence neither for scaling with $H$ over a time scale of a day, nor for fat tails. We speculate that stock prices, in contrast, may exhibit fat tails (but not Hurst exponent scaling) over the same time scale. There is no evidence for market universality, and in far from equilibrium dynamics there is no reason to expect universality.

Drift-free Markov, and more generally martingale processes generate uncorrelated increments that are generally nonstationary, reflecting a hard to beat market: $<x(t,T)x(t,-T)>=0$ where $x(t,-T)=x(t)-x(t-T)$. If the mean square fluctuation $<x^2(t,T)>$ depends on the starting time $t$ then the increments are nonstationary. In FX (and in most other) data analyses stationary increments have been *implicitly* assumed by the use of a technique called a “sliding window”. A ‘sliding window’ is used to build histograms by reading a
time series while varying t in the increment $x(t,T)$ with T fixed, and in the presence of nonstationary increments this method cannot generate the correct density $f_1(x,t)$. Instead, the method at best generates a spurious density $f_s(z,t,T)$ that we will define precisely below. The sliding window technique would be legitimate, would yield $f_1(z,T)$ independent of starting time t iff. the increments were stationary, iff. $z=x(t,T)=x(T)$ independent of the starting time t. But the increments in finance data are not stationary [2], and there is no ergodicity in a nonstationary (i.e., far from statistical equilibrium) time series, so that the sliding window method produces ‘significant artifacts’, spurious stylized facts.

Another conclusion is that scaling doesn’t matter anyway [1], scaling gives us no information whatsoever about either the underlying market dynamics or memory. The purpose of this paper is to explain how to analyze random time series without generating spurious stylized facts. Our method and conclusions are not restricted to finance data but have application to the analysis of stochastically generated time series, whether in physics, economics, biology, or elsewhere. We offer a new viewpoint in the theory of stochastic processes and in data analysis. This paper defines the requireents from extracting knowledge of dynamics from empirically generated time series, whether in the social sciences, turbulence, or elsewhere.

2. Hurst exponent scaling

We define selfsimilar stochastic processes and then show that selfsimilarity is restricted to 1-point densities. A stochastic process $x(t)$ is said be selfsimilar with scaling exponent $H$, $0<H<1$, if [4,5]
\[ x(t) = t^H x(1), \quad (3) \]

where by equality we mean equality ‘in distribution’. Note first that scaling trajectories necessarily pass through the ‘filter’ \( x(0)=0 \), trajectories with \( x(0) \neq 0 \) cannot possibly scale. Second, a method designed by Hurst to detect trends was originally used to define a different scaling exponent that Mandelbrot and Taqqu labeled the Joseph exponent \( J \) [6]. However, the notation “\( H \)” was used by Mandelbrot and van Ness [5] to describe fractional Brownian motion (fBm), a selfsimilar process that does produce the trends of the Hurst-Mandelbrot ‘Joseph Effect’ via long time pair correlations arising from stationarity of the increments. Mandelbrot and Taqqu distinguished \( H \) from \( J \) on the basis of Hurst’s (highly nontransparent) R/S analysis, and noted that while \( H=J \) for fBm, for processes without long time increment autocorrelations, like Levy processes and drift free Markov processes, \( H \neq J = 1/2 \). Embrechts [4] denotes the selfsimilarity exponent by \( H \), but stops short of writing \( H(urst) \). Because of the vast confusion in the scientific literature, wherein \( H \neq 1/2 \) is too often but wrongly thought to imply long time pair correlations, we will call the selfsimilarity exponent \( H \) “the Hurst exponent” and explain that selfsimilarity, taken alone, does not and cannot generate long time pair autocorrelations like those of fBm. We will introduce a second scaling exponent, the ‘sliding window Hurst exponent’ \( H_s \), and will see that \( H_s \) plays essentially the same role as does the Joseph exponent: \( H \neq H_s = 1/2 \) whenever there is selfsimilarity without long time pair correlations, but \( H=H_s \neq 1/2 \) in the presence of long time pair correlations combined with selfsimilarity. The essential requirement for long time pair correlations will be seen to be stationarity of the increments with variance nonlinear in \( t \), not selfsimilarity. Selfsimilarity and stationarity of the increments are confused together into an unhealthy and misleading soup too often in the literature (see, e.g., the definition of the Hurst exponent in Wikipedia,
http://en.wikipedia.org/wiki/Hurst_exponent, where the note added Oct., 2007, is ours). Next, we define selfsimilarity in terms of probability densities, which explains what is meant by asserting that x(t)=t^Hx(1) ‘in distribution’.

The 1-point density f_1(x,t) reflects the statistics collected from many different runs of the time evolution of x(t) from a specified initial condition x(t_0), where x(0)=0 is required for scaling, but cannot describe correlations or the lack of same. Given a dynamical variable A(x,t), the absolute (as opposed to conditional) average of A is

\[ \langle A(t) \rangle = \int_{-\infty}^{\infty} A(x,t) f_1(x,t) dx. \quad (4) \]

From (1), the moments of x must obey

\[ \langle x^n(t) \rangle = t^{nH} \langle x^n(1) \rangle = c_n t^{nH} \quad (5) \]

Combining this with

\[ \langle x^n(t) \rangle = \int x^n f_1(x,t) dx \quad (6) \]

we obtain

\[ f_1(x,t) = t^{-H} F(u), \quad (7) \]

where the scaling variable is u=x/t^H [1,7].

In contrast, the conditional averages \( <A(x,t)>_{\text{cond}} \) needed in finance require the 2-point density

\[ f_2(x,t+T;y,t) = p_2(x,t+T|y,t)f_1(y,t), \quad (8) \]
or, more to the point, the 2-point transition density (conditional probability density) $p_2(x,t+T:y,t)$.

If the absolute average of $x(t)$ vanishes, then the variance is simply

$$\sigma^2 = \langle x^2(t) \rangle = \langle x^2(1) \rangle t^{2H}. \quad (9)$$

This explains what is meant by Hurst exponent scaling, and also specifies what’s meant by asserting that eqn. (1) holds ‘in distribution’. There, ‘in distribution’ refers strictly to the 1-point density, a quantity that tells us nothing about the underlying dynamics.

The vanishing of the absolute average of $x$ does not mean that there’s no conditional trend: in fractional Brownian motion (fBm), e.g., where $\langle x(t) \rangle = x(0) = 0$ by construction, the conditional average of $x$ does not vanish and depends on $t$ [7], reflecting either a trend or an anti-trend. In a Markov process, scaling requires that the drift rate depends at worst on $t$ (is independent of $x$) and has been subtracted, that by “$x$” we really mean the detrended variable $x(t) - \int R(s) ds$. Markov processes with $x$-independent drift can be detrended over a definite time scale, but any attempt to detrend fBm is an illusion because the ‘trend’ is due to long time autocorrelations, not to a removable additive drift term [1]. The attempt to detrend a time series $x(t)$ implicitly assumes an underlying martingale $M(t)$ plus drift $A(t)$, $x(t) = A(t) + M(t)$, and fBm is by construction not of that form [1,7].

Hurst exponent scaling is restricted to 1-point densities and simple averages, and 1-point densities cannot be used to identify the underlying stochastic dynamics [1,7,9]. Even if scaling holds at the 1-point level as in fBm, the 2-point density (the transition density $p_2$) and the pair correlations $\langle x(t+T)x(t) \rangle$
do not scale, and it’s the transition density $p_2$, or at least the pair correlations, that’s required to give a minimal description of the underlying dynamics\(^1\). In particular, scaling, taken alone, implies neither the presence nor absence of autocorrelations in increments/displacements taken over nonoverlapping time intervals. That is, scaling has nothing whatsoever to say about whether a market is effectively efficient (hard to beat), or is easily beatable, in contrast to what at least one of us incorrectly assumed earlier [3,10].

The financial economics literature reflects wrong claims and wrong assumptions about financial time series. In Fama [11], e.g., the claim is made that returns are uncorrelated, $\langle x(t+T)x(t) \rangle = 0$. The correct statement, explained below, is that both prices and returns are always correlated, $\langle p(t+T)p(t) \rangle \neq 0$, $\langle x(t+T)x(t) \rangle \neq 0$, but increments in returns approximately vanish after a trading time of 10 minutes: $\langle x(t,T)x(t,-T) \rangle \approx 0$ for $T \geq 10$ min. of trading [2]. The latter is effectively the efficient market hypothesis: one cannot make money systematically by trading on either simple averages or pair correlations [1]. Note that an assumption of stationary increments, the confusion of $x(t,T)$ with $x(T)$, would lead one wrongly to assert that returns are uncorrelated. Some statisticians and financial economists [12] treat nonstationary time series as if they cold be transformed into stationary ones, but as we show below this is topologically impossible.

3. Stationary vs. nonstationary increments

Stationary processes are often confused with stationary increments in the literature (see [8] for a discussion). Stationary increments are implicitly assumed in data

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\(^1\) For a Gaussian process, pair correlations and $p_2$ provide a complete description. But for nonGaussian processes like FX markets all of the transition densities $p_n$, $n=2,3,\ldots$ are required to pin down the dynamics. In practice, we usually do not know any more about the dynamics than can be extracted from pair correlations.
analyses and simulations whenever a sliding window method is used to extract histograms, and the sliding window method is implicitly assumed whenever \(x(t,T)\) is treated as the variable in data analysis (see, e.g., [13]). We define stationary and nonstationary increments and exhibit their implications for the question of long time autocorrelations, or complete lack of autocorrelations. We emphasize that the question of stationary increments, not scaling, is central for the existence of long time correlations.

By increments, we mean displacements \(x(t,T) = x(t+T) - x(t)\). Stationary increments of a nonstationary process \(x(t)\) are defined by [4,5,7]

\[
x(t + T) - x(t) = x(T), \quad (10)
\]

and by nonstationary increments [1,7,15] we mean that the difference

\[
x(t + T) - x(t) \neq x(T) \quad (11)
\]

depends on both \((t,T)\), not on \(T\) alone. The implications of this distinction for data analysis, and for understanding Hurst exponents, are central. Although the correct 1-point density is \(f_1(x,t) = \int dy f_2(y,t+T;x,t)\) by definition, in the nonstationary increment case the density of increments \(z = x(t,T)\) must be obtained from the two-point density via

\[
f_s(z,t,T) = \int dx dy f_2(y,t+T;x,t) \delta(z - y + x) \quad (12)
\]

and depends on \(t\). In general we cannot assume time-translational invariance, \(f_2(y,t+T;x,t) \neq f_2(y,T;x,0)\), even for a stationary increment process like fBm [7], even though for stationary increments the 1-point density (12) is independent of \(t\), \(f_s(x,t,T) = f_1(z,T)\). In this case sliding windows can be used
to obtain histograms for the correct 1-point density \( f_1(z,T) \) from a single long time series.

The efficient market hypothesis (EMH) is sometimes interpreted to mean that the market is impossible to beat [12], that there are no correlations at all (no systematically repeated price/returns patterns) that can be exploited for profit. Real markets are certainly hard to beat. A Markov market satisfies the condition of an impossible to beat market. But because real markets are very hard if not necessarily impossible to beat, models that generate no autocorrelations in increments are a good zeroth order approximation to real markets [1]. In such models, the autocorrelations in increments \( x(t,T) \) and \( x(t,-T) \) vanish

\[
\langle (x(t_1) - x(t_1 - T_1))(x(t_2 + T_2) - x(t_2)) \rangle = 0, \quad (13)
\]

if there is no time interval overlap,

\[
[t_1 - T_1, t_1] \cap [t_2, t_2 + T_2] = \emptyset, \quad (14)
\]

where \( \emptyset \) denotes the empty set on the line. This is a much weaker and more pregnant condition than would be asserting that the increments are statistically independent. Condition (14) is in fact a martingale condition in weak disguise. Eqn. (14) means that nothing that happened in an earlier time interval can be used to predict systematically the returns in a later time interval at the level of (simple averages and) pair correlations. That is, the market is ‘effectively efficient’ in the sense that simple averages and pair correlations look Markovian, unlike fBm there is no memory in pair correlations to be exploited. This may not rule out higher order correlations that might be used for technical trading. I.e., a Markovian market is ‘efficient’ in the strictest
sense, is impossible to beat, whereas a martingale market looks Markovian to lowest order (at the level of simple averages and pair correlations), but might be systematically beatable at some higher level of insight. This defines precisely what we mean by “lowest order”. It was Mandelbrot who suggested martingales as reflecting the EMH [15], a real market may exhibit memory but that memory will be hard to find and exploit for profit.

Consider a stochastic process $x(t)$ where the increments are uncorrelated. From this condition we easily obtain the autocorrelation function for returns $x(t)$

$$\langle x(t)x(s) \rangle = \langle (x(t) - x(s))x(s) \rangle + \langle x^2(s) \rangle = \langle x^2(s) \rangle > 0, \quad (15)$$

since $x(s)-x(t_o)=x(s)$, so that $\langle x(s)x(t) \rangle = \langle x^2(s) \rangle = \sigma^2$ is simply the variance in $x$. *This is a martingale condition,*

$$\langle x(t+T) \rangle_{\text{cond}} = x(t), \quad (16)$$

or

$$\int dx\,yp_x(y,t+T|x,t) = x. \quad (17)$$

The result has a nice interpretation: since $\langle x(t,T)x(s) \rangle = 0$ for $s \leq t < t+T$, future ‘gains’ $x(t,T)$ are uncorrelated with all past returns. We interpret an efficient market to mean that there are no pair correlations that can be exploited for profit. This doesn’t rule out higher order correlations in a martingale.

We next obtain another central result. Combining

$$\langle (x(t+T) - x(t))^2 \rangle = +\langle x^2(t+T) \rangle + \langle x^2(t) \rangle - 2\langle x(t+T)x(t) \rangle$$

(18)
with (14), we get
\[
\langle (x(t + T) - x(t))^2 \rangle = \langle x^2(t + T) \rangle - \langle x^2(t) \rangle
\]  
(19)

which depends on both \( t \) and \( T \), excepting the rare case
where the variance \( \langle x^2(t) \rangle \) is linear in \( t \). Martingale increments
are uncorrelated and are generally nonstationary. I.e., we must
expect nonstationary increments in effectively efficient
markets. The variance \( \langle x^2(t) \rangle \) of a real FX market is not
linear in \( t \), it has instead very complicated variation with
time.

Consider next the class of all stochastic processes with
stationary increments, \( x(t,T) = x(T) \) ‘in distribution’. Here, we
begin with
\[
-2\langle x(t + T)x(t) \rangle = \langle (x(t + T) - x(t))^2 \rangle - \langle x^2(t + T) \rangle - \langle x^2(t) \rangle,
\]
(20)

and then using (8) on the right hand side of (18) we obtain
\[
-2\langle x(t + T)x(t) \rangle = \langle x^2(T) \rangle - \langle x^2(t + T) \rangle - \langle x^2(t) \rangle
\]
(21)

which differs from (13). The increment autocorrelation
function is
\[
2\langle (x(t) - x(t-T))(x(t+T) - x(t)) \rangle = \langle x^2(2T) \rangle - 2\langle x^2(T) \rangle
\]
(22)

which vanishes iff. the variance \( \langle x^2(t) \rangle \) is linear in \( t \).
Stationary increments are typically strongly correlated. E.g., if
scaling (1) holds then we obtain the prediction of infinitely
long time autocorrelations.
\[
\langle(x(t) - x(t-T))(x(t+T) - x(t))\rangle = \langle x^2(T)\rangle(2^{2H-1} - 1).
\] (23)

characteristic of fBm [5,7]. This autocorrelation vanishes iff. 
\(H=1/2\), otherwise the autocorrelations are strong for all time 
scales \(T\). Such fluctuations violate the EMH, especially if \(H\) 
cannot be approximated as \(H\approx1/2\). Note that scaling is not 
the essential point, is in fact irrelevant: stationarity of the 
increments, reflected in the \(t\)-independent pair correlations (21), is 
the central requirement for long time increment autocorrelations.

Summarizing, the Hurst exponent \(H\) tells us nothing 
whatsoever about autocorrelations in increments, tells us 
nothing whatsoever about the underlying dynamics apart 
from scaling itself, and tells us nothing whatsoever about the 
efficiency or lack of same of a market. In the next two 
sections we will sharpen the distinction by exhibiting both 
scaling Markov processes and fBm where \(H\not\approx1/2\).

4. Selfsimilar Ito Processes

An Ito process is generated locally by the stochastic 
differential equation (sde)

\[
dx = R(x,t) + \sqrt{D(x,t)}dB(t). \quad (24)
\]

where \(B(t)\) is the Wiener process. A Wiener process is an 
uncorrelated Gaussian process scaling with \(H=1/2\), so that 
the increments are stationary and (from Ito’s theorem) 
\(dB^2=dt=<dB^2>\). Iff. \(R(x,t)=R(t)\) is independent of \(x\) can we 
detrend all trajectories once and for all by replacing \(x(t)\) by 
\(x(t)-\int R(s)ds\). With this substitution, the Ito process is a 
martingale. The absolute average gives \(<x(t)>0\) and there is
no trend. Finite memory may be present but we will not write the possible memory explicitly. Instead,

The variance can be calculated from the stochastic integral of (24) as

\[ \sigma^2 = \int_0^t ds \int_{-\infty}^{\infty} dx f(x, s)D(x, s), \]  

(25)

where \( x(0) = 0 \), so that scaling of the density and the variance imply that the diffusion coefficient scales as well [8]:

\[ D(x, t) = t^{2H-1}D(u), u = x / t^H. \]  

(26)

Note that scaling of \( D \) does not imply scaling of the transition density \( p_\sigma(x, t+T; x_0, t) \).

We can also write the mean square fluctuation about an arbitrary point \( x(t) \) globally as

\[ \langle (x(t+T) - x(t))^2 \rangle = \int_0^{t+T} ds \int_{-\infty}^{\infty} dx f(x, s)D(x, s) = \langle x^2(1) \rangle((t+T)^{2H} - t^{2H}) \]  

(27)

and locally for \( t >> T \) as

\[ \langle (x(t+T) - x(t))^2 \rangle \approx t^{2H-1}D(u)T. \]  

(28)

Both the global and local mean square fluctuations are useful in FX data analysis. In particular, in () the mean square fluctuation scales with \( T \) with \( H_s = 1/2 \).

An Ito stochastic process may have finite memory. By ‘finite memory’ we mean a ‘filtration’ \( (x_{n-1}, x_{n-2}, \ldots, x_i) \) that every trajectory must pass through. An example with \( n=2 \) is given in [16,17].
Ito processes are 1-1 with Fokker-Planck pdes [8,18] so we work with the drift free Fokker-Planck pde

$$\frac{\partial p_2}{\partial t} = \frac{1}{2} \frac{\partial^2}{\partial x^2} (D p_2),$$  \hspace{1cm} (29)

where scaling may occur at best only for \( f_1(x,t) = p_2(x,t;0,0). \)

Model 1-point densities that scale with \( H \) are easily calculated [8,18,19]. With

\[
f_1(x,t) = t^{-H} F(u); u = x / t^H \tag{30}
\]

and

\[
D(x,t) = t^{2H-1} D(u), u = x / t^H \tag{31}
\]

the Fokker-Planck pde (32) yields

\[
2H(u F(u))' + (D(u) F(u))'' = 0 \tag{32}
\]

which we integrate to obtain

\[
F(u) = \frac{C}{D(u)} e^{-2H f_1 u / D(u)} \tag{33}
\]

For \( H \neq 1/2 \) all of these processes generate nonstationary increments.
\[ D(u) = \frac{(1 + |u|)}{2H} \quad (34) \]

Then we get the exponential density

\[ F(u) = Ce^{-|u|}, \quad (35) \]

where \( C \) is the normalization constant. For FX data a 2-sided exponential density is needed and is easily derived.

5. The Minimal Description of Dynamics

A 1-point density cannot be used to identify the underlying dynamics. Given a 1-point density or a diffusive pde for a 1-point density, we cannot even conclude that we have a diffusive process. The 1-point density for fBm, a nondiffusive process with long time increment autocorrelations, satisfies exactly the same diffusive pde as does a Gaussian Markov process, whereas the transition density for fBm satisfies no pde. A detrended diffusive process has no increment autocorrelations, so that the pde for the transition density is also diffusive (Fokker-Planck). Therefore, the minimal knowledge needed to identify the c of dynamics is either the transition density depending on 2 points, or else the specification of the pair correlations \( <x(t)x(s)> \) or increment autocorrelations. Nothing less will suffice.

For a general stochastic process, transition densities depending on histories of all orders \( n \) are required. Pair correlations are adequate to determine all of those densities in exactly two cases. For a drift-free process with \( <x(t)x(s)>=<x^2(s)> \), \( s<t \), the process is either Markovian (is memory-free) or else is a martingale with finite memory. In either case the process is diffusive and \( p_n=p_2, \ n\geq 2 \). The other
case where pair correlations determine the process is for Gaussian processes. There, the pair correlations specify the required Gaussian densities of all orders [20].

Here, we cannot determine whether an underlying stochastic process is diffusive, has long time memory like fBm, or arises from correlated noise as in statistical physics near thermal equilibrium without specifying $<x(t)x(s)>$. Two of these three cases are treated below in the text.

6. Inequivalence of stationary and nonstationary processes

We showed earlier that, in contrast with claims made in many financial math texts, an arbitrary martingale is topologically inequivalent to a Wiener process [1]. By a similar path we can show that nonstationary time series are topologically inequivalent to stationary ones. By treating time series as if the noise would always be white, this problem has been seriously mishandled in regression analysis [12].

In regression analysis it’s sometimes assumed that a nonstationary time series can be transformed into a stationary one. This is generally impossible. Stationarity is an analog of the notion of “integrability” in nonlinear dynamics [1]. We show next that global transformations from nonstationarity to stationarity are topologically impossible.

Locally seen, every sde is a Wiener process (the noise is always locally white): with

$$dx = R(x,t)dt + \sqrt{D(x,t)}dB$$  \hspace{1cm} (36)

the local solution, meaning the solution over a very short finite time interval $\delta t = t - t_o$ is
With the transformation \( y = (x - x_0) / (\sqrt{D(x_0, t_0)}) \delta t \) we get a stationary process: \( \langle y^2 \rangle = 1, \langle y \rangle = 0 \), and the density of \( y \) is a stationary Gaussian (see also [12], which goes no further than this). Next, we ask if such a transformation is globally possible. As in nonlinear dynamics or differential geometry, this is an integrability question.

The integrability problem can easily be formulated by using Ito calculus. Starting with the sde for \( x(t) \) we ask for a global transformation \( y = G(x, t) \) to a Wiener process. From a Wiener process \( B(t) \) one can trivially transform to a stationary process \( B(1) = t^{1/2} B(t) \). Given the sde

\[
\frac{dy}{dt} = \left( \frac{\partial G}{\partial t} + R \frac{\partial G}{\partial x} + \frac{1}{2} \frac{\partial^2 G}{\partial x^2} \right) dt + \frac{\partial G}{\partial x} \sqrt{D} dB,
\]

the condition for a Wiener process is

\[
\frac{\partial G}{\partial t} + R \frac{\partial G}{\partial x} + \frac{1}{2} \frac{\partial^2 G}{\partial x^2} = \mu(t),
\]

\[
\frac{\partial G}{\partial x} \sqrt{D} = c = \text{constant}
\]

(39)

The required integrability conditions (the conditions that \( G \) exists globally) are

\[
\frac{\partial^2 G}{\partial x \partial t} = \frac{\partial^2 G}{\partial t \partial x}
\]

(40)

with

\[
x(t) = x_0 + R(x_0, t_0) \delta t + \sqrt{D(x_0, t_0)} \delta B.
\]

(37)
\[
\frac{\partial G}{\partial t} = \mu(t) - cR / \sqrt{D} + \frac{1}{4} \frac{\partial D}{\partial x} / D^{3/2}, \\
\frac{\partial G}{\partial x} = c / \sqrt{D}
\]

(41)

An easy calculation shows that the only process satisfying global integrability is another Wiener process \(y = \mu t + cB\). A nonstationary process with \(D(x,t)\) depending on \(x\) cannot be transformed to a Wiener process! Processes with \(R\) and \(D\) depending only on \(t\) are trivially Wiener by a simple transformation of variables.

One can ask more generally if a nonstationary process can be transformed into an asymptotically stationary process like Ornstein-Uhlenbeck. This can also be formulated as an integrability question, and there is at this stage no general answer. Given some asymptotically stationary process

\[
dy = -\gamma(y)dt + \sqrt{E(y)}dB
\]

(42)

with the appropriate condition on \(\gamma\), the conditions are then

\[
\frac{\partial G}{\partial t} + \sigma R / \sqrt{D} - \frac{1}{4} \frac{\partial D}{\partial x} / D^{3/2} = -\gamma(y), \\
\frac{\partial G}{\partial x} \sqrt{D} = E(y)
\]

(43)

where we must know \(G\) in advance and then invert to obtain \(x = H(y,t)\) in order to test for integrability. No general theory is available, and our conjecture is that the procedure is generally impossible. The deterministic analog is that nonintegrable deterministic systems cannot be transformed into integrable ones. In any case, there is no reason to believe
a priori that an arbitrary nonstationary process can be transformed into a stationary one.

A scaling 1-point density can be transformed into a stationary 1-point density, \( F(u) = t^H f_1(x,t) \). However, both the transition density \( p_2 \) (which does not scale) and the Ito sde [21] shows that the \( u \)-process is nonstationary.

7. Time Series Analysis

One needs many runs of the same identical experiment in order to obtain good histograms/statistics and averages. This means that for data analysis we need different \( N \) realizations of the time series \( x_k(t) \), \( k=1,...,N \), where for good statistics \( N \gg 1 \). At time \( t \) each point in each run provides one point in a histogram. The average of a dynamical variable \( A(x,t) \) is then given by

\[
\langle A(x,t) \rangle = \frac{1}{N} \sum_{k=1}^{N} A(x_k(t), t)
\]

(44)

where the \( N \) values \( x_k(t) \) are taken from different runs at the same time \( t \). Suppose that the outcome \( x_m(t) \) occurs \( F_m \) times during the \( N \) runs, and denote \( f_m = F_m / N \) with

\[
N = \sum_{m=1}^{N} F_m .
\]

(45)

Then

\[
\langle A(x,t) \rangle = \sum_{m=1}^{N} f_m A(x_m(t), t).
\]

(46)

The \( f_m \) are what we mean by the histograms for the 1-point density. If the histograms can be approximated by a smooth density \( f_1(x,t) \), then (46) becomes
\[ \langle A(x,t) \rangle = \int dxf_1(x,t)A(x,t). \quad (47) \]

This is the absolute average. In finance, for calculating option prices, e.g., we always want instead the conditional average starting from a specific initial condition \((x_0,t_0)\). This would require histograms for \(f_2(y,t;x,s)\), whereby \(p_2 = f_2/f_1\) could then be constructed. In practice this is hard. What one does instead is to first check the increment autocorrelations. If the increment autocorrelations vanish then we have a martingale. Martingales obey diffusive dynamics. If \(f_1\) has been extracted, then the diffusion coefficient \(D(x,t)\) can be found by solving the inverse problem in the diffusion pde \([10,18]\), both \(p_2\) and \(f_1\) satisfy the same pde for Ito processes \([16,17]\). This requires first that one knows the time dependence of \(f_1\). If scaling holds then this is easy, one need only find the Hurst exponent \(H\) for the variance. But scaling generally does not hold. FX data are traded 24 hours/day. In that case, when we analyze one market, e.g. the London market, then the we must reset the clock and take an arbitrary time, say 9AM, as the starting time each day \([2]\).

A single time series provides no statistics, no histograms: there is only one point at each time \(t\). Dynamics cannot be deduced from a single time series unless very special conditions are first met. There are only two special cases where we can avoid \(N\) runs of the experiment and obtain histograms and averages from a single, long time series like a 6-7 year price series converted to returns \(x(t)\). The first two methods are inapplicable in finance, and we state them in order to warn the reader to avoid the mistakes that follow from their widespread misapplication.
First, if the time series is stationary then the 1-point density and all absolute averages are \( t \)-independent [14]. In this case we have the ergodic theorem [20,22],

\[
\langle A(x) \rangle = \frac{1}{N} \sum_{k=1}^{N} A(x_k(t)) = \int dx A(x)f_1(x) \tag{48}
\]

where the 1-point density is obtained from the time series from ergodicity: Equally sized regions in the one dimensional phase space \( x \) are visited equally frequently, so we can obtain coarsegrain the interval \( x_{\min} < x < x_{\max} \) into cells and obtain \( f_k \) by counting how often \( x_k \) occurs in the time series. If there is no drift and the motion is bounded (takes place in a box) then \( f_1(x) = \text{constant} \). But finance markets are nonstationary, are very far from statistical equilibrium. The equations that describe finance markets do not even admit statistical equilibrium as a possibility.

Second, if the increments are stationary, \( x(t+T) = x(t) = x(T) \), then we can obtain \( f_1(x,T) \) from a single ,long time series by sliding a window. We start at a point \( t \), read the value of \( x \) at the point \( t+T \), and thereby construct a histogram that yields \( f_1(x,T) \). In this case the log increment \( x(t) = \ln p(t+T)/p(t) = \ln p(T)/p(0) \) is a ‘good’ variable, and a single long time series yields ‘good statistics’. We may test for stationary increments by breaking the time series up into \( N \) ‘runs’ of equal length, and then calculating the mean square fluctuation

\[
\langle (x^2(t,T)) \rangle = \frac{1}{N} \sum_{k=1}^{N} x_k^2(t,T) \tag{49}
\]

for all different times \( t_{\min} < t < t_{\max} \) in a single run. If the increments are stationary then the mean square fluctuation is constant, independent of starting time \( t \). Financial time series do not have stationary increments.
The reader is now referred to a discussion in chapter 1 of [10] where it’s implicitly argued that nothing can be discovered unless something is periodic, or is in some sense systematically repeated, or is invariant (period zero). The repetitiveness in ergodicity (quasiperiodicity), and with stationary increments \( x(T) = x(t,T) \) the 2-point density (but not the 1-point density!) is time translationally invariant.

What can we do if we have a single, long time series and the increments are nonstationary and uncorrelated? In this case we must start by making an ansatz. We assume, e.g., that the traders repeat the same stochastic dynamics each day. This is equivalent to assuming that the same diffusion coefficient \( D(x,t) \) describes the trading day after day. So each day is regarded as a rerun of the same ‘experiment’. One can check this as follows. Calculate the mean square fluctuation \( \langle x^2(t,T) \rangle \) for one day. Then, calculate the same quantity on the time scale of a week. If the ansatz is true then the weekly plot of the mean square fluctuation will look like 5 repetitions of the daily plot.

If this fails, then there is no need to write finance or economics texts because there is no empirical basis, or any other basis, for discovering any lawful behavior whatsoever. The same argument applies to other social sciences. We would then be in the situation described by Wigner [11,23] where there may be laws of motion but we would have no way to discover them.

In superficial contradiction to Wigner’s observation, we’ve described how to discover an empirical model without any apparent underlying invariance principle, but that is not entirely true. Consider arbitrage on a single stock, say AMD. If there is no arbitrage from market to market, then the probability densities for AMD are the same at every location
on the globe where AMD is traded (to within taxes and trading costs). This is the analog of rotational invariance in physics. There is no corresponding conservation law (there is no Lagrangian to which one can apply Noether’s Theorem [24]) but there is still the invariance that Wigner told us must be present for the effort to succeed.

8. Spurious Stylized Facts

We begin with ‘the observed stylized facts’ of FX markets as stated by Holmes [25]: (i) asset prices are persistent and have, or are close to having, a unit root and are thus (close to) nonstationary; (ii) asset returns are fairly unpredictable, and typically have little or no autocorrelations; (iii) asset returns have fat tails and exhibit volatility clustering and long memory. Autocorrelations of squared returns and absolute returns are significantly positive, even at high-order lags, and decay slowly; (iv) Trading volume is persistent and there is positive cross-correlation between volatility and volume. These statements reflect a fairly standard set of expectations. Next, we contrast those expected stylized facts with the hard results of our recent FX data analysis [2]. Our analysis is based on 6 years of Euro/dollar exchange rates taken at 1 min. intervals.

In point (i) above ‘unit root’ means that in $p(t+T) = ap(t) + \text{noise}$, $a=1$. That is a necessary condition for a martingale. That rules out persistence (like fBm), and prices are not ‘close to nonstationary’ prices are far from stationary. (ii) Increment autocorrelations in FX market returns will vanish after about 10 min. of trading, and a simple coordinate transformation $x(t) = \ln p(t)$ cannot erase persistence, whatever ‘persistence’ might be. Both prices and returns have positive autocorrelation, $<x(t+T)x(t)> = <x^2(t)> >$
0, and autocorrelations in increments are approximately zero after 20 min. of trading, \(<x(t,T)x(t,-T)>\approx 0\). (iii) We find no evidence for fat tails, and no evidence for Hurst exponent scaling on the time scale of a day. Because of nonstationarity of the increments, a 7 yr. FX time series is far too short (the histograms have too much scatter due to too few points) to indicate what may happen on larger time scales. Although we do not present the proof here, volatility clustering does not indicate ‘long memory’ but is explained as a purely Markovian phenomenon for variable diffusion processes, stochastic processes with diffusion coefficients \(D(x,t)\) where the \((x,t)\) dependence is inherently nonseparable [8,18,19].

About point (iv) above, we offer no comment in this paper. Our main point is: the data analyses used to arrive at the expected stylized facts have all used a technique called ‘sliding windows’ [2]. The aim of this section is to explain that sliding windows produce spurious, results because FX data are nonstationary processes with nonstationary increments. Only one previous FX data analysis [26] that we are aware of showed that sliding windows lead to a spurious Hurst exponent \(H_s=1/2\), and correctly identified the cause as nonstationarity of the increments. We explain that result theoretically below.

Here’s what’s meant by the sliding window method: one treats the increment \(z=x(t,T)\) as if it would be independet of time of day \(t\), and attempts to construct histograms \(f_1(z,T)\) for increments at different lag times \(T\) by reading a time series of returns \(x(t)\). There, one starts at initial time \(t\) and forms a window at time \(t+T\). One assumes that the increment \(z=x(T,t)=x(t+T)-x(t)\) generates a 1-point density that is independent of \(t\) by sliding the window along the entire length of the time series, increasing \(t\) by one unit at a time while holding \(T\) fixed. For a long time series, one of at least \(t_{\text{max}}\approx\) several years in length, this method is expected to
produce good statistics because it picks up a lot of data points. But the histograms generated from varying \( t \) in the increments \( x(t,T) \) yield \( f_1(z,T) \) independently of \( t \) iff. the increments are stationary, otherwise the assumption is false. And the assumption is false: first, fig. 1 shows that the increments are uncorrelated after about 10 min. Second, fig. 2a shows that the mean square fluctuation \( \langle x^2(t,T) \rangle \) with \( T \) fixed at 10 min. depends very strongly on \( t \) throughout the course of a trading day. This means simply that the traders’ noisy behavior is not independent of time of day. Our conclusion is that FX data, taken at 10 min. (or longer) intervals are described by a martingale with nonstationary increments in log returns.

To illustrate how spurious stylized facts are generated by using a sliding window in data analysis, we apply that method to a time series with uncorrelated nonstationary increments, one with no fat tails and with a Hurst exponent \( H=.35 \), namely, a time series generated by the exponential density \( (16) \) with \( H=.35 \) (figure 3a) and linear diffusion \( (41) \). The process is Markovian. Fig. 3a was generated by taking 5,000,000 independent runs of the Ito process, each starting from \( x(0)=0 \) for \( T=10, 100, \) and 1000. The sliding window result is shown as figure 3b. In this case, the sliding windows appear to yield a scale free density \( F_s(u_s), u_s=x_s(T)/T^H_s \), from an empirical average over \( t \) that one cannot formulate theoretically, because for a nonstationary process there is no ergodic theorem. Not only are fat tails generated artificially, but we get a spurious Hurst exponent \( H_s=1/2 \) as well. This is the method that has been used to generate stylized fact’ in nearly all existing finance data analyses.

Next, we describe our study of a six year time series of Euro-Dollar exchange rates from Olsen & Associates [2]. The increments \( x(t,T)=x(t+T)-x(t)=\ln(p(t+T)/p(t)) \) are nonstationary, as is shown by the root mean square fluctuation in
increments plotted against \( t \) in figure 2a, where \( T=10 \) min. to insure that there are no autocorrelations in increments (Fig. 1). Second, note that the returns data do not scale with a Hurst exponent \( H \) or even with several different Hurst exponents over the course of a trading day (we define a trading day in a 24 hour market by resetting the clock at the same time each morning). Fig. 2b shows that the same stochastic process is repeated on different days of the week, so that we can assume a single, definite intraday stochastic process \( x(t) \) in intraday returns. In fig. 2a we see that scaling is observed at best within four disjoint time intervals during the day, and even then with four different Hurst exponents (\( H<1/2 \) in three of the intervals, \( H>1/2 \) in the other). That is, the intraday stochastic process \( x(t) \) generally does not scale and will exhibit a complicated time dependence in the variance \( \langle x^2(t) \rangle \).

Within the three windows where a data collapse \( F(u)=t^H f(x,t) \) is weakly but inadequately indicated, we see that the scaling function \( F(u) \) has no fat tails, is instead approximately exponential (figure 4a). If we apply the method of sliding windows to the finance time series within the interval I shown in fig. 2a, then we get figure 4b, which has artificially generated fat tails and also a spurious Hurst exponent \( H_s=1/2 \), just as with our numerical simulation using time series generated via the exponential density to generate a Markov time series (fig. 3a,b). This shows how sliding windows can generate artificial fat tails and spurious Hurst exponents of 1/2 in data analysis. That is, the use of sliding windows generates ‘spurious stylized facts’ when the increments are nonstationary. This observation has far reaching consequences for the analysis of random time series, whether in physics, economics/finance, and biology.
Using the short time approximation $T \ll t$, where $t$ ranges from opening to closing time over a day, we obtain from (27) the mean square fluctuation

$$\langle x^2(t,T) \rangle \approx D(x,t)T = t^{2H-1}D(u)T. \quad (50).$$

With uncorrelated nonstationary increments, in a scaling region we have more generally from (34) that

$$\langle x^2(t,T) \rangle = \langle (x(t+T)-x(t))^2 \rangle = \langle x^2(1) \rangle [(t+T)^{2H} - t^{2H}] \quad (51)$$

independent of the details of the diffusion coefficient $D(x,t)$. In most existing data analyses we generally have $T/t \ll 1$ when sliding windows are applied to the increments $x(T,t)$, yielding

$$\langle x^2(t,T) \rangle \approx \langle x^2(1) \rangle 2Ht^{2H-1}T. \quad (52)$$

Sliding windows then average empirically over $t$,

$$\langle x^2(t,T) \rangle_s \approx \langle x^2(1) \rangle 2H \langle t^{2H-1} \rangle_s T \quad (53)$$

yielding $\langle x^2(t,T) \rangle_s \approx T^{2H_s}$ with $2H_s=1$. Sliding window Hurst exponents $H_s=1/2$ have been reported often enough in the literature [27], but without any correct explanation how they arise from models where increments are uncorrelated with $H\neq 1/2$. That $H_s=1/2$ is a consequence of using sliding windows was first reported by Galluccio et al [26] in 1997 in a paper that we did not appreciate at all until we rediscovered the implications of nonstationary increments for ourselves. In 1996 there was no theory available as guide.
Our exponent sliding window $H_s$ plays the same role for scaling martingales and fBm as does the Joseph exponent $J$: when there is scaling with $H \neq 1/2$ and with no increment autocorrelations then $H \neq H_s = 1/2$, whereas for stationary increments with nonlinear variance that scales with $H$ then $H = H_s$. One need not use R/S analysis [6,28] to look for long time correlations, one need only check the mean square fluctuation $<x^2(t,T)>$ for lack of $t$-dependence, for stationary increments.

9. Are cotton returns fat, or simply nonstationary?

Finally, consider figure 2 in Mandelbrot [29], where fat tails with infinite variance were deduced for cotton returns. He plots what he calls a 2\textsuperscript{nd} moment, but is actually a mean square fluctuation analogous to the mean square fluctuation in our fig. 2a (see also our eqn. (38)). In our notation, the exact quantity analyzed is for a single long time series starting with time $t_o$ and running through time $t$ is

$$<x^2(s,T)>_{t-avg} = \frac{1}{t-t_o} \sum_{s=t_o}^{t} x^2(s,T) \tag{54}$$

with $T$ fixed at 1 day by using a sliding window. For either a stationary process or for a nonstationary process with finite increments and finite variance this quantity would be expected to ‘converge’ to a constant in probability.

Mandelbrot correctly observed the quantity (54) is ‘badly behaved’: it doesn’t ‘converge’. He then assumes without proof that the cause of the wild fluctuations is Levy-like fat tails (in a Levy density the variance is strictly infinite) because he assumed without evidence that the underlying time series is stationary. In fact, no direct evidence either for stationarity or fat tails was presented. Here, in contrast, is how we interpret his figure 2.
Markets are nonstationary, are very far from statistical equilibrium, and in that case the assumption about the of ergodicity for the empirical time average in eqn. (38) fails. The mean square fluctuation in (54) will not ‘converge’ but will fluctuate radically if the increments are nonstationary. The ‘bad behavior’ observed by Mandelbrot has nothing to do with fat tails and is instead direct evidence for nonstationarity of the increments. His figure 2 reminds us of the daily uneveness exhibited by noise traders’ behavior in our fig. 2a. We now explain the basis for our assertion?

For the case of FX data, consider the ensemble average over different trading days. This yields the quantity $<x^2(t,T)>$ of our fig. 2a. Next, sum this over different times of day, $t-t_o \leq 24$ hrs., as in (54)) to obtain

$$
\langle \langle x^2(s,T) \rangle \rangle_{t-\text{avg}} = \frac{1}{t-t_o} \sum_{s=t_o}^t \langle x^2(s,T) \rangle. \quad (55)
$$

As $t$ is increased, according to fig. 2a this quantity should fluctuate wildly due to nonstationarity of the increments. If we would take the quantity (54), without the ensemble average over different trading days, then the fluctuations will be more wild, not less. Mandelbrot’s cotton price fluctuations shown as his fig. 2 are due to nonstationary increments, not fat tails. The cotton variance $<x^2(t)>$ is both finite and nonlinear in $t$, because the increments are nonstationary,

$$
\langle x^2(t,T) \rangle = \langle x^2(t+T) \rangle - \langle x^2(t) \rangle, \quad (56)
$$

where the right hand side depends on $t$ and is simply the difference in the variance at two different times. Were the variance linear in $t$, then Mandelbrot’s fig. 2 would be
constant ‘in probability’, not wildly fluctuating and ‘nonconvergent’.

Instead of addition of variances, for nonstationary increments we have

\[ \sigma^2(t + T) = \sigma^2(t) + \langle x^2(t, T) \rangle, \quad (57) \]

Whereas for stationary increments one obtains

\[ \sigma^2(t + T) = \sigma^2(t) + \sigma^2(T). \quad (58) \]

These rules are not like the combination rules for either the central limit theorem or for aggregating Levy processes.

For cotton returns, the natural time scale for a correct data analysis may be one year, with nonstationarity of increments reflecting unevenness of trading during the course of a year. One could only check this speculation by reanalyzing the data used in [29]. Such ‘seasonal variations’ as are exhibited in Mandelbrot’s fig. 2 and our fig. 2a cannot be smoothed without masking the essence of the underlying market dynamics. It would be of interest to check cotton market returns for uncorrelated increments, i.e., to check for a martingale, where the diffusion coefficient (as is explained above) would then describe the unevenness in the volatility of trading (the nonstationarity of the increments) over the time scale of a year. But a reliable cotton market analysis is even more difficult than FX because cotton price statistics are much more sparse, and will yield far more scatter in histograms than do FX market statistics. In the latter case we do not really get adequate daily returns histograms from 6 years of trading taken at 10 min. intervals. We would expect agricultural commodities in general to exhibit nonstationary increments with nonlinear variance, reflecting underlying martingale dynamics.
Instead of asking ‘is cotton fat?’ it would have been better to ask ‘is cotton a martingale?’ but neither question can be answered by using the sliding window technique implicit in eqn. (54).

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Figure Captions

Fig. 1. Normalized autocorrelations in increments $A_{T}(t_1,t_2)=\langle x(t_1,T)x(t_2,T)\rangle / \left(\langle x^2(t_1)\rangle \langle x^2(t_2)\rangle \right)^{1/2}$ for two
nonoverlapping time intervals \([t_{1},t_{1}+T], [t_{2},t_{2}+T]\) decay rapidly toward zero for \(T \geq 10\) min. of trading.

Fig. 2(a). The root mean square fluctuation \(<x^2(t,T)>^{1/2}\) of the daily Euro-Dollar exchange rate is plotted against time of day \(t\), with \(T=10\) min. to insure that autocorrelations in increments have died out (fig. 3).
Fig. 2(b) We observe that the same intraday stochastic process occurs during each trading day. Both of the plots (a) and (b) would be flat were the increments $x(t,T)$ stationary. Instead, the rms fluctuation of $x(t,T)$ varies by a factor of 3.
each day as \( t \) is varied, exhibiting strongly nonstationary increments. In (a) that we find scaling with \( H \) at best in the four disjoint colored regions, and with different values of \( H \) in each region.

![Graph](image)

Fig. 3(a). The scaling function \( F(u) \) is calculated from a simulated time series generated via the exponential model, \( D(u) = 1 + \text{abs}(u) \) with \( H = .35 \). 5,000,000 independent runs of the exponential stochastic process were used.
Fig. 3(b) The ‘sliding window scaling function’ $F_S(u_s)$, $u_s=x_s(T)/T^{H_S}$ was calculated for the same simulated data. Note that $F_S$ has fat tails whereas $F$ does not, and that $H_S=1/2$ appears contradicting the fact that $H=.35$ was used to generate the time series. That is, sliding windows produce two significantly spurious results.
Fig. 4(a). Our scaling analysis uses the small window I shown in fig. 4a. We plot the scaling function $F(u)$ for $H=.35$ with $10 \text{ min.} \leq T \leq 160 \text{ min.}$ Note that $F(u)$ is slightly asymmetric and is approximately exponential, showing that the variance is finite.
Fig. 4(b) The ‘sliding interval scaling function’ \( F_s(u_s) \), \( u_s=x_s(T)/T^{H_s} \), is constructed empirically from the same interval I for \( T=10, 20, \) and 40 min. Note that fat tails have been generated spuriously by the sliding windows, and that a spurious Hurst exponent \( H_s=1/2 \) has been generated as well, just as in the simulation data shown as fig. 3a,b.