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# Preference-based Cooperation in a Prisoner's Dilemma Game

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## Abstract

This paper studies the possibility of whole population cooperation based on players' preferences. Consider the following infinitely repeated game, similar to Ghosh and Ray (1996). At each stage, uncountable numbers of players are randomly matched without information about their partners' past actions and play a prisoner's dilemma game. The players have the option to continue their relationship, and they all have the same discount factor. Also, they have two possible types: high ability player ( $H$ ) or low ability player ( $L$ ).  $H$  can produce better outcomes for its partner as well as for itself than  $L$  can. I look for an equilibrium that is robust against both pair-wise deviation and individual deviation and call such equilibrium a social equilibrium. In this setting, long-term cooperative behavior among the whole population can take place in a social equilibrium because of the players' preferences for their partners' types. In addition, a folk theorem of this model is proposed.

*Journal of Economic Literature Classification Number:* C72, C78

*Keywords:* Folk theorem, Random-matching, Social equilibrium, Type-based payoffs

## 1 Introduction

The motivation of the present paper comes from studies in the area of Folk Theorem. Classical literature in folk theorem, developed by Fudenberg and Maskin (1986), Kandori (1992), and Ellison (1994), showed that a long-term cooperative relationship

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in a prisoner's dilemma is possible without any legal enforcement, assuming that players' past actions affect their future payoffs. Based on a different assumption that players' past actions might not necessarily affect their future payoffs because they can change their partners in a large population, Ghosh and Ray (1996), hereinafter referred to as GR, maintained that a long-term cooperative relationship is still possible according to the structure of their model.

However, GR showed a long-term cooperative relationship among a partial population. In GR's model, there are two types of players; myopic players who have a zero discount factor and non-myopic players who have a positive discount factor. Here, the myopic players will not play any cooperative action because they do not concern about their future, and thus such a cooperative action is strictly dominated by a non-cooperative action. Then, since players can cooperate only with non-myopic players, the matches with non-myopic players are endowed with a *scarcity value*. This scarcity value is used to sustain cooperation among the non-myopic players. As a result, GR's model can show a long-term cooperative relationship only when there exist a significantly large proportion of the myopic players because the effectiveness of the scarcity value depends on this proportion of the myopic players. Therefore, GR's model can be considered as a partial population cooperation model. As a follow-up of GR, the present study is motivated to seek a possibility of whole population cooperation in a prisoner's dilemma game assuming that players' past actions might not affect their future payoffs.

In this study, the whole population cooperation takes place based on two assumptions. First, every player is assumed to be either a high-ability player (H-player) or a low-ability player (L-player) according to her production ability. An H-player is defined as a player who can produce better outcomes for her partner as well as for herself than an L-player. Second, players in a common pair have the option to continue their relationships if they both wish. In this setting, I look for a long-term cooperative behavior that is robust against both pair-wise deviation and individual deviation as GR intended in their study.

The present study shows that such a cooperative behavior can happen in equilibrium because of players' preferences for their partners' types. An H-player wants to match and play only with another H-player because a high-ability partner produces better outcomes than a low-ability partner. So, when an H-player meets an L-player, the H-player would break the relationship with the L-player in order to increase the possibility to meet another H-player. Thus, an H-player would not play any cooperative action with an L-player. Since an L-player is aware of this H-players' intention, she realizes that she can only cooperate with another L-player. Consequently, two kinds of matches, the H-H match and the L-L match, are endowed with a scarcity value. Players can use this scarcity value to sustain their cooperative relationships. Therefore, the result shows that in equilibrium a long-term cooperative relationship among the whole population is possible based on players' preferences for their partners. In addition, when the players are sufficiently patient, they play the maximal

cooperation level in the proper matches, the H-H matches and the L-L matches. This result is proposed as a folk theorem of this model.

Datta (1996) and Kranton (1996) also studied a possibility of cooperation in settings similar to the present model, repeated prisoner's dilemma games with random matching. They showed that cooperative behavior is possible by means of raising cooperation levels gradually, i.e. *building trust*. However, these building trust equilibria are not immune against pair-wise deviation as indicated by GR<sup>1</sup> (see also Furusawa and Kawakami, 2006 and Fujiwara-Greve and Okuno-Fujiwara, 2006). On the other hand, in the present model, right after the players find their proper matches, they play the highest cooperative actions out of all actions that are robust against individual deviation. Therefore, the equilibria in the current model are immune against pair-wise deviation.

Recently, Fujiwara-Greve (2002) studied a similar issue; the possibility of cooperation in a prisoner's dilemma game with random matching. However, in contrast to the *complete random matching process* in which the probability to meet a new partner is one, she considered an *incomplete random matching process* in which the probability to meet a new partner is less than one. She showed that if the probability to meet a new partner is sufficiently low, then players can play the highest cooperative action from the beginning of their relationships, and thus a folk theorem holds in her model. She explained that under the incomplete random matching process, each match is endowed with a scarcity value because if a player loses her current partner, then she might not meet a new partner at the next period. As a result, players in her model can use this scarcity value to sustain a long-term cooperative relationship even when personalized punishments are not feasible. Therefore, in her model, the scarcity value is exogenously determined by the assumption about the incomplete random matching process. In the present model, on the other hand, a scarcity value is not given by any assumption because all the players, who have incentives to cooperate, can meet new partners at any time. The scarcity value, however, is endogenously generated by the players' preferences on their partners' types, and this scarcity value is used by the players when they sustain a cooperative relationship with their partners<sup>2</sup>.

In the present model, one of the critical assumptions is that the players' types depend on their payoff systems. Watson (1999) and (2002) adopted a similar heterogeneity assumption about the players' types and showed that cooperation levels in a prisoner's dilemma game increase gradually. In his models, however, the payoffs to each player do not depend on their partners' types, and heterogeneity in payoff systems causes the players to have different degrees of preferences on cooperation as

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<sup>1</sup>Kranton (1996) also extended her model by introducing myopic players into the model, and found a result similar to GR. That is, the result in her extended model is robust against pair-wise deviation as the result in GR.

<sup>2</sup>To see different approaches on this issue, the possibility of cooperation in a prisoner's dilemma game with random matching, please refer to Boone, Brabander, Carree, Jong, Olff, and Witteloostuijn (2002), Bose (1996), Brosig (2002), Outkin (2003), and Yang, Yue, and Yu (2007).

the heterogeneity assumption of GR whose model featured the myopic players, who have no incentive to cooperate, and the non-myopic players, who have an incentive to cooperate. Therefore, the heterogeneity in Watson (1999) and (2002) can be considered as an assumption similar to the heterogeneity assumption in GR (see also Rauch and Watson, 2003). In the current model, on the other hand, the payoffs to each player depend on their partners' types, and this heterogeneity in payoff systems makes the players have an incentive to cooperate with specific types, even when all the players have the same degree of preferences on cooperation. As a result, a long-term cooperative relationship among the whole population is possible based on this heterogeneity assumption.

This paper is organized as follows. Section 2 is devoted to detailed description of the model. Section 3 introduces the concept of a social equilibrium. Section 4 presents the results of this study, including the folk theorem of this model. Section 5 concludes

## 2 The Model

The following setting of the model comes from GR. A continuum of players are randomly matched in pairs and bilaterally play an infinitely repeated stage game with an option to break up their relationships. Each stage of the game consists of two substages. At the first substage, players in a common pair play a prisoner's dilemma game with an action set  $[0, \tilde{a}] \subset \mathbb{R}$ . At the second substage, after watching the actions chosen before, the players decide whether to break up their relationships. Only when both players in a common pair decide to maintain their relationship, can they play the stage game between themselves at the next stage. If one of the players in a common pair breaks up the relationship, then both in the pair go into *the pool of unmatched players* and would be randomly matched with other players in the pool. At the next stage, all players bilaterally repeat this stage game.

The present model introduces new features into the setting of GR. All players have the same discount factor  $\delta$ , but they have their own types. Each player is either an H-player or an L-player. An H-player has higher abilities to produce an outcome than an L-player does. Based on this ability difference, the present model reflects the situation in which a partner of an H-player can benefit from the high ability of the H-player by sharing the produced outcome. Therefore, it is assumed that a player's payoff depends on her partner's type as well as on her own type and also depends on her partner's and her actions so that when other things being equal, **a player gets a better payoff when she cooperates with an H-player than when she cooperates with an L-player.**

The payoff functions of the players are as follows. For any  $I, J \in \{H, L\}$ , the function  $\Pi_{IJ} : [0, \tilde{a}]^2 \rightarrow \mathbb{R}$  denotes a payoff function of  $I$ -type when she works with  $J$ -type. For example, let  $a, a' \in [0, \tilde{a}]$ , then  $\Pi_{HL}(a, a')$  denotes the payoff to an H-player when she works with an L-player under her action  $a$  and her partner's

action  $a'$ . Here, the players' actions  $a$  and  $a'$  can be referred to as *cooperation levels*. Then, in order to reflect the prisoner's dilemma setting, it is assumed that for each  $a, a' \in [0, \tilde{a}]$ , if  $a > 0$ , then  $\Pi_{IJ}(0, a') > \Pi_{IJ}(a, a')$ . In addition, the payoff under zero actions,  $\Pi_{IJ}(0, 0)$ , is normalized to zero.

In this study, three assumptions about the payoff functions from GR's model are adopted and adapted. First, the payoff function  $\Pi_{IJ}$  is assumed to be continuous, and the function  $\Pi_{JJ}(a, a)$  is assumed to be strictly increasing in  $a$ . This assumption is used for the sake of simplicity. Second, there exists  $a \in (0, \tilde{a}]$  such that  $\Pi_{JJ}(a, a) > (1 - \delta)\Pi_{JJ}(0, a)$ . Third, given any  $a_L \in [0, \tilde{a}]$ , there exists  $a \in (0, \tilde{a}]$  such that  $\pi\Pi_{HH}(a, a) + (1 - \pi)\Pi_{HL}(a, a_L) > (1 - \pi)\Pi_{HL}(0, a_L)$  where  $\pi$  is the proportion of H-players in the pool of unmatched players. If the second or the third assumption does not hold, then players might not have any incentive to play a positive action. Therefore, the latter two assumptions are used to exclude a trivial case in which players have no incentive to cooperate with their partners and prefer to play zero actions.

Regarding information, a player has limited information about types and actions. A player is informed only of her own type. However, if her partner plays a positive action, she can figure out her partner's type by comparing the outcomes drawn from her action and her partner's action. This is because, other things being equal, the cooperative action performed by a high ability partner brings out a better outcome than the action performed by a low ability partner. Note that a player cannot figure out her partner's type if her partner plays a zero action because of the normalization of the payoffs. In addition, a player knows only her own actions and her partners' actions from the beginning, but they do not know the actions taken by others. A player's *personal history* is defined as the record of her type, the types of her partners who have played positive actions, and all the actions taken by her partners and her from the beginning. Therefore, a pure strategy of a player is a possible mapping from her personal histories either to the set of the actions  $[0, \tilde{a}]$  for the first substages or to the set of the breakup decisions for the second substages.

### 3 Social Equilibrium

In this study, our interest is restricted to *social norms* and *steady states* like in the study of GR. A social norm is a profile of pure strategies such that players of the same type use the same pure strategy. A state is steady if the proportion of H-players in the pool of unmatched players,  $\pi$ , is constant over time<sup>3</sup>. Moreover, our study focuses

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<sup>3</sup>For information about the feasibility of a constant  $\pi$ , please refer to GR. Here, another interpretation of a constant  $\pi$  is presented. If we assume that the relationship will be exogenously broken up with a probability  $\theta > 0$  regardless of players' breakup decisions, then we can easily show that a constant  $\pi$  is feasible. In addition, given any  $\pi > 0$  and any positive number  $\varepsilon > 0$ , we can find an exogenous breakup probability  $\theta > 0$  such that  $\varepsilon > \theta$  and  $\theta$  makes  $\pi$  a constant proportion of H-players in the pool over time. Therefore, the steady state in which  $\pi > 0$  and  $\theta = 0$  can be

on the cooperation possibility based on players' preferences for the high ability of an H-player. So, we rule out the cases in which a player prefers betraying an H-player partner rather than cooperating with the H-player partner because of a possible huge payoff when she betrays the H-player partner. In addition, our equilibrium is required to satisfy two criteria: "Individual incentive constraint" and "Bilateral rationality," which were proposed by GR. These two criteria require an equilibrium to be proof against *individual deviation* and *pair-wise deviation*, respectively<sup>4</sup>.

These two criteria are applied to five possible phases. First, these are applied to the phase in which two H-players are matched into a pair and they are aware of their partners' types. In this phase, H-players solve the following optimization problem; given  $0 \leq x_H \leq \delta \max_{a \in [0, \tilde{a}]} \left\{ \frac{\Pi_{HH}(a, a)}{1 - \delta} - \Pi_{HH}(0, a) \right\}$ ,

$$\max_{a \in [0, \tilde{a}]} \frac{\Pi_{HH}(a, a)}{1 - \delta} \equiv V_H^F(x_H) \quad (1)$$

$$s.t. \frac{\Pi_{HH}(a, a)}{1 - \delta} \geq \Pi_{HH}(0, a) + \delta x_H \quad (2)$$

where  $x_H$  denotes a present value to an H-player when she is in the pool of unmatched players. Given a present value to an H-player, this optimization problem yields the highest possible cooperation level, which, therefore, satisfies bilateral rationality, among all the cooperation levels that satisfy individual incentive constraint.

Second, based on the optimization problem above, the two criteria are applied to the phase for an H-player when she is newly matched and thus she does not know her partner's type; given  $x_H$  and  $a_L^S \in [0, \tilde{a}]$ ,

$$\max_{a \in [0, \tilde{a}]} \pi \{ \Pi_{HH}(a, a) + \delta V_H^F(x_H) \} + (1 - \pi) \{ \Pi_{HL}(a, a_L^S) + \delta x_H \} \equiv V_H^S(x_H, a_L^S) \quad (3)$$

$$s.t. \pi \{ \Pi_{HH}(a, a) + \delta V_H^F(x_H) \} + (1 - \pi) \{ \Pi_{HL}(a, a_L^S) + \delta x_H \} \geq \pi \{ \Pi_{HH}(0, a) + \delta x_H \} + (1 - \pi) \{ \Pi_{HL}(0, a_L^S) + \delta x_H \} \quad (4)$$

where  $a_L^S$  denotes an action of an L-player when she is newly matched.

Similarly, the two criteria are applied to the phases for L-players. Third, two L-players who are certain that their partners are L-players solve the following problem; given  $0 \leq x_L \leq \delta \max_{a \in [0, \tilde{a}]} \left\{ \frac{\Pi_{LL}(a, a)}{1 - \delta} - \Pi_{LL}(0, a) \right\}$ ,

$$\max_{a \in [0, \tilde{a}]} \frac{\Pi_{LL}(a, a)}{1 - \delta} \equiv V_L^F(x_L) \quad (5)$$

$$s.t. \frac{\Pi_{LL}(a, a)}{1 - \delta} \geq \Pi_{LL}(0, a) + \delta x_L \quad (6)$$

interpreted as the limit of the exogenous breakup cases.

<sup>4</sup>In GR, *individual incentive constraint* is defined as a social norm under which, given that other players follow the norm, no player has an incentive to deviate from the norm. In addition, *bilateral rationality* is defined as a social norm under which, given that other players follow the norm, no matched pair of players who have followed the norm can improve their payoffs by making a joint change from the norm. For more information about these criteria, please refer to GR.

where  $x_L$  denotes a present value to an L-player when she is in the pool of unmatched players.

Fourth, an L-player who is newly matched solves the following problem; given  $x_L$  and  $a_H^S \in [0, \tilde{a}]$ ,

$$\max_{a \in [0, \tilde{a}]} \pi \{ \Pi_{LH}(a, a_H^S) + \delta x_L \} + (1 - \pi) \{ \Pi_{LL}(a, a) + \delta V_L^F(x_L) \} \equiv V_L^S(x_L, a_H^S) \quad (7)$$

$$\begin{aligned} s.t. \quad & \pi \{ \Pi_{LH}(a, a_H^S) + \delta x_L \} + (1 - \pi) \{ \Pi_{LL}(a, a) + \delta V_L^F(x_L) \} \\ & \geq \pi \{ \Pi_{LH}(0, a_H^S) + \delta x_L \} + (1 - \pi) \{ \Pi_{LL}(0, a) + \delta x_L \} \end{aligned} \quad (8)$$

where  $a_H^S$  denotes an action of an H-player when she is newly matched.

Finally, the two criteria are applied to the phase in which an H-player and an L-player are matched into a pair and they are aware of their partners' types. In equilibrium, players could have long-term cooperative relationships in the previous four phases only if they cannot achieve cooperation in this phase. So, given present values in the pool of unmatched players, we need to show that every cooperation level that satisfies individual incentive constraint does not give an H-player or an L-player a greater payoff than their present values in the pool. This condition is formalized at the condition 9 in Definition 1.

Now, we are ready to define our equilibrium, which we call a ‘‘Social Equilibrium.’’ This social equilibrium is adopted and adapted from GR.

**Definition 1** *A social equilibrium is a collection of actions  $(a_H^F, a_H^S, a_L^F, a_L^S)$  and payoffs  $(V_H^F, V_H^S, V_L^F, V_L^S)$  such that*

1. given  $V_H^S, a_H^F$  solves (1) subject to (2);
2. given  $V_H^S$  and  $a_L^S, a_H^S$  solves (3) subject to (4);
3. given  $V_L^S, a_L^F$  solves (5) subject to (6);
4. given  $V_L^S$  and  $a_H^S, a_L^S$  solves (7) subject to (8);
5. the payoff  $V_H^F$  equals the maximum value  $V_H^F(V_H^S)$ ;
6. the payoff  $V_H^S$  equals the maximum value  $V_H^S(V_H^S, a_L^S)$ ;
7. the payoff  $V_L^F$  equals the maximum value  $V_L^F(V_L^S)$ ;
8. the payoff  $V_L^S$  equals the maximum value  $V_L^S(V_L^S, a_H^S)$ ;

and for all  $a', a'' \in [0, \tilde{a}]$ ,

$$9. \text{ if } \frac{\Pi_{HL}(a', a'')}{1 - \delta} \geq \Pi_{HL}(0, a'') + \delta V_H^S, \text{ then } V_H^S \geq \frac{\Pi_{HL}(a', a'')}{1 - \delta} \text{ or} \quad (9)$$

$$\text{if } \frac{\Pi_{LH}(a'', a')}{1 - \delta} \geq \Pi_{LH}(0, a') + \delta V_L^S, \text{ then } V_L^S \geq \frac{\Pi_{LH}(a'', a')}{1 - \delta}. \quad (10)$$

## 4 Results

In this study, the results are similar to GR's in respect to the factors that can influence the level of cooperation in equilibrium. In both studies, cooperation is enhanced when players find their proper matches or when the discount factor goes up. However, while GR's results apply to partial population only, the following results show that a long-term cooperative relationship among the whole population is possible. The first result shows that there exists a social equilibrium. Like in GR, special assumptions on payoff functions are used for the existence of the equilibrium. Note that only Proposition 1 uses these special assumptions.

**Assumption 1.** For each  $J \in \{H, L\}$ , the payoff function  $\Pi_{JJ}(a, a)$  is strictly concave, the function  $\Pi_{JJ}(a, 0)$  is concave, and the function  $\Pi_{JJ}(0, a)$  is convex<sup>5</sup>.

**Assumption 2.** The left-hand partial derivatives of  $\Pi_{HL}(a_1, a_2)$  and  $\Pi_{LH}(a_1, a_2)$  with respect to the first argument  $a_1$  are continuous in the second argument  $a_2$ .

Assumptions 1 and 2 guarantee that the optimization functions  $V_H^S(\cdot, \cdot)$  and  $V_L^S(\cdot, \cdot)$  and the optimizers in these functions are continuous in their arguments. This property of continuity serves as a stepping-stone for the existence of a fixed point in the optimization problems above.

**Assumption 3.** For each  $IJ \in \{HL, LH\}$ , the payoff function  $\Pi_{IJ}(a_1, a_2)$  is concave in  $a_1$  and convex in  $a_2$ , and for  $a_1 > 0$ ,  $\Pi_{IJ}(0, a_2) - \Pi_{IJ}(a_1, a_2) \leq \Pi_{IJ}(0, a'_2) - \Pi_{IJ}(a_1, a'_2)$  if  $a_2 > a'_2$ .

Assumption 3 implies that in the different-type matches, *i.e.* the H-L matches, the payoff  $\Pi_{IJ}(a_1, a_2)$  decreases with her own action  $a_1$  at an increasing rate and increases with her partner's action  $a_2$  at an increasing rate. In addition, when  $a_1$  is positive, the payoff difference  $\Pi_{IJ}(0, a_2) - \Pi_{IJ}(a_1, a_2)$  decreases in  $a_2$ . This assumption is used for the sake of simplicity.

Under Assumptions 1, 2, and 3, Proposition 1 presents a sufficient condition for the existence of a social equilibrium. Like in GR, the notations below are used to simplify the sufficient condition. First, denote by  $a_H^1$  and  $a_L^1$  the maximizers of the functions  $\Pi_{HH}(a, a) - (1 - \delta)\Pi_{HH}(0, a)$  and  $\Pi_{LL}(a, a) - (1 - \delta)\Pi_{LL}(0, a)$ , respectively. Next, let  $a_H^2$  and  $a_L^2$  denote the maximum values of  $a$  s.t.

$$\begin{aligned} & \pi\{\Pi_{HH}(0, a) - \Pi_{HH}(a, a)\} + (1 - \pi)\{\Pi_{HL}(0, \tilde{a}) - \Pi_{HL}(a, \tilde{a})\} \\ \leq & \pi\{\Pi_{HH}(0, a_H^1) - \Pi_{HH}(a_H^1, a_H^1)\} \text{ and} \\ & \pi\{\Pi_{LH}(0, \tilde{a}) - \Pi_{LH}(a, \tilde{a})\} + (1 - \pi)\{\Pi_{LL}(0, a) - \Pi_{LL}(a, a)\} \\ \leq & (1 - \pi)\{\Pi_{LL}(0, a_L^1) - \Pi_{LL}(a_L^1, a_L^1)\}, \text{ respectively.} \end{aligned}$$

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<sup>5</sup>For the information about this assumption, please refer to GR.

Finally, let  $a_H^3$  and  $a_L^3$  denote the maximizers of the strictly concave functions  $\pi\Pi_{HH}(a, a) + (1 - \pi)\Pi_{HL}(a, \tilde{a})$  and  $\pi\Pi_{LH}(a, \tilde{a}) + (1 - \pi)\Pi_{LL}(a, a)$ , respectively.

Here is a sufficient condition<sup>6</sup> for the existence of a fixed point in the aforementioned optimization problems.

**Condition E** If  $a_H^3 \leq a_H^2$ , then

$$\begin{aligned} & \pi\Pi_{HH}(a_H^3, a_H^3) + (1 - \pi)\Pi_{HL}(a_H^3, \tilde{a}) \\ & \leq \left(\pi + \frac{1}{\delta}\right)\Pi_{HH}(a_H^1, a_H^1) + \left(1 - \pi - \frac{1}{\delta}\right)\Pi_{HH}(0, a_H^1) \}. \end{aligned} \quad (11)$$

If  $a_H^3 > a_H^2$ , then

$$\delta\pi\Pi_{HH}(0, a_H^2) + \delta(1 - \pi)\Pi_{HL}(0, \tilde{a}) \leq \Pi_{HH}(a_H^1, a_H^1) - (1 - \delta)\Pi_{HH}(0, a_H^1). \quad (12)$$

If  $a_L^3 \leq a_L^2$ , then

$$\begin{aligned} & \pi\Pi_{LH}(a_L^3, \tilde{a}) + (1 - \pi)\Pi_{LL}(a_L^3, a_L^3) \\ & \leq \left(1 - \pi + \frac{1}{\delta}\right)\Pi_{LL}(a_L^1, a_L^1) + \left(\pi - \frac{1}{\delta}\right)\Pi_{LL}(0, a_L^1) \}. \end{aligned} \quad (13)$$

If  $a_L^3 > a_L^2$ , then

$$\delta\pi\Pi_{LH}(0, \tilde{a}) + \delta(1 - \pi)\Pi_{LL}(0, a_L^2) \leq \Pi_{LL}(a_L^1, a_L^1) - (1 - \delta)\Pi_{LL}(0, a_L^1). \quad (14)$$

To sustain a social equilibrium, a fixed point in the optimization problems above has to satisfy the condition 9 in Definition 1 in which one of the types has no incentive to cooperate with the other type. If the ability difference between an H-player and an L-player is *wide enough*, then the H-player would have no incentive to cooperate with the L-player, and therefore, the fixed point would satisfy the condition 9 in Definition 1. Definition 2 below provides the level of the ability difference in which an H-player has no incentive to cooperate with an L-player.

**Definition 2** Define  $a_H^4$  as the value of  $a$  such that  $(1 - \delta\pi)\Pi_{LH}(0, a) = \delta(1 - \pi)\Pi_{LL}(a_L^1, a_L^1)$ . The ability difference between an H-player and an L-player is said to be **wide enough** if  $\delta\pi\Pi_{HH}(a_H^1, a_H^1) \geq (1 - \delta + \delta\pi)\Pi_{HL}(a_H^4, \tilde{a})$  whenever  $a_H^4$  exists.

**Proposition 1** Under Assumptions 1, 2, and 3, a social equilibrium exists if Condition E holds and the ability difference between an H-player and an L-player is wide enough.

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<sup>6</sup>For an intuitive description of this condition, please refer to GR.

**Proof.** See Appendix. ■

Examples with specific payoff functions can be found in GR. The payoff functions from GR, however, have to be adapted for the L-players. In GR, the myopic type, who has the zero discount factor, has no incentive to play any positive action. The zero action by the myopic type lowers a present value to the non-myopic type in the pool of unmatched players, and this lowered present value in turn makes an ongoing cooperative relationship more valuable. As a result, although an one-period payoff from betrayal is high, the non-myopic type players can sustain a long-term cooperative relationship among themselves. In the present model, on the other hand, when H-players are newly matched with L-players, they play positive cooperative actions  $a_H^S$ . Since the H-players' actions  $a_H^S$  significantly improve present values to L-players in the pool, if one-period payoffs to L-players when they betray other L-players are as high as those in GR, then L-players would prefer betraying their low-ability partners more than cooperating with them. Therefore, the payoff functions from GR need to be modified so that L-players can sustain long-term cooperative relationships among themselves.

The second result describes cooperation levels in each phase in equilibrium. Each type of the players faces two possible phases in which they can play different levels of cooperation. First, each type reaches the first phase right after they confirm that their partners are of the same types as themselves. Next, each type reaches the second phase right after they are newly matched, and thus in this phase, they do not know their partners' types. Proposition 2 below shows that each type plays a higher cooperative action in the former phase than in the latter phase except that she achieves the same level of cooperation when she plays full cooperative actions in both phases. According to the interpretation of GR, Proposition 2 characterizes a social equilibrium into a "testing phase" and a "cooperation phase." In the testing phase, the players are "cautious," and as a result, they have less to achieve. If they are confirmed that they are matched with the same type players as themselves, then they move into the cooperation phase where they can play at greater cooperation levels.

**Proposition 2** *In a social equilibrium,  $a_J^F \geq a_J^S$  where  $J \in \{H, L\}$  with strict inequality holding whenever  $a_J^F < \tilde{a}$ .*

**Proof.** Consider an H-player case. If  $a_H^F = \tilde{a}$ , then it is trivial. Let  $a_H^F < \tilde{a}$  in equilibrium. By way of contradiction, suppose that  $a_H^F \leq a_H^S$ . Then, we have that  $\Pi_{HH}(0, a_H^S) + \delta V_H^S \geq \frac{\Pi_{HH}(a_H^S, a_H^S)}{1-\delta}$  by the constraint (2). Then,

$$\begin{aligned} (1-\delta)\{\Pi_{HH}(0, a_H^S) - \Pi_{HH}(a_H^S, a_H^S)\} &\geq \delta\{\Pi_{HH}(a_H^S, a_H^S) - (1-\delta)V_H^S\} \\ &\geq \delta\{\Pi_{HH}(a_H^F, a_H^F) - (1-\delta)V_H^S\} = \delta(1-\delta)(V_H^F - V_H^S) \\ &> \delta(1-\delta)(V_H^F - V_H^S) + \frac{1-\pi}{\pi}(1-\delta)\{\Pi_{HL}(a_H^S, a_L^S) - \Pi_{HL}(0, a_L^S)\} \end{aligned}$$

where the fact  $\Pi_{HL}(a_H^S, a_L^S) - \Pi_{HL}(0, a_L^S) < 0$  is used at the last inequality. This contradicts (4). Therefore, we have  $a_H^F > a_H^S$ . Similarly, we can show  $a_L^F \geq a_L^S$  with strict inequality holding whenever  $a_L^F < \tilde{a}$ . ■

The final result goes one step further from GR's. In their paper, as players become infinitely patient, the cooperation level in equilibrium approaches full cooperation once players find their proper matches. In the present model, Proposition 3 below states that *when players are sufficiently patient, they play the maximal cooperation level in equilibrium right after they check that they are matched with the same type partners as themselves*. The present study proposes Proposition 3 as a folk theorem of this model.

**Proposition 3 (Folk Theorem)** *There exists a discount factor  $\delta^* < 1$  such that for any  $\delta \in [\delta^*, 1)$ ,  $a_H^F = a_L^F = \tilde{a}$  in a social equilibrium under  $\delta$ , whenever the social equilibrium exists.*

**Proof.** By way of contradiction, suppose not. Then, for any  $\delta < 1$ , there exists  $1 > \delta' \geq \delta$  such that under  $\delta'$ , there exists a social equilibrium with  $a_H^F < \tilde{a}$  or  $a_L^F < \tilde{a}$ . First, consider the case in which for any  $\delta < 1$ , there exists  $1 > \delta' \geq \delta$  such that under  $\delta'$ , there exists a social equilibrium with  $a_H^F < \tilde{a}$ . In the social equilibrium under the discount factor  $\delta'$ , let  $V_H^S$  be a present value to an H-player in the pool of unmatched players. Then, according to the constraint (2), we have that

$$\frac{\Pi_{HH}(\tilde{a}, \tilde{a})}{1 - \delta'} < \Pi_{HH}(0, \tilde{a}) + \delta' V_H^S. \quad (15)$$

In addition, we have that

$$V_H^S \leq \frac{1}{\delta'} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta'} - \Pi_{HH}(0, a_H^1) \right\} \quad (16)$$

where  $a_H^1$  is a maximizer of  $\Pi_{HH}(a, a) - (1 - \delta)\Pi_{HH}(0, a)$ . Note that since  $\frac{1}{\delta'} \left\{ \frac{\Pi_{HH}(\tilde{a}, \tilde{a})}{1 - \delta'} - \Pi_{HH}(0, \tilde{a}) \right\} < V_H^S \leq \frac{1}{\delta'} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta'} - \Pi_{HH}(0, a_H^1) \right\}$ , we have that  $a_H^1 < \tilde{a}$ . By combining (15) with (16), we have that

$$\begin{aligned} \frac{\Pi_{HH}(\tilde{a}, \tilde{a})}{1 - \delta'} &< \Pi_{HH}(0, \tilde{a}) + \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta'} - \Pi_{HH}(0, a_H^1) \\ \iff \frac{1}{1 - \delta'} \{ \Pi_{HH}(\tilde{a}, \tilde{a}) - \Pi_{HH}(a_H^1, a_H^1) \} &< \Pi_{HH}(0, \tilde{a}) - \Pi_{HH}(0, a_H^1). \end{aligned} \quad (17)$$

However, since the inequality (17) holds for any  $\delta < 1$  and thus for any  $1 > \delta' \geq \delta$ , (17) is contradiction. Similarly, we can show that it is contradiction that for any  $\delta < 1$ , there exists  $1 > \delta' \geq \delta$  such that under  $\delta'$ , there exists a social equilibrium with  $a_L^F < \tilde{a}$ . This completes the proof. ■

Distinguished from GR's model, the present model is significant in two aspects. First, in GR, if there exists a social equilibrium, it must be unique, because one type

always prefers to play a zero action and the other type has only one best response to the zero action. In the present model, however, there could be multiple social equilibria, because players can play different levels of initial actions  $(a_H^S, a_L^S)$ . Since each type has the best response to the initial action of the other type, there could be multiple social equilibria elicited from multiple mutually best initial responses. Second, in GR, a change in  $\pi$ , the proportion of non-myopic players of unmatched players, directly influences the payoffs. An increase in  $\pi$  results in an increase in the present values when players are in the unmatched pool and also results in a non-increase in the payoffs to non-myopic players when they find non-myopic partners. In the present model, however, due to the possible existence of multiple equilibria, a change in  $\pi$ , the proportion of H-players in the pool of unmatched players, does not have a clear effect on the payoffs  $(V_H^F, V_H^S, V_L^F, V_L^S)$ . This is because the impact from a change in  $\pi$  could be diluted with the influence from a change in equilibria. For example, an increase in  $\pi$  affects the H-players' payoff  $V_H^S$  to increase, but this influence could be canceled out by a change in equilibria from a high value of  $V_H^S$  to a low value of it.

## 5 Conclusion

A long-term cooperative behavior that is robust to both pair-wise deviation and individual deviation is possible among the whole population in equilibrium. Regarding cooperation levels, after players play a lower cooperation in the testing phase, they move on to higher cooperation in the cooperation phase. If players are patient enough, both H-players and L-players can achieve full cooperation once they find their proper matches. Therefore, based on players' preferences for their partners' types, a long-term cooperative relationship among the whole population is possible in equilibrium.

## Appendix

**Proof of Proposition 1.** Consider (1) subject to (2). Note that  $V_H^F(x_H)$  is continuous and non-increasing in  $x_H$ . Also, we have that  $V_H^F(x_H) - x_H > 0$  because of (2). Given  $x_H \in [0, \frac{1}{\delta} \{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1-\delta} - \Pi_{HH}(0, a_H^1) \}]$  and  $a_L^S \in [0, \tilde{a}]$ , define

$$\begin{aligned} a_H^S(x_H, a_L^S) &\in \arg \max_{a \in [0, \tilde{a}]} \pi \{ \Pi_{HH}(a, a) + \delta V_H^F(x_H) \} + (1 - \pi) \{ \Pi_{HL}(a, a_L^S) + \delta x_H \} \\ &\quad s.t. \pi \{ \Pi_{HH}(0, a) + \delta x_H \} + (1 - \pi) \{ \Pi_{HL}(0, a_L^S) + \delta x_H \} \\ &\leq \pi \{ \Pi_{HH}(a, a) + \delta V_H^F(x_H) \} + (1 - \pi) \{ \Pi_{HL}(a, a_L^S) + \delta x_H \}. \end{aligned}$$

Let  $a_H^2(x_H, a_L^S)$  be the maximum value of  $a$  such that

$$\begin{aligned}
& \pi\{\Pi_{HH}(0, a) + \delta x_H\} + (1 - \pi)\{\Pi_{HL}(0, a_L^S) + \delta x_H\} \\
& \leq \pi\{\Pi_{HH}(a, a) + \delta V_H^F(x_H)\} + (1 - \pi)\{\Pi_{HL}(a, a_L^S) + \delta x_H\} \\
& \iff \pi\{\Pi_{HH}(0, a) - \Pi_{HH}(a, a)\} + (1 - \pi)\{\Pi_{HL}(0, a_L^S) - \Pi_{HL}(a, a_L^S)\} \\
& \leq \delta\pi\{V_H^F(x_H) - x_H\}.
\end{aligned}$$

Then,  $a_H^2(x_H, a_L^S) > 0$  since  $V_H^F(x_H) - x_H > 0$ . Also,  $a_H^2(x_H, a_L^S)$  is continuous in  $x_H$  and  $a_L^S$  because 1)  $\pi\{\Pi_{HH}(0, a) - \Pi_{HH}(a, a)\} + (1 - \pi)\{\Pi_{HL}(0, a_L^S) - \Pi_{HL}(a, a_L^S)\}$  is strictly increasing in  $a$  and continuous in  $a$  and  $a_L^S$ ; and 2)  $\delta\pi\{V_H^F(x_H) - x_H\}$  is continuous in  $x_H$ . In addition, let  $a_H^3(a_L^S)$  denote the maximizer of the strictly concave function  $\pi\Pi_{HH}(a, a) + (1 - \pi)\Pi_{HL}(a, a_L^S)$ . Then  $a_H^3(a_L^S) > 0$  because given any  $a_L^S \in [0, \tilde{a}]$ , there exists  $a > 0$  s.t.  $\pi\Pi_{HH}(a, a) + (1 - \pi)\Pi_{HL}(a, a_L^S) > (1 - \pi)\Pi_{HL}(0, a_L^S)$ . The function  $\Pi_{HL}(a_1, a_2)$  is concave in  $a_1$ , and therefore, its left-hand partial derivative with respect to  $a_1$ ,  $\frac{\partial \Pi_{HL}(a_1 - 0, a_2)}{\partial a_1}$ , is well-defined on  $(0, \tilde{a}]^2$ . According to Assumption 2,  $\frac{\partial \Pi_{HL}(a_1 - 0, a_2)}{\partial a_1}$  is continuous in  $a_2$ . Also, the function  $\Pi_{HH}(a, a)$  is strictly concave in  $a$ . Therefore,  $a_H^3(a_L^S)$  is continuous in  $a_L^S$ . Note that  $a_H^S(x_H, a_L^S) = \min\{a_H^2(x_H, a_L^S), a_H^3(a_L^S)\}$ . Since  $a_H^2(x_H, a_L^S)$  and  $a_H^3(a_L^S)$  are positive and continuous in  $x_H$  and  $a_L^S$ , so is  $a_H^S(x_H, a_L^S)$ . Define

$$\begin{aligned}
\Phi_H(x_H, a_L^S) & \equiv \max_{a \in [0, \tilde{a}]} \pi\{\Pi_{HH}(a, a) + \delta V_H^F(x_H)\} + (1 - \pi)\{\Pi_{HL}(a, a_L^S) + \delta x_H\} \\
& \text{s.t. } \pi\{\Pi_{HH}(0, a) - \Pi_{HH}(a, a)\} + (1 - \pi)\{\Pi_{HL}(0, a_L^S) - \Pi_{HL}(a, a_L^S)\} \\
& \leq \delta\pi\{V_H^F(x_H) - x_H\}.
\end{aligned}$$

Then  $\Phi_H(x_H, a_L^S) = \pi\{\Pi_{HH}(a_H^S(x_H, a_L^S), a_H^S(x_H, a_L^S)) + \delta V_H^F(x_H)\} + (1 - \pi)\{\Pi_{HL}(a_H^S(x_H, a_L^S), a_L^S) + \delta x_H\}$ , and  $\Phi_H(x_H, a_L^S)$  is continuous in  $x_H$  and  $a_L^S$ . Similarly, we can define  $a_L^S(x_L, a_H^S)$  and  $\Phi_L(x_L, a_H^S)$  for an L-player and show that  $a_L^S(x_L, a_H^S)$  and  $\Phi_L(x_L, a_H^S)$  are continuous in  $x_L$  and  $a_H^S$ .

Let

$$\begin{aligned}
\hat{V}_H^S & \equiv \max_{a \in (0, \tilde{a}]} \left\{ \frac{\Pi_{HH}(a, a)}{1 - \delta} - \Pi_{HH}(0, a) \right\} \text{ and} \\
\hat{V}_L^S & \equiv \max_{a \in (0, \tilde{a}]} \left\{ \frac{\Pi_{LL}(a, a)}{1 - \delta} - \Pi_{LL}(0, a) \right\}.
\end{aligned}$$

Then  $\hat{V}_H^S$  and  $\hat{V}_L^S$  exist and are positive because  $\Pi_{JJ}(a, a) > (1 - \delta)\Pi_{JJ}(0, a)$  for some  $a > 0$  where  $J \in \{H, L\}$ . If

$$\max_{a_L^S} \{\Phi_H(\hat{V}_H^S, a_L^S)\} \leq \hat{V}_H^S \text{ and} \tag{18}$$

$$\max_{a_H^S} \{\Phi_L(\hat{V}_L^S, a_H^S)\} \leq \hat{V}_L^S, \tag{19}$$

then by using the values  $a_H^S(x_H, a_L^S)$ ,  $a_L^S(x_L, a_H^S)$ ,  $\min\{\Phi_H(x_H, a_L^S), \hat{V}_H^S\}$ , and  $\min\{\Phi_L(x_L, a_H^S), \hat{V}_L^S\}$ , we can construct a continuous function from  $[0, \tilde{a}]^2 \times [0, \hat{V}_H^S] \times [0, \hat{V}_L^S]$  into  $[0, \tilde{a}]^2 \times [0, \hat{V}_H^S] \times [0, \hat{V}_L^S]$  such that a fixed point of the function, whose existence is guaranteed by Brouwer's Fixed Point Theorem, solves (3) subject to (4) and solves (7) subject to (8). Therefore, to complete the proof, we must check that (18) and (19) are equivalent to Condition E and also should show that if the ability difference between an H-player and an L-player is wide enough, then the fixed point satisfies the condition 9 in Definition 1.

First, check that (18) and (19) are equivalent to Condition E. Note that

$$\hat{V}_H^S = \frac{1}{\delta} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta} - \Pi_{HH}(0, a_H^1) \right\}.$$

In addition, note that  $\Phi_H(x_H, \tilde{a}) \geq \Phi_H(x_H, a_L^S)$  for every  $a_L^S \in [0, \tilde{a}]$  since  $\Pi_{HL}(0, a_2) - \Pi_{HL}(a_1, a_2) \leq \Pi_{HL}(0, a'_2) - \Pi_{HL}(a_1, a'_2)$  if  $a_2 > a'_2$ . Therefore, if  $a_H^3(\tilde{a}) \leq a_H^2(\hat{V}_H^S, \tilde{a})$ , *i.e.*  $a_H^3 \leq a_H^2$ , then

$$\begin{aligned} \max_{a_L^S} \{\Phi_H(\hat{V}_H^S, a_L^S)\} \leq \hat{V}_H^S &\iff \Phi(\hat{V}_H^S, \tilde{a}) \leq \hat{V}_H^S \\ &\iff \pi \Pi_{HH}(a_H^3, a_H^3) + (1 - \pi) \Pi_{HL}(a_H^3, \tilde{a}) \\ &+ \delta \pi \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta} + \delta \frac{(1 - \pi)}{\delta} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta} - \Pi_{HH}(0, a_H^1) \right\} \\ &\leq \frac{1}{\delta} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta} - \Pi_{HH}(0, a_H^1) \right\}, \end{aligned}$$

which is equivalent to (11). If  $a_H^3 > a_H^2$ , then by the definition of  $a_H^2$ ,

$$\begin{aligned} \Phi_H(\hat{V}_H^S, \tilde{a}) \leq \hat{V}_H^S &\iff \pi \Pi_{HH}(0, a_H^2) + (1 - \pi) \Pi_{HL}(0, \tilde{a}) \\ &+ \frac{1 - \pi + \delta \pi}{1 - \delta} \Pi_{HH}(a_H^1, a_H^1) - (1 - \pi) \Pi_{HH}(0, a_H^1) \\ &\leq \frac{1}{\delta} \left\{ \frac{\Pi_{HH}(a_H^1, a_H^1)}{1 - \delta} - \Pi_{HH}(0, a_H^1) \right\}, \end{aligned}$$

which is equivalent to (12). Similarly, we can show that (19) is equivalent to (13) and (14). Therefore, (11), (12), (13), and (14) are a sufficient condition for the existence of a fixed point.

Finally, we need to show that the fixed point satisfies (9) and (10). Let  $V_H^S$  and  $V_L^S$  be parts of the fixed point such that  $V_H^S$  and  $V_L^S$  satisfy the respective conditions 6 and 8 in Definition 1. Then, we have  $V_H^S(V_H^S, a_L^S) = V_H^S$  and  $V_L^S(V_L^S, a_H^S) = V_L^S$  for some  $a_L^S$  and  $a_H^S$ . Note that  $V_H^F(x_H)$  and  $V_L^F(x_L)$  are non-increasing in  $x_H$  and  $x_L$ , respectively, and thus,  $V_H^F(x'_H) \geq V_H^F(\hat{V}_H^S)$  and  $V_L^F(x'_L) \geq V_L^F(\hat{V}_L^S)$  for any  $x'_H$  and

$x'_L$ . By (3) and (7), we have that

$$V_H^S \geq \delta\pi V_H^F(\hat{V}_H^S) + \delta(1-\pi)V_H^S \iff V_H^S \geq \frac{\delta\pi}{1-\delta+\delta\pi} \frac{\Pi_{HH}(a_H^1, a_H^1)}{1-\delta} \quad (20)$$

$$\text{and } V_L^S \geq \delta\pi V_L^S + \delta(1-\pi)V_L^F(\hat{V}_L^S) \iff V_L^S \geq \frac{\delta(1-\pi)}{1-\delta\pi} \frac{\Pi_{LL}(a_L^1, a_L^1)}{1-\delta}. \quad (21)$$

Suppose that  $a', a'' \in [0, \tilde{a}]$  satisfy the premises of (9) and (10). Then,

$$\begin{aligned} \frac{\Pi_{LH}(0, a')}{1-\delta} &\geq \frac{\Pi_{LH}(a'', a')}{1-\delta} \geq \Pi_{LH}(0, a') + \delta V_L^S \\ \implies \delta \frac{\Pi_{LH}(0, a')}{1-\delta} &\geq \delta \frac{\delta(1-\pi)}{1-\delta\pi} \frac{\Pi_{LL}(a_L^1, a_L^1)}{1-\delta} \end{aligned} \quad (22)$$

where (21) is used at the inequality (22). Since the function  $\Pi_{LH}(0, a)$  is convex, from (22), we can find that there exists  $a_H^4$  and that  $a' \geq a_H^4$ . Since  $\tilde{a} \geq a''$ , we have that  $\frac{\Pi_{HL}(a_H^4, \tilde{a})}{1-\delta} \geq \frac{\Pi_{HL}(a', a'')}{1-\delta}$ . Since the ability difference between an H-player and an L-player is wide enough,

$$\begin{aligned} \frac{\delta\pi}{1-\delta+\delta\pi} \Pi_{HH}(a_H^1, a_H^1) &\geq \Pi_{HL}(a_H^4, \tilde{a}) \\ \implies V_H^S &\geq \frac{\Pi_{HL}(a_H^4, \tilde{a})}{1-\delta} \geq \frac{\Pi_{HL}(a', a'')}{1-\delta} \end{aligned}$$

where the second inequality follows from (20). Since  $a', a'' \in [0, \tilde{a}]$  are arbitrary, the fixed point satisfies the condition 9 in Definition 1. This completes the proof.///

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