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Automatic Signal Extraction for Stationary and Non-Stationary Time Series by Circulant SSA

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1 Introduction

In many occasions, macroeconomic policy relies on analyzing a particular signal from the observed time series as the cycle or the trend. Additionally, statistical offices need to produce seasonally adjusted data for a large amount of economic indicators. Singular Spectrum Analysis (SSA) is a non-parametric (and, therefore, model free) procedure based on subspace algorithms for signal extraction. The main task in SSA is to extract the underlying components of a time series like the trend, cycle, seasonal and irregular components. It has been applied to a wide range of time series problems, besides signal extraction, like forecasting, missing value imputation and others. SSA builds a trajectory matrix by putting together lagged pieces of the original time series and works with the Singular Value Decomposition of this matrix. It is a procedure closely related to Principal Component (PC) analysis but applied to the trajectory matrix.

SSA has been applied in several fields. In economics, Hassani and Thomakos (2010) review SSA for economic and financial time series, focusing on forecasting and the business cycle monitoring. Regarding forecasting, Hassani, Heravi, Brown and Ayoubkani (2013) and Silva and Hassani (2015) focus on the effects of forecasting with SSA before and after the 2008 recession, Hassani, Soofi and Zhigljavsky (2013) forecast the inflation dynamics or Hassani, Heravi and Zhigljavsky (2013) forecast industrial production with multivariate SSA. Related to business cycles, de Carvalho, Rodrigues and Rua (2012) track the US business cycle, de Carvalho and Rua (2017) focus on the real time nowcasting of the output gap and Sella, Vivaldo, Groth and Ghil (2016) analyze economic cycles and their synchronization in three European countries. SSA has also been applied to estimate stochastic volatility models by Arteche and García-Enríquez (2016).

However, an important drawback of the initial SSA procedures is that the intervention of the analyst is required to identify the harmonic frequencies of the extracted components. To solve this problem we propose a new SSA methodology based on circulant matrices (CSSA). The main feature of these matrices is that their eigenstructure can be obtained as a function of the frequencies and therefore we can automatically identify the eigenvalues and eigenvectors associated to any particular frequency. Moreover, we also prove the validity of our proposal for nonstationary time series as well. An additional contribution of our method is the strong separability of the extracted components as compared to previous variants of SSA.

In summary, our contribution is to propose Circulant SSA to automatically apply SSA

for signal extraction, without the intervention of the analyst, recovering reliable components that are strongly separable for both stationary and nonstationary time series.

The structure of this paper is as follows: Section 2 briefly describes the SSA technique. Section 3 proposes our new SSA procedure, named after Circulant SSA and proves its use for nonstationary time series too. Section 4 verifies the strong separability of the extracted components. Section 5 presents a set of simulations to check the properties of the proposed methodology and Section 6 applies it to several real time series. Finally, Section 7 concludes.

2 SSA methodology

The origin of SSA dates back to 1986 with the publication of the papers by Broomhead and King (1986a, 1986b) and Fraedrich (1986). Vautard and Ghil (1989) introduce Toeplitz SSA under the assumption of stationary time series and Vautard et al. (1992) further develop the technique and are the first to derive an algorithm to obtain the extracted components with the length of the original series. At the same time, and independently, the so-called Caterpillar technique was developed in the former Soviet Union (see, Danilov and Zhigljavsky, 1997). Elsner and Tsonis (1996), Golyandina et al. (2001) and Golyandina and Zhigljavsky (2013) are books on the topic.

In this section we briefly describe the steps of the SSA technique to decompose a time series in its unobserved components. Let $\{x_t\}$ be a real valued time series of size T , $\mathbf{x} = (x_1, \dots, x_T)'$, and L a positive integer, called the window length, such that $1 < L < T/2$. The Basic SSA or Broomhead-King (BK) procedure involves 4 steps:

1st step: Embedding

From the original time series we will obtain an $L \times N$ trajectory matrix \mathbf{X} given by L dimensional time series of length $N = T - L + 1$ as

$$\mathbf{X} = (\mathbf{x}_1 | \dots | \mathbf{x}_N) = \begin{pmatrix} x_1 & x_2 & x_3 & \dots & x_N \\ x_2 & x_3 & x_4 & \dots & x_{N+1} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_L & x_{L+1} & x_{L+2} & \dots & x_T \end{pmatrix}$$

where $\mathbf{x}_j = (x_j, \dots, x_{j+L-1})'$ indicates the vector of dimension L and origin at time j . Notice that the trajectory matrix \mathbf{X} is Hankel and both, by columns and rows, we obtain subseries of the original one.

2nd step: Decomposition

In this step, we perform the singular value decomposition (SVD) of the trajectory matrix $\mathbf{X} = \mathbf{U}\mathbf{D}^{1/2}\mathbf{V}'$ where \mathbf{U} is the $L \times L$ matrix whose columns \mathbf{u}_k are the eigenvectors of the second moment matrix $\mathbf{S} = \mathbf{X}\mathbf{X}'$, $\mathbf{D} = \text{diag}(\tau_1, \dots, \tau_L)$, $\tau_1 \geq \dots \geq \tau_L \geq 0$, are the eigenvalues of \mathbf{S} and \mathbf{V} is the $N \times L$ matrix whose columns \mathbf{v}_k are the L eigenvectors of $\mathbf{X}'\mathbf{X}$ associated to nonzero eigenvalues. This decomposition allows to write \mathbf{X} as the sum of the so-called elementary matrices \mathbf{X}_k of rank 1,

$$\mathbf{X} = \sum_{k=1}^r \mathbf{X}_k = \sum_{k=1}^r \mathbf{u}_k \mathbf{w}_k',$$

where $\mathbf{w}_k = \mathbf{X}'\mathbf{u}_k = \sqrt{\tau_k}\mathbf{v}_k$ and $r = \max_{\tau_k > 0} \{k\} = \text{rank}(\mathbf{X})$.

3rd step: Grouping

Under the assumption of weak separability given in Golyandina et al. (2001), we group the elementary matrices \mathbf{X}_k into m disjoint groups summing up the matrices within each group. Let $I_j = \{j_1, \dots, j_p\}$, $j = 1, \dots, m$ each disjoint group of indexes associated to the corresponding eigenvectors. The matrix $\mathbf{X}_{I_j} = \mathbf{X}_{j_1} + \dots + \mathbf{X}_{j_p}$ is associated to the I_j group. The decomposition of the trajectory matrix into this groups is given by $\mathbf{X} = \mathbf{X}_{I_1} + \dots + \mathbf{X}_{I_m}$. The contribution of the component coming from matrix \mathbf{X}_{I_j} is given by $\sum_{k \in I_j} \tau_k / \sum_{k=1}^r \tau_k$.

4th step: Reconstruction

Let $\mathbf{X}_{I_j} = (\tilde{x}_{ij})$. In this step, each matrix \mathbf{X}_{I_j} is transformed into a new time series of the same length T as the original one, denoted as $\tilde{\mathbf{x}}^{(j)} = (\tilde{x}_1^{(j)}, \dots, \tilde{x}_T^{(j)})'$ by diagonal averaging of the elements of \mathbf{X}_{I_j} over its antidiagonals as follows

$$\tilde{x}_t^{(j)} = \left\{ \begin{array}{ll} \frac{1}{t} \sum_{i=1}^t \tilde{x}_{i,t-i+1}, & 1 \leq t < L \\ \frac{1}{L} \sum_{i=1}^L \tilde{x}_{i,t-i+1}, & L \leq t \leq N \\ \frac{1}{T-t+1} \sum_{i=L-N+1}^{T-N+1} \tilde{x}_{i,t-i+1}, & N < t \leq T \end{array} \right\}.$$

The alternative Toeplitz SSA or Vautard-Ghil (VG) relies on the assumption that \mathbf{x} is stationary and zero mean and it performs the SVD decomposition in step 2 from an alternative matrix $\mathbf{S}_T = (s_{ij})$ where

$$s_{ij} = \frac{1}{T - |i - j|} \sum_{m=1}^{T - |i - j|} x_m x_{m - |i - j|}, \quad 1 \leq i, j \leq L. \quad (1)$$

In this case, the matrix \mathbf{S}_T is the sample lagged variance-covariance matrix of the original series, a symmetric Toeplitz matrix. The set $(\tau_k, \mathbf{u}_k, \mathbf{w}_k)$ is named the k -th eigentriple. The rest of the algorithm remains unchanged.

3 Circulant SSA

As previously stated in the introduction, a drawback of SSA in any of its variants is that it requires the intervention of the analyst to identify the harmonic frequencies of the extracted components. To try to overcome this problem, Ghil and Mo (1991), associate two different extracted principal components with similar eigenvalues to the same oscillation if they are highly correlated for a given lag. Vautard et al. (1992) suggest a test based on the periodogram to establish if a pair of eigenvectors are associated to the same harmonic. Later, Alexandrov and Golyandina (2004, 2005) introduce optimal thresholds for grouping eigenvectors linked to nearby frequencies in order to assign them to the same harmonic. Alonso and Salgado (2008) and Bilancia and Campobasso (2010) apply cluster techniques for grouping the elementary components based on k-means and hierarchical clustering, respectively. Nevertheless, whatever procedure is used, the grouping of frequencies is made after the elementary components are extracted. Also, the previous tests and procedures are based on parameters and/or thresholds that have to be previously set in a subjective way. Since the pairs of eigenvalues and eigenvectors are obtained, not as a function of the frequency, but rather on a decreasing magnitude, this means that the grouping is done with uncertainty. Bozzo et al. (2010) provided a partial solution by linking the eigenvalues-eigenvectors as a function of the frequency for symmetric positive definite Toeplitz matrices. However, the analytic form of the eigenvalues for this type of matrices is only known for heptadiagonal ones (see, Solary, 2013). We generalize this link between the eigenstructure and the associated harmonics by the use of circulant matrices.

In this section, we propose an automatic version of SSA based on circulant matrices. First, we deal with the stationary case and later on we will extend our proposal to the nonstationary case.

3.1 Stationary case

In this subsection we propose to apply SSA to an alternative matrix of second moments that is circulant. In this case, we have closed form eigenvalues-eigenvectors that are linked to the desirable specific frequencies. We show the asymptotic equivalence between the traditional Toeplitz matrices used in SSA and our proposed circulant matrices. We also propose a more friendly and very easy to estimate approach to the elements of the circulant matrix. Based on all the previous results we propose a new algorithm that we name Circulant SSA (CSSA).

Toeplitz matrices appear when considering the population second order moments of the trajectory matrix. Let $\{x_t\}$ be an infinite, zero mean stationary time series whose autocovariances are given by $\gamma_m = E(x_t x_{t-m})$ $m = 0, 1, \dots$ and its spectral density function, a real 2π -periodic, continuous function, denoted by f . Let

$$\mathbf{\Gamma}_L(f) = \begin{pmatrix} \gamma_0 & \gamma_1 & \gamma_2 & \cdots & \gamma_{L-1} \\ \gamma_1 & \gamma_0 & \gamma_1 & \cdots & \gamma_{L-2} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \gamma_{L-1} & \gamma_{L-2} & \gamma_{L-3} & \cdots & \gamma_0 \end{pmatrix} \quad (2)$$

be the $L \times L$ matrix that collects the second moments. Notice that $\mathbf{\Gamma}_L(f)$ is a symmetric Toeplitz matrix that depends on the spectral density f through the covariances γ_m . Recall that $\gamma_m = \int_0^1 f(w) \exp(i2\pi m w) dw$ for any integer m where w is the frequency in cycles per unit of time.

Analytic expressions for the eigenvalues of Toeplitz matrices are only known up to heptadiagonal matrices. To be able to have closed solutions of the eigenvalues and eigenvectors for any dimension, we use a special case of Toeplitz matrices that are the circulant ones. In a circulant matrix every row is a right cyclic shift of the row above as follows:

$$\mathbf{C}_L(f) = \begin{pmatrix} c_0 & c_1 & c_2 & \cdots & c_{L-1} \\ c_{L-1} & c_0 & c_1 & \cdots & c_{L-2} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ c_1 & c_2 & c_3 & \cdots & c_0 \end{pmatrix}.$$

Following Lancaster (1969), the k -th eigenvalue of the $L \times L$ circulant matrix $\mathbf{C}_L(f)$ is given by

$$\lambda_{L,k} = \sum_{m=0}^{L-1} c_m \exp\left(i2\pi m \frac{k-1}{L}\right)$$

for $k = 1, \dots, L$ with associated eigenvector

$$\mathbf{u}_k = L^{-1/2}(u_{k,1}, \dots, u_{k,L})' \quad (3)$$

where $u_{k,j} = \exp\left(-i2\pi(j-1)\frac{k-1}{L}\right)$.

In particular, if we consider the circulant matrix of order $L \times L$ with elements c_m defined as:

$$c_m = \frac{1}{L} \sum_{j=0}^{L-1} f\left(\frac{j}{L}\right) \exp\left(i2\pi m \frac{j}{L}\right), \quad m = 0, 1, \dots, L-1, \quad (4)$$

we have two interesting results. First, the eigenvalues of this circulant matrix coincide with the spectral density evaluated at points $w = \frac{k-1}{L}$,

$$\lambda_{L,k} = f\left(\frac{k-1}{L}\right); \quad (5)$$

and second, the matrices $\mathbf{\Gamma}_L(f)$ and $\mathbf{C}_L(f)$ are asymptotically equivalent as $L \rightarrow \infty$, $\mathbf{\Gamma}_L(f) \sim \mathbf{C}_L(f)$, in the sense that both matrices have bounded eigenvalues and $\lim_{L \rightarrow \infty} \frac{\|\mathbf{\Gamma}_L(f) - \mathbf{C}_L(f)\|_F}{\sqrt{L}} = 0$, where $\|\cdot\|_F$ is the Frobenius norm, as Gray (1972; lemma 4.1) shows. Moreover, the eigenvalues of both matrices $\mathbf{\Gamma}_L(f)$ and $\mathbf{C}_L(f)$ are asymptotically equally distributed in the sense of Weyl¹ as a consequence of the fundamental theorem of Szegő (Grenander and Szegő, 1958) as Trench (2003) shows.

To obtain a more operational version of the procedure, we consider a new circulant matrix $\tilde{\mathbf{C}}_L(f)$ whose elements \tilde{c}_m are given by

$$\tilde{c}_m = \frac{L-m}{L} \gamma_m + \frac{m}{L} \gamma_{L-m}, \quad m = 0, 1, \dots, L-1. \quad (6)$$

In this case, Pearl (1973) shows that $\mathbf{\Gamma}_L(f)$ is asymptotically equivalent to $\tilde{\mathbf{C}}_L(f)$. By the transitivity property, the three matrices $\mathbf{\Gamma}_L(f)$, $\tilde{\mathbf{C}}_L(f)$ and $\mathbf{C}_L(f)$ are asymptotically equivalent.

Therefore, our proposal will consist on using these closed forms of the eigenvalues and eigenvectors to associate the SSA elementary components to a particular frequency before extracting them. Moreover, with this approach the spectral density is easily evaluated at frequencies $\frac{k-1}{L}$ by the eigenvalues of the $\tilde{\mathbf{C}}_L(f)$ matrix.

Finally, to deal with observed data we have to work with estimated, rather than population, quantities. So, we substitute the population autocovariances $\{\gamma_m\}_{m=0}^{L-1}$, by the sample second moments $\{s_m\}_{m=0}^{L-1}$ where $s_m, m = 0, \dots, L-1$ is defined as

$$s_m = \frac{1}{T-m} \sum_{t=1}^{T-m} x_t x_{t-m}.$$

¹Weyl defines two sets of bounded real numbers $\{a_{n,k}\}_{k=1}^n$ and $\{b_{n,k}\}_{k=1}^n$ as asymptotically equally distributed if for a given continuous function F on the interval $[-K, K]$, it holds that $\lim_{n \rightarrow \infty} \frac{\sum_{k=1}^n (F(a_{n,k}) - F(b_{n,k}))}{n} = 0$.

Since the sample autocovariances converge in probability to the population autocovariances, we define S_C with elements given by

$$\hat{c}_m = \frac{L-m}{L}s_m + \frac{m}{L}s_{L-m}, \quad m = 0, 1, \dots, L-1. \quad (7)$$

In what follows, we describe our new proposed algorithm, named Circulant SSA. Given the time series data $\{x_t\}_{t=1}^T$:

1st step: Embedding. This step is as before.

2nd step: Decomposition. Compute the circulant matrix S_C whose elements are given in (7). Find the eigenvalues $\hat{\lambda}_k$ of S_C and based on (5), associate the k -th eigenvalue to the frequency $w = \frac{k-1}{L}$, $k = 1, \dots, L$.

3rd step: Grouping. Given the symmetry of the spectral density, we have that $\hat{\lambda}_k = \hat{\lambda}_{L+2-k}$. Their corresponding eigenvectors given by (3) are complex, therefore, they are conjugated complex by pairs, $\mathbf{u}_k = \bar{\mathbf{u}}_{L+2-k}$ where $\bar{\mathbf{v}}$ indicates the complex conjugate of a vector \mathbf{v} , and $\mathbf{u}_k^* \mathbf{X}$ and $\mathbf{u}_{L+2-k}^* \mathbf{X}$ correspond to the same harmonic period, where \mathbf{v}^* denotes the transpose conjugate of \mathbf{u}_k . We proceed as follows to transform them in pairs of real eigenvectors in order to compute the associated components.

To form the elementary matrices we first form the groups of 2 elements $B_k = \{k, L+2-k\}$ for $k = 2, \dots, M$ with $B_1 = \{1\}$ and $B_{\frac{L}{2}+1} = \{\frac{L}{2} + 1\}$ if L is even. Second, we compute the elementary matrix by frequency \mathbf{X}_{B_k} as the sum of the two elementary matrices \mathbf{X}_k and \mathbf{X}_{L+2-k} , associated to eigenvalues $\hat{\lambda}_k$ and $\hat{\lambda}_{L+2-k}$ and frequency $\frac{k-1}{L}$,

$$\begin{aligned} \mathbf{X}_{B_k} &= \mathbf{X}_k + \mathbf{X}_{L+2-k} \\ &= \mathbf{u}_k \mathbf{u}_k^* \mathbf{X} + \mathbf{u}_{L+2-k} \mathbf{u}_{L+2-k}^* \mathbf{X} \\ &= (\mathbf{u}_k \mathbf{u}_k^* + \bar{\mathbf{u}}_k \bar{\mathbf{u}}_k^*) \mathbf{X} \\ &= 2(R_{\mathbf{u}_k} R'_{\mathbf{u}_k} + I_{\mathbf{u}_k} I'_{\mathbf{u}_k}) \mathbf{X} \end{aligned}$$

where the prime denotes transpose, $R_{\mathbf{u}_k}$ denotes the real part of \mathbf{u}_k and $I_{\mathbf{u}_k}$ its imaginary part. In this way, all the matrices \mathbf{X}_k , $k = 1, \dots, L$, are real.

4th step: Reconstruction. As before.

Notice that the elementary reconstructed series by frequency can be automatically assigned to a component according to the goal of our analysis.

3.2 Nonstationary case

In economics, many time series are nonstationary. That is to say, the autoregressive polynomial has unit roots. This has important consequences in our analysis and we have to

show that Circulant SSA can be applied to nonstationary time series. The next theorem, a generalization of the analogous given by Gray (1974), provides the theoretical background needed to apply Circulant SSA to nonstationary time series.

Theorem 1 *Let $\mathbf{T}_L(s)$ be a sequence of Toeplitz matrices with $s(w)$ a real, continuous and 2π -periodic, such that $s(w) \geq 0$, where the equality is reached in a finite number of points $H = \{w_i^0, i = 1, \dots, l\}$. Given a finite δ , consider the disjoint sets*

$$\Omega_i = \left\{ w \in [w_i^0 - a_i, w_i^0 + b_i] \mid s(w) \leq \frac{1}{\delta} \right\}, a_i, b_i \in \mathbb{R}^+, i = 1, \dots, l$$

and let $g(w)$ be a function defined as

$$g(w) = \begin{cases} f(w) = \frac{1}{s(w)} & \text{if } w \notin \cup_{i=1}^l \Omega_i \\ h_i(w) & \text{if } w \in \Omega_i \end{cases}$$

where $h_i(w)$ is any real valued bounded function continuous in Ω_i . Let $M_{h_i} = \text{ess sup } h_i < \infty$ and $m_{h_i} = \text{ess inf } h_i = h_i(w_i^0 - a_i) = h_i(w_i^0 + b_i) = \delta$.

Let $\rho_{L,k}, k = 1, \dots, L$, be the eigenvalues of $(\mathbf{T}_L(s))^{-1}$ sorted in decreasing order and let $F(x)$ be a continuous function in $\left[\frac{1}{M_s}, \max_i M_{h_i} \right]$ with $M_s = \text{ess sup } s$, then

$$\lim_{L \rightarrow \infty} \frac{1}{L} \sum_{k=1}^L F(\min(\rho_{L,k}, \max(\tilde{g}_k, \delta))) = \int_0^1 F(g(w)) dw, \quad (8)$$

where \tilde{g}_k are the values of $g(\frac{k-1}{L})$ sorted in descending order.

Proof: The proof is given in the Appendix.

In a similar way to Gray (1974), the theorem states that the sequence of eigenvalues of the sequence of matrices $(\mathbf{T}_L(s))^{-1}$ are asymptotically distributed (in the sense of Weyl) as the eigenvalues of the sequence of matrices $\mathbf{T}_L(g)$ up to a finite value δ as L tends to infinity. Moreover, the matrices $\mathbf{T}_L(g) \sim \mathbf{C}_L(g)$ and by Szegő's theorem, the eigenvalues of the sequence of matrices $\mathbf{T}_L(g)$ are asymptotically distributed as the eigenvalues of the sequence of matrices $\mathbf{C}_L(g)$ up to a finite value δ as L tends to infinity.

As a result, for a nonstationary series, the union of the estimation of the spectral density in a point of discontinuity with the estimations in the adjoint frequencies through segments is an easy way of building the functions h_i . If all the functions h_i are constant and equal to a particular value δ finite, we have the particular case proved in Gray (1974). Therefore, the generalization to functions h_i allows a better approximation of the spectral density when we increase the window length.

4 Separability of SSA

Separability of the elementary series as well as those grouped by frequencies is an assumption of SSA and should also be a characteristic of the estimated components. This characteristic is important since many signal extraction procedures assume zero correlation between their underlying components, whereas the estimated signals can be quite correlated. As Golyandina et al. (2001) point out the SSA decomposition can be successful only if the resulting additive components of the series are quite separable from each other. In this section, we first introduce the basic notions of separability and how it is measured. Afterwards, we show that Circulant SSA produces component series that are highly separable outperforming alternative algorithms.

For a fixed window length L , given two series $\{x_t^{(1)}\}$ and $\{x_t^{(2)}\}$ extracted from the series $\{x_t\}$, we say that they are weakly separable if both their column as well as row spaces are orthogonal, that is $\mathbf{X}^{(1)} (\mathbf{X}^{(2)})' = \mathbf{0}_{L \times L}$ and $(\mathbf{X}^{(1)})' \mathbf{X}^{(2)} = \mathbf{0}_{N \times N}$. Furthermore, we say that two series $\{x_t^{(1)}\}$ and $\{x_t^{(2)}\}$ are strongly separable if they are weakly separable and the two sets of singular values of the trajectory matrices $\mathbf{X}^{(1)}$ and $\mathbf{X}^{(2)}$ are disjoint. When the trajectory matrix of the original time series has not multiple singular values or, equivalently, each elementary reconstructed series belongs to a different harmonic, strong separability is guaranteed according to the previous definition.

Usually, separability is measured in terms of \mathbf{w} -correlation (see, for instance, Golyandina et al., 2001, and Golyandina and Zhigljavsky, 2013), that it is given by

$$\rho_{12}^w = \frac{\langle \mathbf{x}^{(1)}, \mathbf{x}^{(2)} \rangle_w}{\|\mathbf{x}^{(1)}\|_w \|\mathbf{x}^{(2)}\|_w},$$

where $\langle \mathbf{x}^{(1)}, \mathbf{x}^{(2)} \rangle_w = (\mathbf{x}^{(1)})' \mathbf{W} \mathbf{x}^{(2)}$ is the so called w -inner product and $\|\mathbf{x}^{(1)}\|_w = \sqrt{\langle \mathbf{x}^{(1)}, \mathbf{x}^{(1)} \rangle_w}$ and $\mathbf{W} = \text{diag}(1, 2, \dots, \underbrace{L, \dots, L}_{T - 2(L - 1) \text{ times}}, \dots, 2, 1)$. Note that the window length L en-

ters the definition of \mathbf{w} -correlation. We are interested on producing components with \mathbf{w} -correlation (ideally) zero because, in this case, we can conclude that the component series are \mathbf{w} -orthogonal, i. e. $\langle \mathbf{x}^{(1)}, \mathbf{x}^{(2)} \rangle_w = 0$ and separable (see, Golyandina et al. 2001). To quickly check how separable are the component series when performing SSA, we plot the matrix of the absolute values of the \mathbf{w} -correlations for all the component series, coloring in white the absence of \mathbf{w} -correlation, in black \mathbf{w} -correlations in absolute value equal to 1 and in a scale of grey colors the remaining intermediate values.

To show that Circulant SSA produces components that are strongly separable, first notice that the real eigenvectors $\sqrt{2}R_{\mathbf{u}_k}$ and $\sqrt{2}I_{\mathbf{u}_k}$ (linked to eigenvalues λ_k and λ_{L+2-k} , respectively, $\lambda_k = \lambda_{L+2-k}$) are orthogonal and have information associated only to frequency $\frac{k-1}{L}$. Those are the only eigenvectors that have information related to this frequency. As eigenvectors can be considered filters, Kume (2013), these pair of eigenvectors extract elementary series linked to the same frequency without mixing harmonics of other frequencies. As a result, the two elementary series, when reconstructed in step 4, have spectral correlation close to 1 between them and close to zero with the remaining ones. Taking into account the pairs of reconstructed series per frequency, any grouping of the reconstructed series results in disjoint sets from the point of view of the frequency. Then, Circulant SSA produce components that are approximately strongly separable. In this case, the graph of the \mathbf{w} -correlation matrix is black color in the main diagonal and white elsewhere as in the ideal case.

As we shall see in the simulation and in the empirical application, CSSA produces components that are more separable than previous alternatives os SSA, Basic and Toeplitz.

5 Simulations

In this section we compare the performance of our new proposal, Circulant SSA, with the competing SSA algorithms, i.e. Basic SSA and Toeplitz SSA for a linear as well as nonlinear time series model. We focus on two main aspects: reliability of the estimated components in finite samples and separability.

5.1 Linear time series

The first model is a basic structural time series model

$$x_t = T_t + c_t + s_t + e_t \quad (9)$$

where T_t is the trend component, c_t is the cycle, s_t is the seasonal component and e_t is the irregular component. We assume an integrated random walk for the trend (see Young 1984) given by

$$\begin{aligned} T_t &= T_{t-1} + \beta_{t-1} \\ \beta_t &= \beta_{t-1} + \eta_t \end{aligned} \quad (10)$$

with $\eta_t \sim N(0, \sigma_\eta^2)$. The cyclical and seasonal components are specified according to Durbin and Koopman (2012), where the cycle is given by the first component of the bivariate VAR(1)

$$\begin{pmatrix} c_t \\ \tilde{c}_t \end{pmatrix} = \rho_c \begin{pmatrix} \cos(2\pi w_c) & \sin(2\pi w_c) \\ -\sin(2\pi w_c) & \cos(2\pi w_c) \end{pmatrix} \begin{pmatrix} c_{t-1} \\ \tilde{c}_{t-1} \end{pmatrix} + \begin{pmatrix} \varepsilon_t \\ \tilde{\varepsilon}_t \end{pmatrix} \quad (11)$$

with $\begin{pmatrix} \varepsilon_t \\ \tilde{\varepsilon}_t \end{pmatrix} \sim N(\mathbf{0}, \sigma_\varepsilon^2 I)$ and $\frac{1}{w_c}$ the period with $w_c \in [0, 1]$. The seasonal component is given by

$$s_t = \sum_{j=1}^{\lfloor s/2 \rfloor} a_{j,t} \cos(2\pi w_j t) + b_{j,t} \sin(2\pi w_j t) \quad (12)$$

with $w_j = \frac{j}{s}, j = 1, \dots, \lfloor s/2 \rfloor$ and s the seasonal period, where $\lfloor \cdot \rfloor$ is the integer part and $a_{j,t}$ and $b_{j,t}$ are two independent random walks with noise variances equal to σ_j^2 . Finally, the irregular component is white noise with variance σ_ε^2 . All the components are independent of each other. We set $\rho_c = 1$, so the trend, cycle and seasonal components have a unit root. We consider that the series are monthly with $s = 12$ and cyclical period equal to $\frac{1}{w_c} = 48$ months. The sample size is $T = 193$ and the noise variances of the different components are given by $\sigma_\eta^2 = 0.0006^2$, $\sigma_j^2 = 0.004^2$, $\sigma_\varepsilon^2 = 0.008^2$ and $\sigma_e^2 = 0.06^2$. We choose as window length $L = 48$ following Golyandina and Zhigljavsky (2013), since L is multiple of the seasonal period, it is equal to the cyclical period and $T - 1$ is multiple of L .

The trend is related to the 0 frequency, the cycle to frequency $1/48$ and the seasonal components to frequencies $1/12, 1/6, 1/3, 1/4, 5/12$ and $1/2$. Then, according to (5) and the symmetry of the spectral density, the trend is reconstructed with the eigentriple 1, the cyclical component with the eigentriples 2 and 48, and the seasonal components with the eigentriples 5, 9, 13, 17, 21, 25, 29, 33, 37, 41 and 45. For example, for the frequency $w = \frac{1}{12}$, we have that $\frac{k-1}{L} = \frac{1}{12}$, and therefore, we sum the elementary components $k = \frac{48}{12} + 1 = 5$ and $L + 2 - k = 48 + 2 - 5 = 45$.

If the procedure for signal extraction works well, the simulated component y_t (y_t can be the trend, cycle or seasonal component) could be written as

$$y_t = \hat{y}_t + u_t$$

where u_t is the noise and \hat{y}_t is the extracted signal. Then, in the regression

$$y_t = a + b\hat{y}_t + e_t \quad (13)$$

$a = 0$ (unbiasedness) and $b = 1$ (the scale is not changed). We simulate 1000 times the model and perform signal extraction with Circulant SSA. Table 1 shows the percentiles of the empirical distribution of the estimated coefficients of the regression in (13). The last three rows of the table show the inverse of the signal to noise ratio

$$SNR^{-1} = \frac{\sigma_u^2}{\sigma_s^2}$$

where σ_u^2 is the variance of the noise $u_t = y_t - \hat{y}_t$ and σ_s^2 is the variance of the estimated signal \hat{y}_t . A value close to zero indicates that the explanatory power of the noise is very small compared to that of the signal and it is an indication of a good approximation. Table 1 shows that the median of the estimated intercept is almost zero for the three estimated components (cycle, seasonal component and trend). The median for the scale parameter b is almost one for the three components, but looking at the values for different quantiles, the empirical distribution for the estimated b associated to the cycle indicates a larger dispersion.

TABLE 1 SHOULD BE INSERTED AROUND HERE

The estimated residuals from equation (9) are given by $\hat{e}_t = x_t - \hat{T}_t - \hat{c}_t - \hat{s}_t$ and should be white noise. In order to check this, we fit an AR(1) to \hat{e}_t . Table 2 shows the quantiles of the empirical distribution of the mean, standard error and autoregressive coefficient of the residuals of the 1000 replications. The median of the mean and autoregressive coefficient are close to zero. The median of the standard deviation is 0.0529 (the value used for the simulations was 0.06).

TABLE 2 SHOULD BE INSERTED AROUND HERE

The results from the simulations seem very good. In order to compare Circulant SSA with alternative algorithms as Basic and Toeplitz SSA, we describe in more detail the simulation corresponding to the replication number 500. With Circulant SSA, we know in advance the eigentriples corresponding to each component (trend, cycle and seasonal component). For Basic and Toeplitz SSA, we associate the eigentriples to each component (trend, cycle or seasonal component) afterwards. In this particular case, for Basic SSA, we associate the eigentriple 1 with the trend, eigentriples 2 and 3 with the cycle and eigentriples 4 to 14 with the seasonal component. For Toeplitz SSA, the trend is reconstructed with the eigentriple 1, the cycle with eigentriples 2 and 3 and the seasonal component with the eigentriples 5 to 11 and 14 to 18. We also compute the statistics associated to the error

term of the estimated components. In Table 3 we present the summary statistics for the error term as well as the inverse of the SNR .

TABLE 3 SHOULD BE INSERTED AROUND HERE

Although the summary statistics from Table 3 seem to show that the three algorithms (Circulant, Basic and Toeplitz SSA) produce similar results, notice that Circulant SSA produces components with smaller SNR^{-1} .

Regarding separability, Figure 1 plots the \mathbf{w} -correlation matrices for the components extracted with the three algorithms. Notice that Circulant SSA produces matrices that are closer to diagonality than the other two alternatives where we can see different degrees of grey in the off-diagonal cells. Therefore, as it was expected, Circulant SSA recovers components that are more separable than the two alternative versions of SSA, Basic and Toeplitz.

FIGURE 1 SHOULD BE INSERTED AROUND HERE

5.2 Non-linear time series

For the case of non-linear time series, we borrow the model from Durbin and Koopman (2012) for UK travellers given by

$$x_t = T_t + c_t + \exp(a_0 + a_1 T_t) \gamma_t + \varepsilon_t$$

where T_t is the trend, c_t is the cycle and γ_t is the seasonal component specified as in (10), (11) and (12), respectively. The parameters a_0 and a_1 are unknown fixed coefficients. Coefficient a_0 scales the seasonal component. The sign of the coefficient a_1 determines whether the seasonal variation increases or decreases when a positive change in the trend occurs. The overall time varying amplitude of the seasonal component is determined by the combination $a_0 + a_1 \mu_t$.

As for the linear case, we simulate the model 1000 times for series of length $T = 193$ observations. We set a_0 and a_1 such that for each replication $0.5 \leq \exp(a_0 + a_1 \mu_t) \leq 1.5$, with $a_1 > 0$. We apply Circulant SSA with a window length $L = 48$. Table 4 shows the quantiles of the empirical distribution of the estimated coefficients of the regression in (13). The last three rows of the table show the inverse of the signal to noise ratio SNR^{-1} .

TABLE 4 SHOULD BE INSERTED AROUND HERE

In order to check that the estimated residuals are white noise, we fit an AR(1) to \hat{e}_t as in the linear case. Table 5 shows the quantiles of the empirical distribution of the mean, standard error and autoregressive coefficient of the residuals of the 1000 replications. The median of the mean and autoregressive coefficient are close to zero. The median of the standard deviation is 0.053 (the value used for the simulations was 0.06).

TABLE 5 SHOULD BE INSERTED AROUND HERE

As in the linear case, the results from the simulations seem very good. To compare Circulant SSA with alternative algorithms as Basic and Toeplitz SSA, we describe in more detail replication number 500. Table 6 shows the summary statistics of the residuals as well as the inverses of the SNR in order to check the adequacy of the three versions of SSA.

TABLE 6 SHOULD BE INSERTED AROUND HERE

Although the three algorithms seem to work quite well, Circulant SSA produces components with smaller SNR^{-1} . Figure 2 shows the \mathbf{w} -correlation matrices for the components extracted with the three algorithms. Notice that in the nonlinear case, Circulant SSA also presents \mathbf{w} -correlation matrices that are closer to the diagonality than the other two alternatives where we can see different degrees of grey in the off-diagonal cells. Again, Circulant SSA recovers components that are more separable than the two alternative versions of SSA, Basic and Toeplitz.

FIGURE 2 SHOULD BE INSERTED AROUND HERE

6 Application

We consider monthly series of Industrial Production (IP), index 2010=100, of six countries: France, Germany, Italy, UK, Japan and USA. Industrial Production is widely followed since it is pointed out in the definition of a recession by the National Bureau of Economic Research (NBER), <http://www.nber.org/cycles/recessions.html>, as one of the four monthly indicators series to check in the analysis of the business cycle. The sample covers from January 1970 to September 2014, so the sample size $T = 537$. The data source is the IMF database. As it can be seen in Figure 3, these indicators show different trend, seasonality and cyclical behavior, and our goal is to extract these components and discuss about the results.

FIGURE 3 SHOULD BE INSERTED AROUND HERE

The first step is to establish the window length. Due to the monthly periodicity and seasonality, we select a window length multiple of 12. Assuming that the period of the cycle in these series goes from 1 year and a half to 8 years, we choose a window length multiple of $8 \times 12 = 96$ months. From the two available options, 96 and 192 months, we select the second one since it is larger according to the asymptotic results provided in Section 3.

We apply Circulant SSA, and associate the trend to the frequencies $w = 0$ and $w = 1/192$ (as they correspond to periods of infinite and a long cycle of 16 years respectively). According to (5) and the symmetry of the spectral density, the trend is reconstructed with the eigentriples 1, 2 and 192 and with the elementary groups by frequencies B_1 and B_2 respectively. According to the assumption that the period for the cycle goes from 1.5 to 8 years, this component is associated to the frequencies $w = 1/96, 1/64, 1/48, 5/192, 1/32, 7/192, 1/24, 3/64, 5/96$ and the cycle signal is reconstructed with the eigentriples 3 to 11 and 183 to 191, with the elementary groups by frequencies from B_3 to B_{11} . Finally, the seasonal component is associated to the frequencies $w = 1/12, 1/6, 1/4, 1/3, 5/12, 1/2$ and reconstructed in a similar way with the eigentriples 17, 33, 49, 65, 81, 97, 113, 129, 145, 161 and 177 and with the elementary groups by frequencies $B_{17}, B_{33}, B_{49}, B_{65}, B_{81}$, and B_{97} .

Table 7 shows the contributions of the signals to the original IP variations in percentage. First, we highlight that the contribution of the irregular component (those oscillations not explained by the trend, cyclical or seasonal components) is smaller than 3.5% in all the countries. Main contributions come from the trend and seasonality, that account for more than 84% in all the countries. As expected, the contribution of the seasonal component is almost negligible in USA, and quite small in Japan and Germany, while it is very relevant in Italy and France. Finally, the cycle contributes in a range between 7.8% in Italy to 13.8% in Japan.

TABLE 7 SHOULD BE INSERTED AROUND HERE

Figure 3 shows the estimated trends for every country. The trend is a smooth component that has shown a decreasing evolution since the last decade for France, Italy and UK as a consequence of the last economic crisis. On the contrary, in Germany and US, the trend shows an upward evolution in all the sample period.

Figure 4 shows the cyclical component where the shaded areas correspond to recessions as dated by the OECD. We can see that the extracted cycle reflects quite well the business

cycle for all countries.

FIGURES 4 AND 5 SHOULD BE INSERTED AROUND HERE

Figure 5 shows the matrices of \mathbf{w} -correlations and it can be seen that, as expected, Circulant SSA produces components that are strongly separable. Separability results is a very desirable feature in the construction of seasonal adjusted time series, that is the absence of any remaining seasonality. To check the quality of seasonal adjustment by Circulant SSA, we have applied the *combined test for seasonality* (Lothian, 1978) used in X12-ARIMA. We found that there were no signs of any remaining seasonality in any of the seasonal adjusted time series for the different countries².

7 Conclusions

SSA is a nonparametric technique to extract the unobserved components present in a time series. Up to now, the intervention of the analyst was needed to identify the frequencies associated to each component. In this paper, we propose a new version of SSA, Circulant SSA, that does not need the intervention of the analyst. It relies on the asymptotic equivalence between Toeplitz and circulant matrices of second order moments of time series. The properties of circulant matrices allow to estimate the spectral density of a time series at certain frequencies through the eigenvalues. We can also identify automatically and a priori the frequencies associated to those eigenvalues. In this way, results are obtained very fast and with no subjective intervention from the analyst.

We also extend the algorithm to the nonstationary case providing a generalization of Gray's theorem (1974).

The eigenvectors obtained from the diagonalization of the circulant matrix associated to second moments of the original series are real and form an orthonormal basis in the column space of the trajectory matrix. As a result, we can guarantee that all the elemental components are real. Additionally, they are strongly separable, so it is easy to group the elemental series to obtain the different signals (trend, cycle, seasonality...). We have compared our version of SSA to two already available ones (Basic and Toeplitz SSA) and although the final results are quite similar, Circulant SSA is faster, automatic and produces more separable components.

²Results are available from the authors upon request.

The properties of Circulant SSA have been checked through a set of simulations for linear and nonlinear time series models as well as through the empirical application where we showed that Circulant SSA produced deseasonalized series clean of any seasonality. The cycle was also very useful to study the business cycle.

8 Appendix

Proof of Theorem 1: As defined, the function $g(w)$ is real, continuous and 2π -periodic. Its image is $\left[\frac{1}{M_s}, \max_i M_{h_i}\right]$ being different from zero in the whole interval. Then, by the properties of the inverse of Toeplitz matrices $(\mathbf{T}_L(g^{-1}))^{-1} \sim \mathbf{T}_L(g)$. Moreover, if $F(x)$ is continuous in $\left[\frac{1}{M_s}, \max_i M_{h_i}\right]$, then $F\left(\frac{1}{x}\right)$ is continuous in $\left[\frac{1}{\max_i M_{h_i}}, M_s\right]$. Given that Gutiérrez and Gutiérrez (2012) relax the assumption of $g(w)$ being a Wiener's class function to a continuous and 2π -periodic function, Szegő's Theorem leads to (8). ■

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9 Tables and Figures

Statistic	Component	Quantiles				
		5	25	50	75	95
a	Trend	-.058	-.023	-.012	.019	.054
	Cycle	-.010	-.004	.000	.005	.011
	Seasonal	-.002	-.001	.000	.001	.002
b	Trend	.975	.996	1.004	1.015	1.062
	Cycle	.854	.957	1.005	1.046	1.126
	Seasonal	.947	.983	1.006	1.029	1.064
SNR^{-1}	Trend	.001	.002	.005	.021	.169
	Cycle	.018	.041	.085	.179	.522
	Seasonal	.035	.052	.070	.092	.139

Table 1. Statistics related to the goodness of fit of the extracted signals. The first columns are quantiles of the empirical distribution of the estimated coefficients of the regression of the generated components over the extracted ones; the last three rows show the inverse of the signal to noise ratio.

Statistic	Quantiles				
	5	25	50	75	95
Mean	-.003	-.001	.000	.001	.003
S.E.	.048	.051	.053	.055	.058
ρ	-.173	-.083	-.031	.028	.117

Table 2. Quantiles of the empirical distribution of the statistics related to the residuals.

Algorithm	Statistics for \hat{e}_t			SNR^{-1}		
	Average	S.E.	ρ	Trend	Cycle	Seas
Circulant	.004	.053	-.063	.0008	.0133	.0586
Basic	-.001	.053	-.073	.0014	.0140	.0599
Toeplitz	.001	.054	-.059	.0008	.0194	.0651

Table 3. Summary statistics of the residuals of the model \hat{e}_t (columns 2 to 4) and inverses of the SNR (columns 5 to 7) for the replication number 500.

Statistic	Component	Quantiles				
		5	25	50	75	95
a	Trend	-.057	-.020	.000	.021	.058
	Cycle	-.011	-.004	.000	.005	.011
	Seasonal	-.002	-.001	.000	.001	.002
b	Trend	.971	.995	1.003	1.014	1.062
	Cycle	.845	.954	1.002	1.046	1.138
	Seasonal	.921	.976	1.006	1.034	1.073
SNR^{-1}	Trend	.001	.002	.006	.022	.181
	Cycle	.020	.041	.080	.158	.495
	Seasonal	.037	.060	.082	.117	.184

Table 4. Statistics related to the goodness of fit of the extracted signals for the nonlinear model. The columns are quantiles of the empirical distribution of the estimated coefficients of the regression of the generated components over the extracted ones; the last three rows show the inverse of the signal to noise ratio.

Statistic	Quantiles				
	5	25	50	75	95
Mean	-.004	-.001	.000	.001	.003
S.E.	.048	.051	.053	.055	.059
ρ	-.166	-.089	-.026	.029	.104

Table 5. Quantiles of the empirical distribution of the statistics related to the residuals.

Algorithm	Statistics for \hat{e}_t			SNR^{-1}		
	Average	S.E.	ρ	Trend	Cycle	Seas
Circulant	-.001	.054	-.145	.0020	.0315	.0372
Basic	.002	.054	-.148	.0027	.0318	.0403
Toeplitz	.000	.059	-.228	.0021	.0433	.0628

Table 6. Summary statistics of the residuals of the nonlinear model \hat{e}_t (columns 2 to 4) and inverses of the SNR (columns 5 to 7) for the replication number 500.

Components	France	Germany	Italy	Japan	UK	USA
Trend	52.1	77.3	42.7	79.0	72.0	87.9
Cycle	9.5	12.6	7.8	13.8	11.1	10.3
Seasonal	35.6	6.7	47.3	5.1	13.5	0.3
Irregular	2.8	3.4	2.2	2.1	3.4	1.5
Total	100.0	100.0	100.0	100.0	100.0	100.0

Table 7. Contribution (%) of the different signals to IP.

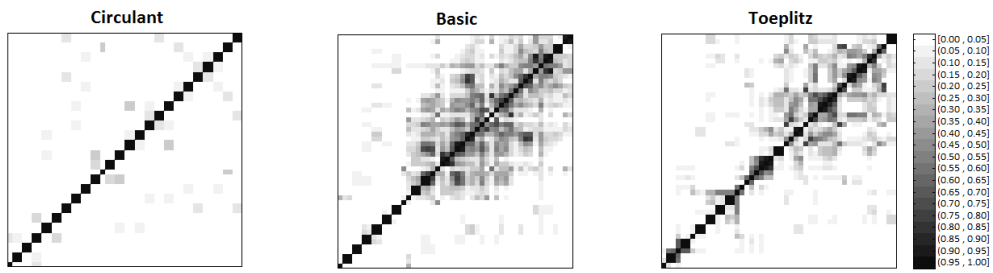


Figure 1: Example: w-correlations of the extracted components with Circulant, Basic and Toeplitz SSA.

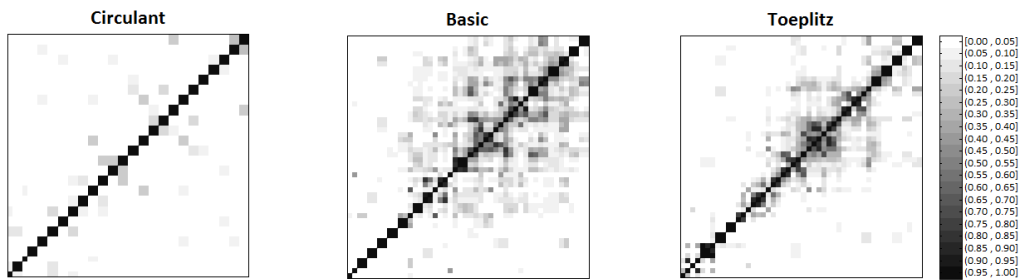


Figure 2: Illustrative example: w-correlations of the extracted components with Circulant, Basic and Toeplitz SSA (nonlinear case).

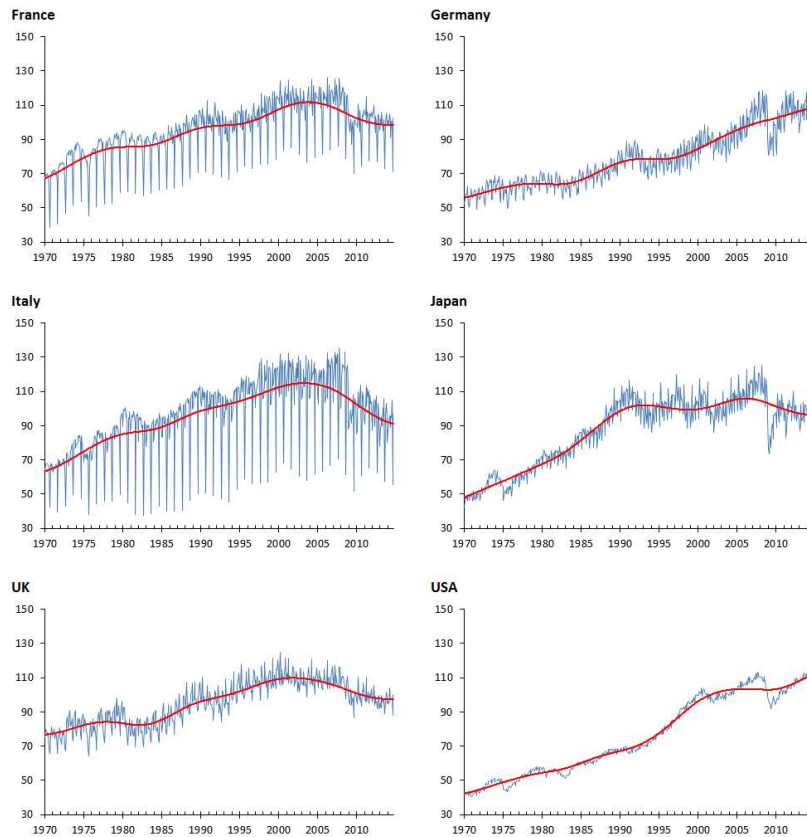


Figure 3: Original IP and trend for the different countries.

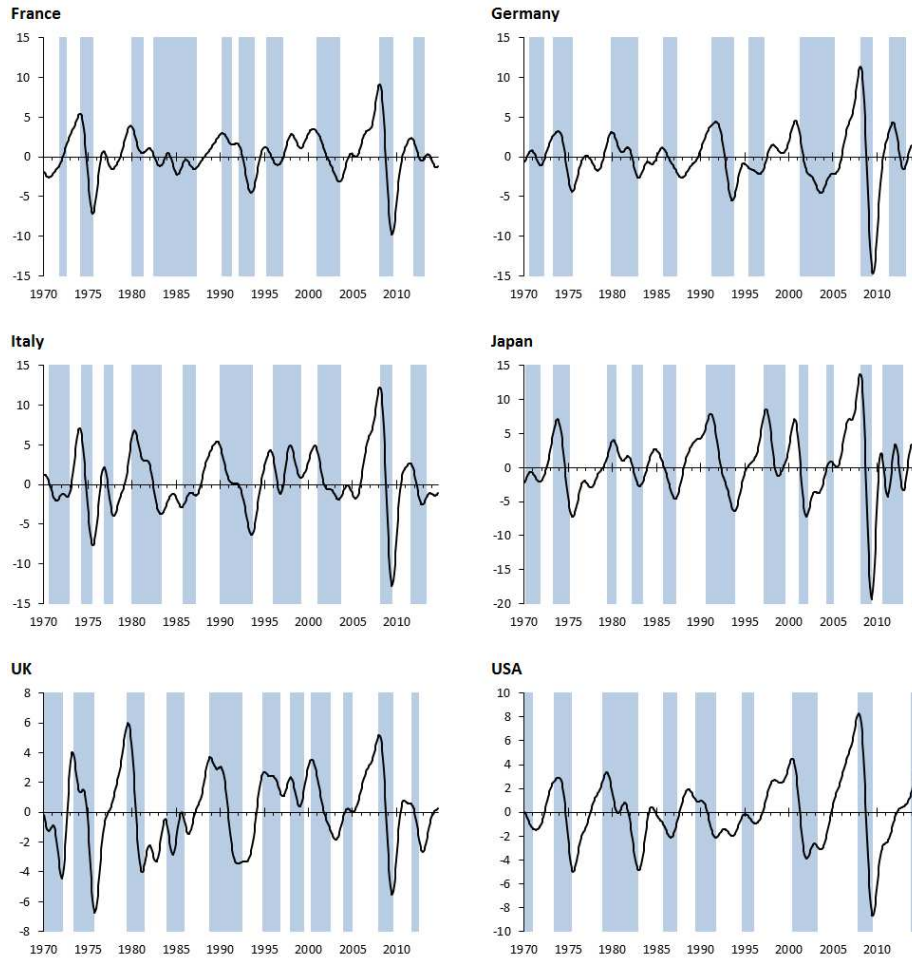


Figure 4. Estimated cycles and OECD announced recessions (shadowed areas).

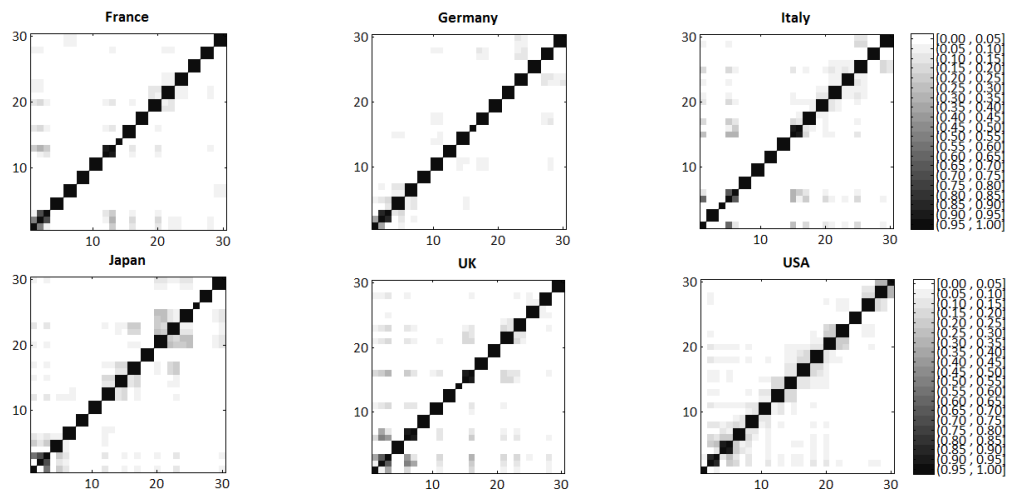


Figure 5. w-correlation matrix for the elementary reconstructed series for the 30 greatest eigenvalues.