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Negative binomial quasi-likelihood inference for general integer-valued time series models

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Abstract

Two *negative binomial quasi-maximum likelihood estimates* (*NB-QMLE*'s) for a general class of count time series models are proposed. The first one is the *profile NB-QMLE* calculated while arbitrarily fixing the dispersion parameter of the negative binomial likelihood. The second one, termed *two-stage NB-QMLE*, consists of four stages estimating both conditional mean and dispersion parameters. It is shown that the two estimates are consistent and asymptotically Gaussian under mild conditions. Moreover, the two-stage *NB-QMLE* enjoys a certain asymptotic efficiency property provided that a negative binomial *link function* relating the conditional mean and conditional variance is specified. The proposed *NB-QMLE*'s are compared with the Poisson *QMLE* asymptotically and in finite samples for various well-known particular classes of count time series models such as the (Poisson and negative binomial) Integer *GARCH* model and the *INAR*(1) model. Applications to two real datasets are given.

Keywords and phrases: Integer-valued time series models, Integer *GARCH*, Integer *AR*, Generalized Linear Models, Quasi-likelihood, Geometric *QMLE*, Negative Binomial *QMLE*, Poisson *QMLE*, consistency and asymptotic normality.

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1. Introduction

Integer-valued time series like count and binary data are well observed in a broad range of applications (e.g. economics, finance, epidemiology, medicine, telecommunications...). They are characterized by some stylized facts such as small values, overfrequency of zeros, locally constant behavior, overdispersion, positive autocorrelation structure, and asymmetric marginal distributions (see e.g. Kedem and Fokianos, 2002; McKenzie, 2003; Fokianos, 2012; Cameron and Trivedi, 2013; Silva, 2015; Davis et al, 2016). It is well documented that continuous-valued time series models such as *ARMA*-like processes are inappropriate for modeling such integer-valued series. This is why considerable interest has been paid in recent decades to alternative integer-valued time series models. Numerous models have been introduced so it appears difficult to classify them. However, two major classes of integer-valued models have played a central role. The first one is the class of models based on integer-valued regressions like *generalized ARMA (GARMA)* models, Poisson autoregression and especially *Integer Generalized Conditional Heteroskedastic (INGARCH)* models (e.g. Benjamin et al, 2003; Heinen, 2003; Ferland et al, 2006; Fokianos et al, 2009; Zhu, 2011-2012a-2012b; Doukhan et al, 2012; Christou and Fokianos, 2014; Davis and Liu, 2016; Chen et al, 2016). The second class, however, concerns stochastic difference equations involving the *thinning* operator where the best known example is the *INteger AR (INAR)* model (e.g. McKenzie, 1985-2003; Al-Osh and Alzaid, 1987; Silva, 2015; Bourguignon, 2016).

Ahmad and Francq (2016) recently introduced a more general integer-valued time series model that encompasses many models of the two aforementioned classes. This model we call *INteger Generalized AutoRegression* (henceforth *INGAR*) is defined through specifying its conditional mean as a measurable parametric function of the infinite past of the observed process. Important subclasses of this model are the general *Poisson autoregression* (Doukhan et al, 2012; Doukhan and Kengne, 2015; Kengne, 2015), the *INGARCH* model and the *INAR* model. For the *INGAR* model, Ahmad and Francq (2016) established consistency and asymptotic normality of the *Poisson quasi-maximum likelihood estimate (P-QMLE)*, which is calculated as if the conditional distribution of the model were Poissonian. The

P - $QMLE$ has in fact many advantages: i) firstly, it is robust to misspecification of the true conditional distribution whenever the conditional expectation is well specified. This is due to the fact that the Poisson likelihood belongs to the linear exponential family (White, 1982; Gourieroux et al, 1984a). ii) Secondly, it is asymptotically efficient when the true conditional distribution of the model is Poissonian. iii) Thirdly, when the conditional variance and conditional mean of the model are proportional, the P - $QMLE$ is asymptotically efficient in the class of all $QMLE$'s whose likelihood belongs to the linear exponential family (see Gourieroux et al, 1984a). The latter proportionality between the conditional mean and conditional variance is usually called the Poisson *Generalized Linear Model* (henceforth *GLM*) *assumption* (or *link function*). However, despite these advantages, the Poisson distribution, which is known to be equidispersed fit badly to overdispersed series that are frequently observed in practice. Therefore, it is likely that the P - $QMLE$ does not reach its full asymptotic efficiency in the presence of overdispersed data. Thus a quasi-maximum likelihood (QML) estimate, which is calculated using an overdispersed likelihood while belonging to the linear exponential family would be an interesting complementary to the P - $QMLE$.

For the *INGAR* model considered by Ahmad and Francq (2016), we propose two variants of the *negative binomial QMLE* (NB - $QMLE$). These estimates are calculated on the basis of the negative binomial likelihood, belonging to the linear exponential family. The first one, which we call "profile NB - $QMLE$ " (pNB - $QMLE$) consists in maximizing the negative binomial likelihood over the conditional mean parameter letting the corresponding dispersion parameter arbitrarily fixed. In particular, when the latter parameter equals one, the resulting estimate reduces to the *geometric QMLE* (Aknouche and Bendjeddou, 2017). The second one, however, consists of four stages: a two-stage NB - $QMLE$ to estimate the conditional mean parameter of the model and a two-stage weighted least squares estimate for the dispersion parameter. For this, the *INGAR* model should satisfy a negative binomial *GLM link function* involving the unknown dispersion parameter to be estimated. In the context of static integer-valued regression, a similar three-stage estimate was termed "*quasi-generalized pseudo-maximum likelihood estimate*" by Gourieroux et al (1984b) and "*two-*

stage negative binomial quasi-maximum likelihood estimate" (*2SNB-QMLE*) by Wooldridge (1997). Adopting the latter notation, the four-stage estimate we propose will be denoted by *2SNB-QMLE*. It will be shown under some mild assumptions that the two proposed estimates are consistent and asymptotically Gaussian without fully specifying the conditional distribution of the model. Moreover, under the negative binomial *GLM* link function, the *2SNB-QMLE* is asymptotically efficient in the class of all *QMLE*'s belonging to the linear exponential family, including the *P-QMLE*.

The rest of this paper is outlined as follows. Section 2 presents the *INGAR* model and the corresponding negative binomial *QML* criteria. Section 3 establishes consistency and asymptotic normality of the *pNB-QMLE* and the *2SNB-QMLE*. As a result, Section 4 compares the asymptotic variance of the proposed *NB-QMLE*'s with that of the *P-QMLE* under some specific *GLM* assumptions as well as on particular classes of the *INGAR* model. In particular, the *Poisson INGARCH* model, the *negative binomial INGARCH* model and the *INAR(1)* model are examined. Moreover, these estimates are compared in finite samples via some simulation experiments. Application to the number of poliomyelitis cases in the United States (Polio data, Zeger, 1988) and the number of transactions of the Ericsson *B* stock (Transaction data, Fokianos et al, 2009; Christou and Fokianos, 2014) under the negative binomial *INGARCH* framework are considered. Section 6 concludes while proofs of the main results are left to Section 7.

In what follows, we heavily use the following notations and conventions: All random variables and sequences we consider are defined on a probability space (Ω, \mathcal{F}, P) . The symbols $\mathbb{Z} = \{\dots, -1, 0, 1, \dots\}$, $\mathbb{N} = \{0, 1, \dots\}$ and $\mathbb{N}^* = \mathbb{N}/\{0\}$ denote respectively the set of integers, the set of nonnegative integers and the set of positive integers. The notation $Y \sim \mathcal{P}(\mu)$ means that the random variable Y has a Poisson distribution with parameter $\mu > 0$. Similarly, $X \sim \mathcal{NB}(r, p)$ means that X has the negative binomial distribution (also called mixture Poisson-Gamma distribution). This distribution is given for any $x \in \mathbb{N}$ by $f_X(x) := P(X = x) = \frac{\Gamma(x+r)}{x!\Gamma(r)} p^r (1-p)^x$, where $r > 0$ is a positive real number called the dispersion parameter, $p \in (0, 1)$ is a probability parameter, Γ is the gamma function and

$x!$ is the factorial of x . When $r \in \mathbb{N}^*$ has to be a positive integer, the factor $\frac{\Gamma(x+r)}{x!\Gamma(r)}$ may be replaced by the binomial coefficient $\binom{x+r-1}{x}$. In particular, when $r = 1$ we find the geometric distribution and we simply write $X \sim \mathcal{G}(p)$. Following Cameron and Trivedi (2013), the negative binomial- K conditional distribution given a σ -algebra $\mathcal{B} \subset \mathcal{F}$ is defined by $X/\mathcal{B} \sim \mathcal{NB}\left(r\lambda^{2-K}, \frac{r\lambda^{2-K}}{r\lambda^{2-K}+\lambda}\right)$ where $\lambda = E(X/\mathcal{B})$ and $r > 0$. Two important cases of the latter model are the negative binomial- I conditional distribution corresponding to $K = 1$ and the negative binomial- II model for which $K = 2$. Finally, the symbols $\xrightarrow[n \rightarrow \infty]{a.s.}$, $\xrightarrow[n \rightarrow \infty]{p}$ and $\xrightarrow[n \rightarrow \infty]{\mathcal{L}}$ denote respectively almost sure convergence, convergence in probability and convergence in distribution as $n \rightarrow \infty$ while $o_p(1)$, $o_{a.s.}(1)$ and O_p are respectively: a term converging in probability to zero, a term converging almost surely (*a.s.*) to zero and a term bounded in probability as $n \rightarrow \infty$.

2. The *INGAR* model: a general class of count time series models

Let $\theta_0 \in \Theta \subset \mathbb{R}^m$ ($m \in \mathbb{N}^*$) be an unknown "true" parameter and consider a measurable positive real-valued function $\lambda : \mathbb{N}^\infty \times \Theta \rightarrow (0, \infty)$. A general class of count time series models, as proposed by Ahmad and Francq (2016), is given through an observable integer-valued stochastic process $\{X_t, t \in \mathbb{Z}\}$, which is defined on (Ω, \mathcal{F}, P) with conditional expectation specified as follows

$$E(X_t/\mathcal{F}_{t-1}) = \lambda(X_{t-1}, X_{t-2}, \dots; \theta_0) := \lambda_t(\theta_0) := \lambda_t, \quad t \in \mathbb{Z}, \quad (2.1)$$

where $\mathcal{F}_t \subset \mathcal{F}$ is the σ -algebra generated by $\{X_t, X_{t-1}, \dots\}$. Letting

$$e_t := e_t(\theta_0) = X_t - E(X_t/\mathcal{F}_{t-1}),$$

model (2.1), which is defined through the conditional mean representation (2.1), may also be written in the following stochastic difference equation (or in innovation form, cf. Grunwald et al, 2000)

$$X_t = \lambda(X_{t-1}, X_{t-2}, \dots; \theta_0) + e_t, \quad t \in \mathbb{Z}. \quad (2.2)$$

Equation (2.2), which is driven by the $\{\mathcal{F}_t, t \in \mathbb{Z}\}$ -martingale difference $\{e_t, t \in \mathbb{Z}\}$, appears to be an infinite generalized autoregression with integer-valued solution $\{X_t, t \in \mathbb{Z}\}$. The term "generalized" refers to the general form of the function λ , which may be linear or nonlinear. This is why the model is termed *INteger Generalized AutoRegression (INGAR)*. In fact, the *INGAR* model (2.1)-(2.2) is quite general and encompasses many important classes of integer-valued time series models such as the (stable) *Poisson INGARCH* model (Heinen, 2003; Ferland et al, 2006), the general Poisson autoregression (Doukhan et al, 2012; Doukhan and Kengne, 2015; Kengne, 2015), the stable negative binomial *INGARCH* model (Zhu, 2011; Christou and Fokianos, 2014; Davis and Liu, 2016; Diop and Kengne, 2016) and the *INAR* model (Al-Osh and Alzaid, 1987).

Note that the generality of the *INGAR* model (2.1) stems not only from the general form of the function $\lambda(\cdot)$ (see also Doukhan and Wintenberger, 2008), but also from the fact that apart from the conditional mean, no other specification concerning the conditional distribution of the process $\{X_t, t \in \mathbb{N}\}$ is required. However, it is sometimes important to specify a *link function* relating the conditional variance and the conditional mean of model (2.1), i.e.

$$\text{Var}(X_t/\mathcal{F}_{t-1}) = l(E(X_t/\mathcal{F}_{t-1})), \quad (2.3)$$

where $l : (0, \infty) \rightarrow (0, \infty)$ is a positive real function. In the literature on *generalized linear models* (e.g. Nelder and Wedderburn, 1972; McCullagh and Nelder, 1989), such a link function is also called the *GLM nominal variance assumption* and is induced either by the conditional distribution of the model when it is fully specified or by the structure of the model. For example, when the conditional distribution corresponding to (2.1) is Poissonian with parameter λ_t , which reduces to a special case of the general Poisson autoregression proposed by Doukhan et al (2012), the Poisson *GLM* link function for model (2.1) is given by the linear form $l(x) = x$. A more general linear link function

$$l(x) = \left(1 + \frac{1}{r_0}\right)x, \text{ for some } r_0 > 0,$$

is induced by the conditional negative binomial-*I* conditional distribution, i.e. $X_t/\mathcal{F}_{t-1} \sim$

$\mathcal{NB}\left(r_0\lambda_t, \frac{r_0\lambda_t}{r_0\lambda_t+\lambda_t}\right)$, $r_0 > 0$ (see Cameron and Trivedi, 1986 and Section 4.1 below). Furthermore, the link function implied by the negative binomial-II conditional distribution, that is $\mathcal{NB}\left(r_0, \frac{r_0}{r_0+\lambda_t}\right)$, is given by

$$l(x) = x\left(1 + x\frac{1}{r_0}\right), \quad r_0 > 0. \quad (2.4)$$

When $r_0 = 1$, we find the link function corresponding to the Geometric distribution. On the other hand, a link function may be exhibited even when the conditional distribution of the model is misspecified. In Section 4.1.4 we will see that the *GLM* link function for the *INAR*(1) model is always an affine function regardless of the conditional distribution of this model.

In this paper we are interested in estimating the unknown conditional mean parameter θ_0 using a series X_1, X_2, \dots, X_n ($n \in \mathbb{N}^*$) generated from (2.1). When a negative binomial-II link function like (2.3)-(2.4) is specified we are also interested in estimating the dispersion parameter r_0 . In fact, two instances of (2.1) are considered:

Case 1: Only the conditional mean (2.1) is specified so that we only have to estimate the conditional mean parameter θ_0 .

Case 2: Equation (2.1) and the negative binomial-II *GLM* link function (2.3)-(2.4) are both specified so we have to estimate both θ_0 and r_0 .

A particularly important instance of **Case 2** appears when the full conditional distribution of the model is specified as a negative binomial-II one, i.e. $X_t/\mathcal{F}_{t-1} \sim \mathcal{NB}\left(r_0, \frac{r_0}{r_0+\lambda_t}\right)$, where a special case is the negative binomial-II *INGARCH* model (see Davis and Liu, 2016; Zhu, 2011; Christou and Fokianos, 2014 and Section 4.1.3 below).

For our estimation purposes we make the following regularity assumption on (2.1).

A0 *The process $\{X_t, t \in \mathbb{Z}\}$ given by (2.1) is strictly stationary and ergodic.*

For some particular classes of (2.1) like the *INGARCH* and *INAR* models, assumption **A0** may be expressed more explicitly as a stability condition on θ_0 (see Ahmad and Francq, 2016 and Section 4.1 below). Furthermore, when the conditional distribution of (2.1) is Poissonian, Doukhan et al (2012) provided general conditions on the function λ in (2.1) for strict stationarity and ergodicity of the model.

Now, given a generic parameter $\theta \in \Theta$, the conditional mean function given by

$$\lambda(X_{t-1}, X_{t-2}, \dots; \theta) := \lambda_t(\theta), \quad t \in \mathbb{N},$$

clearly coincides with the conditional mean in (2.1) when $\theta = \theta_0$. It is unobservable because of the unobservable values $X_0, X_{-1}, X_{-2}, \dots$. For any arbitrary fixed initial values $\tilde{X}_0, \tilde{X}_{-1}, \tilde{X}_{-2}, \dots$, let

$$\tilde{\lambda}_t(\theta) = \lambda\left(X_{t-1}, X_{t-2}, \dots, X_1, \tilde{X}_0, \tilde{X}_{-1}, \dots; \theta\right), \quad t \in \mathbb{N}^*,$$

be an observable proxy for $\lambda_t(\theta)$. The latter approximation serves in calculating various *QMLE*-type of θ_0 we intend to study below.

3. Negative binomial *QMLE*'s of the *INGAR* model

This Section considers two negative binomial *QMLE*'s of the *INGAR* model (2.1) given a realization X_1, \dots, X_n of (2.1). To describe these estimates consider **Case 2** of model (2.1)-(2.4) with unknown parameters θ_0 and r_0 . For any generic $\theta \in \Theta$ and $r > 0$, the negative binomial (log) likelihood, $\tilde{L}_{NB}(\theta, r)$, based on the negative binomial-II conditional distribution, $\mathcal{NB}\left(r, \frac{r}{r+\lambda_t(\theta)}\right)$, is given by

$$\begin{aligned} \tilde{L}_{NB}(\theta, r) &= \frac{1}{n} \sum_{t=1}^n \tilde{l}_t(\theta, r), & (3.1) \\ \text{with } \tilde{l}_t(\theta, r) &= r \log\left(\frac{r}{r+\lambda_t(\theta)}\right) + X_t \log\left(\frac{\tilde{\lambda}_t(\theta)}{r+\tilde{\lambda}_t(\theta)}\right) + \frac{\Gamma(X_t+r)}{X_t! \Gamma(r)}. \end{aligned}$$

A negative binomial quasi-maximum likelihood estimate (*NB-QMLE*) of (θ_0, r_0) is a maximizer of $\tilde{L}_{NB}(\theta, r)$ over $\theta \in \Theta$ and $r > 0$.

Note, however, that $\tilde{l}_t(\theta, r)$ given by (3.1) is not a member of the linear exponential family in the sense of *Gourieroux et al (1984a)*. So any maximizer of (3.1) might be inconsistent under misspecification of the true conditional distribution of model (2.1), which constitutes a serious limitation. In lieu of maximizing directly (3.1) and picking up the estimate component corresponding to θ_0 , we may consider a four-stage approach which is rather robust to misspecification of the true conditional distribution and which consists in:

i) Fixing r in (3.1) arbitrarily to any known positive number, say $r^* > 0$, and estimating θ_0 while maximizing (3.1) with respect to θ , giving a first-step *QMLE* $\hat{\theta}_{r^*}$.

ii) Estimating r_0 under the *GLM* link function (2.3)-(2.4) using a weighted least squares estimate \hat{r}_1 while replacing θ_0 in the weight by its *QMLE*, $\hat{\theta}_{r^*}$, obtained in *i*).

iii) Re-estimating θ_0 by maximizing a variation of (3.1) obtained while replacing r by the estimate \hat{r}_1 obtained in *ii*), giving $\hat{\theta}_{\hat{r}_1}$.

iv) Re-estimating r_0 using the same weighted least squares method in *ii*) but while replacing θ_0 by $\hat{\theta}_{\hat{r}_1}$ obtained in *iii*).

For a similar approach in the context of static count regression see *Gourieroux et al* (1984a, 1984b) and *Wooldridge* (1997, 2002). In the above first and third steps, maximization of (3.1) is carried out with respect to θ letting r fixed. So the last term in (3.1) may be left out and (3.1) is simply replaced by the following "*profile negative binomial likelihood*"

$$\tilde{L}_{n,r}(\theta) = \frac{1}{n} \sum_{t=1}^n \tilde{l}_{t,r}(\theta) \quad \text{with} \quad \tilde{l}_{t,r}(\theta) = r \log \left(\frac{r}{r + \lambda_t(\theta)} \right) + X_t \log \left(\frac{\lambda_t(\theta)}{r + \lambda_t(\theta)} \right). \quad (3.2)$$

It should be noted that $\tilde{l}_{t,r}(\theta)$ in (3.2) rather belongs to the linear exponential family. Therefore any maximizer of (3.2) with respect to θ would be robust to misspecification of the conditional distribution, whenever correctly specifying the conditional mean like (2.1). It turns out that for any fixed $r > 0$, $\tilde{L}_{n,r}(\theta)$ is the *Wedderburn* quasi-likelihood function (*Wedderburn*, 1974) based on the negative binomial *GLM* link function (2.3)-(2.4) (with r in place of r_0).

On the other hand, considering **Case 1** of model (2.1) where only the conditional mean is specified, then only θ_0 has to be estimated and r in (3.1) can be set to any positive real value. So maximization of (3.1) will only be done with respect to θ , which again amounts to maximizing (3.2). In summary, for both **Case 1** and **Case 2**, we have to maximize the profile (or Quasi-) likelihood (3.2) with respect to θ .

In the rest of this Section we shall study asymptotics of two *QML*-type estimates that maximize (3.2) over $\theta \in \Theta$. Subsection 3.1 examines consistency and asymptotic normality of a maximizer of (3.2) for arbitrarily fixed $r > 0$. The resulting estimate will be called

profile (or marginal) negative binomial quasi-maximum likelihood estimate (*pNB-QMLE*). In Subsection 3.2, consistency and asymptotic normality of the four-stage estimate (see *i*)-*iv*) above) are established assuming the nominal *GLM* link function (2.3)-(2.4) for an unknown $r_0 > 0$.

3.1. Profile negative binomial *QMLE*

Consider **Case 1** of the *INGAR* model where only (2.1) is required. A *profile negative binomial quasi-maximum likelihood estimate (pNB-QMLE)* of θ_0 is any measurable solution of the following problem

$$\hat{\theta}_r = \arg \max_{\theta \in \Theta} \left(\tilde{L}_{n,r}(\theta) \right), \quad (3.3)$$

for some Θ and some fixed known $r > 0$, where $\tilde{L}_{n,r}(\theta)$ is given by (3.2). When $r = 1$, $\hat{\theta}_1$ reduces to the geometric *QMLE* (*G-QMLE*) studied by Aknouche and Bendjeddou (2017). The choice of $(\tilde{X}_0, \tilde{X}_{-1}, \dots)$ is of no asymptotic importance, but may influence the accuracy of estimate in finite samples. In general, one assumes that $\tilde{X}_0 = x, \tilde{X}_{-1} = x, \dots$ with x depending on the function λ or on the observations (see Ahmad and Francq, 2016). To study consistency of the *pNB-QMLE*, $\hat{\theta}_r$, we need the following assumptions:

A1 $\theta \mapsto \lambda_t(\theta)$ is *a.s. continuous*; $\lambda_t(\theta) > c$ and $\tilde{\lambda}_t(\theta) > c$, *a.s. for some* $c > 0$.

A2 $a_t \xrightarrow[t \rightarrow \infty]{a.s.} 0$ and $a_t X_t \xrightarrow[t \rightarrow \infty]{a.s.} 0$ where $a_t = \sup_{\theta \in \Theta} \left| \tilde{\lambda}_t(\theta) - \lambda_t(\theta) \right|$.

A3 $E(X_t^\delta) < \infty$ for some $\delta > 1$.

A4 $\lambda_t(\theta) = \lambda_t(\theta_0)$ *a.s. if and only if* $\theta = \theta_0$.

A5 Θ is compact.

Assumptions **A1-A5** are standard and may be made more explicit for some particular models of (2.1). Similar assumptions were considered by Ahmad and Francq (2016) for the strong consistency of their *P-QMLE*.

Theorem 3.1 *Under (2.1) and A0-A5,*

$$\hat{\theta}_r \xrightarrow[n \rightarrow \infty]{a.s.} \theta_0, \quad \text{for all } r > 0. \quad (3.4)$$

The latter result shows that, like the P - $QMLE$, the pNB - $QMLE$ is robust to misspecification of the true conditional distribution where only (2.1) has to be specified. This is not surprising as the profile negative binomial log-likelihood (3.2) belongs to the linear exponential family (see *Gourieroux et al, 1984a*).

We now examine the asymptotic normality of the pNB - $QMLE$. Let $l_{t,r}(\theta)$ be defined in the same way as $\tilde{l}_{t,r}(\theta)$ in (3.2) with $\lambda_t(\theta)$ in place of $\tilde{\lambda}_t(\theta)$ and set

$$L_{n,r}(\theta) = \frac{1}{n} \sum_{t=1}^n l_{t,r}(\theta).$$

Consider the following supplementary assumptions.

A6 The variables c_t , $c_t X_t$, $a_t d_t$, $a_t d_t X_t$ and $b_t d_t X_t$ are of order $O(t^{-\tau})$ a.s. for some $\tau > 1/2$, where $b_t = \sup_{\theta \in \Theta} \left| \tilde{\lambda}_t^2(\theta) - \lambda_t^2(\theta) \right|$, $c_t = \sup_{\theta \in \Theta} \left\| \frac{\partial(\tilde{\lambda}_t(\theta) - \lambda_t(\theta))}{\partial \theta} \right\|$ and

$$d_t = \sup_{\theta \in \Theta} \max \left(\left\| \frac{1}{\tilde{\lambda}_t(\theta)(r + \tilde{\lambda}_t(\theta))} \frac{\partial \tilde{\lambda}_t(\theta)}{\partial \theta} \right\|, \left\| \frac{1}{\lambda_t(\theta)(r + \lambda_t(\theta))} \frac{\partial \lambda_t(\theta)}{\partial \theta} \right\| \right).$$

A7 The true θ_0 belongs to the interior of Θ .

A8 The conditional variance $v_t(\theta_0) := \text{Var}(X_t / \mathcal{F}_{t-1}) = E(X_t^2 / \mathcal{F}_{t-1}) - \lambda_t^2(\theta_0)$ is a.s. finite.

A9 The derivatives $\frac{\partial^2 \lambda_t(\theta)}{\partial \theta \partial \theta'}$ and $\frac{\partial^2 \tilde{\lambda}_t(\theta)}{\partial \theta \partial \theta'}$ exist and are continuous, the matrices

$$I_r = E \left(\frac{v_t(\theta_0)}{\lambda_t^2(\theta_0)(r + \lambda_t(\theta_0))^2} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right) \text{ and } J_r = E \left(\frac{1}{\lambda_t(\theta_0)(r + \lambda_t(\theta_0))} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right),$$

are finite, and J_r is nonsingular for all $r > 0$.

A10 There is a neighborhood $V(\theta_0)$ of θ_0 such that $E \left(\sup_{\theta \in V(\theta_0)} \left\| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta \partial \theta'} \right\| \right) < \infty$ for all $r > 0$.

Like consistency conditions, assumptions **A6**-**A10** may be made more explicit for specific cases of (2.1). Now we have the following asymptotic normality result.

Theorem 3.2 Under (2.1) and **A0**-**A10**,

$$\sqrt{n} \left(\hat{\theta}_r - \theta_0 \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N \left(0, J_r^{-1} I_r J_r^{-1} \right) \text{ for all } r > 0. \quad (3.5)$$

Some remarks are in order:

- When the conditional distribution of the data generating process (2.1) is negative binomial-II with parameters r_0 and $\frac{r_0}{r_0+\lambda_t}$, i.e. $X_t/\mathcal{F}_{t-1} \sim \mathcal{NB}\left(r_0, \frac{r_0}{r_0+\lambda_t}\right)$, then (3.5) holds with $I_r = \frac{1}{r_0} E\left(\frac{r_0+\lambda_t(\theta_0)}{\lambda_t(\theta_0)(r+\lambda_t(\theta_0))^2} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'}\right)$. In particular, when r in (3.2)-(3.3) coincides with the "true" r_0 in (2.3)-(2.4), then $\hat{\theta}_{r_0}$ becomes the maximum likelihood estimate (*MLE*), which is then asymptotically efficient with

$$I_{r_0} = \frac{1}{r_0} J_{r_0}.$$

Therefore, (3.5) becomes

$$\sqrt{n} \left(\hat{\theta}_{r_0} - \theta_0\right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N\left(0, \frac{1}{r_0} J_{r_0}^{-1}\right). \quad (3.6)$$

- A weaker result, which does not require specifying the full conditional distribution is that under the following more general *negative binomial-II GLM link function*

$$\text{Var}(X_t/\mathcal{F}_{t-1}) = \delta^2 E(X_t/\mathcal{F}_{t-1}) \left(1 + \frac{1}{r_0} E(X_t/\mathcal{F}_{t-1})\right) \text{ for some } \delta^2 > 0, r_0 > 0, \quad (3.7)$$

which generalizes (2.3)-(2.4), $\hat{\theta}_{r_0}$ is asymptotically efficient in the class of all *QMLE*'s in the linear exponential family (see e.g. *Gourieroux et al (1984a, 1984b)* and *Wooldridge (1997)* in the context of *QML* inference for static integer-valued regression models). In that case we have

$$\sqrt{n} \left(\hat{\theta}_{r_0} - \theta_0\right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N\left(0, \delta^2 J_{r_0}^{-1}\right). \quad (3.8)$$

Note, however, that r_0 is generally unknown and (3.6) and (3.8) does not hold unless r_0 is consistently estimated under (3.7) as we will see in the following subsection.

Now an important issue is to estimate the asymptotic variance of the *pNB-QMLE*. Similarly to *Ahmad and Francq (2016)*, a consistent estimate of the asymptotic variance $J_r^{-1} I_r J_r^{-1}$ of the *pNB-QMLE*, $\hat{\theta}_r$, is $\hat{J}_r^{-1} \hat{I}_r \hat{J}_r^{-1}$ with

$$\hat{I}_r = \frac{1}{n} \sum_{t=1}^n \left(\frac{X_t - \tilde{\lambda}_t(\hat{\theta}_r)}{\tilde{\lambda}_t(\hat{\theta}_r)(r + \tilde{\lambda}_t(\hat{\theta}_r))} \right)^2 \frac{\partial \tilde{\lambda}_t(\hat{\theta}_r)}{\partial \theta} \frac{\partial \tilde{\lambda}_t(\hat{\theta}_r)}{\partial \theta'}. \quad (3.9)$$

$$\hat{J}_r = \frac{1}{n} \sum_{t=1}^n \frac{1}{\tilde{\lambda}_t(\hat{\theta}_r)(r + \tilde{\lambda}_t(\hat{\theta}_r))} \frac{\partial \tilde{\lambda}_t(\hat{\theta}_r)}{\partial \theta} \frac{\partial \tilde{\lambda}_t(\hat{\theta}_r)}{\partial \theta'}. \quad (3.10)$$

3.2. Two-stage negative binomial QMLE

Consider **Case 2** of model (2.1)-(2.4) for which we study the aforementioned four-stage procedure i)-iv). Here, the second and fourth steps are described in more details. Under the GLM assumption (2.3)-(2.4), if we set

$$u_t = (X_t - \lambda_t)^2 - E((X_t - \lambda_t)^2 / \mathcal{F}_{t-1}) = (X_t - \lambda_t)^2 - \left(1 + \frac{1}{r_0} \lambda_t\right) \lambda_t,$$

then $E(u_t / \mathcal{F}_{t-1}) = 0$ and

$$\frac{(X_t - \lambda_t(\theta_0))^2 - \lambda_t(\theta_0)}{\lambda_t^2(\theta_0)} = \gamma_0 + \frac{u_t}{\lambda_t^2(\theta_0)}, \quad (3.11)$$

where $\gamma_0 = \frac{1}{r_0}$. Regression (3.11) is not ready to be used to estimate γ_0 since its regressand, $\frac{(X_t - \lambda_t(\theta_0))^2 - \lambda_t(\theta_0)}{\lambda_t^2(\theta_0)}$, depends on the unknown θ_0 and is then unobservable. If a consistent estimate of θ_0 , say $\hat{\theta}$, is available then we may form the following modified (observable-regressand) regression

$$\frac{(X_t - \hat{\lambda}_t)^2 - \hat{\lambda}_t}{\hat{\lambda}_t^2} = \gamma_0 + \frac{u_t}{\hat{\lambda}_t^2}, \quad (3.12)$$

from which a consistent estimate of r_0 is \hat{r} , the inverse of the weighted least squares estimate $\hat{\gamma}$ of γ_0 given by

$$\hat{r} = \left(\frac{1}{n} \sum_{t=1}^n \frac{((X_t - \hat{\lambda}_t)^2 - \hat{\lambda}_t)}{\hat{\lambda}_t^2} \right)^{-1}, \quad \hat{\gamma} = \hat{r}^{-1}, \quad (3.13)$$

where $\hat{\lambda}_t = \tilde{\lambda}_t(\hat{\theta})$. Note that the estimate \hat{r} we use here is a dynamic *INGAR* adaptation of the estimate proposed by *Gourieroux et al (1984b)* in the context of static negative binomial regression. Now, with (3.13) the following algorithm summarizes the four-stage approach i)-iv) described above.

Algorithm 3.1 (Two-stage NB-QMLE)

Given a fixed known $r^* > 0$, the two-stage NB-QMLE of (θ_0, r_0) in (2.1)-(2.4) consists of a quadruple $(\hat{\theta}_{r^*}, \hat{r}_1, \hat{\theta}_{\hat{r}_1}, \hat{r}_2)$, which is described by the following steps:

Step 1 Set $\hat{\theta}_{r^*} = \arg \max_{\theta \in \Theta} \tilde{L}_{n,r^*}(\theta)$, a solution to the problem (3.3) while replacing r par r^* . Let $\hat{\lambda}_{1t} = \tilde{\lambda}_t(\hat{\theta}_{r^*})$, $(1 \leq t \leq n)$.

Step 2 Set $\hat{\gamma}_1 = \frac{1}{n} \sum_{t=1}^n \frac{(X_t - \hat{\lambda}_{1t})^2 - \hat{\lambda}_{1t}}{\hat{\lambda}_{1t}^2}$ and $\hat{r}_1 = \hat{\gamma}_1^{-1}$.

Step 3 Let $\hat{\theta}_{\hat{r}_1} = \arg \max_{\theta \in \Theta} \tilde{L}_{n, \hat{r}_1}(\theta)$ be a solution of the problem (3.3) while replacing the generic r by \hat{r}_1 . Get $\hat{\lambda}_{2t} = \tilde{\lambda}_t(\hat{\theta}_{\hat{r}_1})$, $(1 \leq t \leq n)$.

Step 4 Set $\hat{\gamma}_2 = \frac{1}{n} \sum_{t=1}^n \frac{(X_t - \hat{\lambda}_{2t})^2 - \hat{\lambda}_{2t}}{\hat{\lambda}_{2t}^2}$ and $\hat{r}_2 = \hat{\gamma}_2^{-1}$.

To get asymptotic properties of the quadruple $(\hat{\theta}_{r^*}, \hat{r}_1, \hat{\theta}_{\hat{r}_1}, \hat{r}_2)$, note first that $\hat{\theta}_{r^*}$ is no other than the profile *NB-QMLE* proposed in Section 3.1 whose asymptotic properties were given by Theorem 3.1 and Theorem 3.2. So it remains to study the triple $(\hat{r}_1, \hat{\theta}_{\hat{r}_1}, \hat{r}_2)$, asymptotic properties of which are given by the following result.

Theorem 3.3 Under (2.1), (2.3)-(2.4) and **A0-A10**,

$$\hat{r}_1 \xrightarrow[n \rightarrow \infty]{a.s.} r_0, \quad (3.14a)$$

$$\sqrt{n}(\hat{\gamma}_1 - \gamma_0) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N\left(0, E\left(\frac{\left((X_t - \lambda_t(\theta_0))^2 - (\lambda_t(\theta_0) + \frac{1}{r_0} \lambda_t^2(\theta_0))\right)^2}{\lambda_t^4(\theta_0)}\right)\right), \hat{\gamma}_2 \stackrel{A.D.}{=} \hat{\gamma}_1, \quad (3.14b)$$

$$\hat{\theta}_{\hat{r}_1} \xrightarrow[n \rightarrow \infty]{a.s.} \theta_0, \quad (3.14c)$$

$$\sqrt{n}(\hat{\theta}_{\hat{r}_1} - \theta_0) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N\left(0, \frac{1}{r_0} J_{r_0}^{-1}\right), \quad (3.14d)$$

where $\stackrel{A.D.}{=}$ stands for equality in asymptotic distribution.

A few broad conclusions can be drawn.

- Strong consistency of $\hat{\theta}_{\hat{r}_1}$ directly follows from strong consistency of $\hat{\theta}_r$ (for all $r > 0$) and \hat{r}_1 .

- The third-step estimate $\hat{\theta}_{\hat{r}_1}$ is clearly more asymptotically efficient than the first-step estimate $\hat{\theta}_{r^*}$.

- No supplementary moment assumptions apart those required by **A0-A10** are needed for consistency and asymptotic normality of $\hat{\gamma}_1$. Other methods for estimating γ are available (e.g. Christou and Fokianos, 2014), but they may involve higher order moment conditions.

- Asymptotic distribution of \hat{r}_1 is a *reciprocal normal distribution*, which is bimodal and has no first moment.

- Since $\hat{\gamma}_1$ and $\hat{\gamma}_2$ have the same asymptotic distribution, **Step 4** is optional and may be left out. However, for finite-samples considerations, we keep it here because it allows to re-estimate r_0 using $\hat{\lambda}_{2t}$ and hence $\hat{\theta}_{\hat{r}_1}$, which is more asymptotically efficient than $\hat{\theta}_r$ we used

in **Step 2**.

- A consistent estimate of the asymptotic variance $\frac{1}{r_0} J_{r_0}^{-1}$ of the third-step estimate, $\widehat{\theta}_{\widehat{r}_1}$, is

$$\frac{1}{\widehat{r}_2} \widehat{J}_{\widehat{r}_2}^{-1}, \quad (3.15)$$

where \widehat{J}_r is given by (3.10). Note that since here $I_r = J_r$, then (3.9) may also be used.

- A consistent estimate of the asymptotic variance of $\widehat{\gamma}_2$ in (3.14b) is

$$\frac{1}{n} \sum_{t=1}^n \frac{\left((X_t - \lambda_t(\widehat{\theta}_{\widehat{r}_1}))^2 - (\lambda_t(\widehat{\theta}_{\widehat{r}_1}) + \frac{1}{r_0} \lambda_t^2(\widehat{\theta}_{\widehat{r}_1})) \right)^2}{\lambda_t^4(\widehat{\theta}_{\widehat{r}_1})}. \quad (3.16)$$

- The outputs of the *2SNB-QMLE* method are $\widehat{r}_2 = (\widehat{\gamma}_2)^{-1}$ and $\widehat{\theta}_{\widehat{r}_1}$.

4. Comparison between the *NB-QMLE*'s and the *Poisson QMLE*

For the conditional mean parameter θ_0 of the *INGAR* model (2.1), Ahmad and Francq (2016) proposed a Poisson *QMLE* (*P-QMLE*), which is defined as a measurable solution to the following problem

$$\widehat{\theta}_P = \arg \max_{\theta \in \Theta} \left(\widetilde{L}_{P,n}(\theta) \right), \quad (4.1a)$$

where

$$\widetilde{L}_{P,n}(\theta) = \frac{1}{n} \sum_{t=1}^n \left(-\widetilde{\lambda}_t(\theta) + X_t \log \left(\widetilde{\lambda}_t(\theta) \right) \right). \quad (4.1b)$$

Under similar assumptions to **A0-A10**, Ahmad and Francq (2016) showed consistency and asymptotic normality of the *P-QMLE* with

$$\sqrt{n} \left(\widehat{\theta}_P - \theta_0 \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N \left(0, J_P^{-1} I_P J_P^{-1} \right), \quad (4.2)$$

where $I_P = E \left(\frac{v_t(\theta_0)}{\lambda_t^2(\theta_0)} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right)$ and $J_P = E \left(\frac{1}{\lambda_t(\theta_0)} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right)$. One important property of the *P-QMLE* is its robustness to misspecification of the true conditional distribution of model (2.1). In this Section we will compare the *NB-QMLE*'s and *P-QMLE* with regard to asymptotic relative efficiency for some well-known specific cases of (2.1) and also on some

particular *GLM* link functions of (2.3). We also compare these estimates in finite samples through some simulation experiments.

4.1. Comparison on asymptotic relative efficiency for specific models

4.1.1. The Poisson *INGARCH* model (Poisson autoregression)

The Poisson integer *GARCH* (*INGARCH* (p, q)) process $\{X_t, t \in \mathbb{Z}\}$, as proposed by Heinen (2003) and Ferland et al (2006), is defined to have a Poisson conditional distribution

$$X_t / \mathcal{F}_{t-1} \sim \mathcal{P}(\lambda_t), \quad t \in \mathbb{Z}, \quad (4.3a)$$

with conditional mean $\lambda_t = \lambda_t(\theta_0)$ specified as follows

$$\lambda_t(\theta_0) = \omega_0 + \sum_{i=1}^q \alpha_{0i} X_{t-i} + \sum_{j=1}^p \beta_{0j} \lambda_{t-j}(\theta_0), \quad (4.3b)$$

where $\theta_0 = (\omega_0, \alpha_{01}, \dots, \alpha_{0q}, \beta_{01}, \dots, \beta_{0p})'$ is such that $\omega_0 > 0$, $\alpha_{0i} \geq 0$, $\beta_{0j} \geq 0$. Ferland et al (2006) showed that under the following stability condition

$$\sum_{i=1}^q \alpha_{0i} + \sum_{j=1}^p \beta_{0j} < 1, \quad (4.4)$$

the process $\{X_t, t \in \mathbb{Z}\}$ given by (4.3) is strictly stationary and ergodic (see also Douc et al, 2013; Gonçalves et al, 2015; Davis and Liu, 2016). Under $\sum_{j=1}^p \beta_{0j} < 1$, the conditional mean λ_t of the process may be written in the form (2.1); hence model (4.3) is a special case of (2.1). In particular, it is characterized by the following "identity" *GLM* link function

$$\text{Var}(X_t / \mathcal{F}_{t-1}) = E(X_t / \mathcal{F}_{t-1}). \quad (4.5)$$

On the other hand, the *P-QMLE* of (4.3) reduces to the maximum likelihood estimate, which is asymptotically efficient and is then more asymptotically efficient than the *pNB-QMLE*. In particular $I_P = J_P$ follows from (4.2) and (4.5). Furthermore, assumptions **A1-A10** simplify in the case of the Poisson *INGARCH* model (4.3) as in Ahmad and Francq

(2016). For instance, I_r defined in **A9** reduces to $I_r = E \left(\frac{1}{\lambda_t(\theta_0)(r+\lambda_t(\theta_0))^2} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right)$. Note finally that the *2SNB-QMLE* given by Section 3.2 is ill-defined in the present Poisson *INGARCH* case since the **Step 2** of Algorithm 3.1 is derived under the *GLM* assumption (2.3)-(2.4), which is different from the link function (4.5) characterizing the Poisson *INGARCH* model (4.3).

4.1.2. The negative binomial-*I* *INGARCH* model

Here we follow Cameron and Trivedi (1986, 2013) who proposed the negative binomial- K conditional distribution in the context of static integer-valued regression. We say that $\{X_t, t \in \mathbb{Z}\}$ is a negative binomial- K *INGARCH* (*NB-K-INGARCH* (p, q)) process if its conditional distribution is a negative binomial one,

$$X_t/\mathcal{F}_{t-1} \sim \mathcal{NB}(r_t, \pi_t), \quad t \in \mathbb{Z}, \quad (4.6a)$$

with parameters

$$r_t = r_0 \lambda_t^{2-K} \quad \text{and} \quad \pi_t = \frac{r_0 \lambda_t^{2-K}}{r_0 \lambda_t^{2-K} + \lambda_t}, \quad (4.6b)$$

where $K \in \mathbb{Z}$, $r_0 > 0$ and $\lambda_t = \lambda_t(\theta_0)$ satisfies the *INGARCH* (p, q) representation (4.3b). Model (4.6) in which $E(X_t/\mathcal{F}_{t-1}) = \lambda_t$ satisfies the following *GLM* link function

$$\text{Var}(X_t/\mathcal{F}_{t-1}) = E(X_t/\mathcal{F}_{t-1}) \left(1 + \frac{1}{r_0} (E(X_t/\mathcal{F}_{t-1}))^{K-1} \right), \quad (4.7)$$

which implies the process is overdispersed since $\text{Var}(X_t/\mathcal{F}_{t-1}) > E(X_t/\mathcal{F}_{t-1})$.

Now consider the *NB-I-INGARCH* (p, q) model corresponding to $K = 1$, i.e.

$$X_t/\mathcal{F}_{t-1} \sim \mathcal{NB} \left(r_0 \lambda_t, \frac{r_0 \lambda_t}{r_0 \lambda_t + \lambda_t} \right) \equiv \mathcal{NB} \left(r_0 \lambda_t, \frac{r_0}{r_0 + 1} \right), \quad (4.8a)$$

for which (4.7) reduces to the following linear form

$$\text{Var}(X_t/\mathcal{F}_{t-1}) = \left(1 + \frac{1}{r_0} \right) E(X_t/\mathcal{F}_{t-1}), \quad (4.8b)$$

which is a strict generalization of the Poisson *GLM* condition (4.5) implied by the Poisson *INGARCH* model. In view of (4.5) and (4.8b), the *NB-I-INGARCH* model (4.8a) presents

some similarities with the Poisson *INGARCH* model (4.3). Indeed, it is straightforward to show that the *NB-I-INGARCH* is strictly stationary with finite second moment and ergodic under the same stationarity condition (4.4) for the Poisson *INGARCH* model. Moreover, from (4.2) and (4.8b), it follows under similar assumptions to **A0-A10** (see Ahmad and Francq, 2016) that

$$\sqrt{n} \left(\widehat{\theta}_P - \theta_0 \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N \left(0, \left(1 + \frac{1}{r_0} \right) \left(E \left(\frac{1}{\lambda_t(\theta_0)} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right) \right)^{-1} \right).$$

A more important result is that under the Poisson *GLM* condition (4.8b), it is easily seen that the *P-QMLE* is asymptotically efficient in the class of all *QMLE*'s belonging to the linear exponential family. So the *P-QMLE* is more asymptotically efficient than the *pNB-QMLE* (see Gouriéroux et al, (1984a, 1984b) in the case of static integer-valued regression models where adaptation to the present dynamic case is trivial). In fact, under **A0-A10** and in view of (3.5) and (4.8b), the asymptotic variance of the *pNB-QMLE*, $\widehat{\theta}_r$, is in "sandwich" form with

$$I_r = \left(1 + \frac{1}{r_0} \right) E \left(\frac{1}{\lambda_t(\theta_0)(r + \lambda_t(\theta_0))^2} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right).$$

Note finally that as in the Poisson *INGARCH* case, the *2SNB-QMLE* given by Section 3.2 is ill-defined.

4.1.3. The negative binomial-II *INGARCH* model

Consider the *NB-II-INGARCH* (p, q) model corresponding to (4.6) with $K = 2$, i.e.

$$X_t / \mathcal{F}_{t-1} \sim \mathcal{NB} \left(r_0, \frac{r_0}{r_0 + \lambda_t} \right), \quad (4.9)$$

where $r_0 > 0$ and λ_t is given by (4.3b). Model (4.9) has been considered by Zhu (2011), Davis and Liu (2016) and Christou and Fokianos (2014) who gave for $p = q = 1$ the following strict stationarity condition

$$\alpha_0^2 \left(1 + \frac{1}{r_0} \right) + 2\alpha_0\beta_0 + \beta_0^2 < 1,$$

with finite second moment. The formulation of Zhu (2011) is in fact,

$$X_t / \mathcal{F}_{t-1} \sim \mathcal{NB} \left(r_0, \frac{1}{1 + \mu_t} \right), \quad (4.10)$$

where $r_0 \in \mathbb{N}^*$ is restricted to be a positive integer and μ_t satisfying (4.3b). However, the latter may be written in the form (4.9) while taking $\lambda_t = \frac{\mu_t}{r_0}$. For model (4.9), the link function (4.7) clearly reduces to the negative binomial-II *GLM* condition (3.7) (with $\delta^2 = 1$), i.e.

$$\text{Var}(X_t/\mathcal{F}_{t-1}) = E(X_t/\mathcal{F}_{t-1}) \left(1 + \frac{1}{r_0} E(X_t/\mathcal{F}_{t-1})\right), \quad r_0 > 0, \quad (4.11)$$

under which the *2SNB-QMLE* is derived. Christou and Fokianos (2014) used the Poisson *QMLE* for estimating model (4.9) and proved its consistency and asymptotic normality with asymptotic variance in sandwich form like (4.2) where, in view of (4.4),

$$I_P = \frac{1}{r_0} E \left(\frac{(r_0 + \lambda_t(\theta_0))}{\lambda_t(\theta_0)} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right).$$

Ahmad and Francq (2016) showed how their assumptions of consistency and asymptotic normality for the general model (2.1) simplify for model (4.9).

Concerning the *pNB-QMLE* it is clear that

$$I_r = \frac{1}{r_0} E \left(\frac{(r_0 + \lambda_t(\theta_0))}{(r + \lambda_t(\theta_0))} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right).$$

Thus none of the *pNB-QMLE* and *P-QMLE* is asymptotically superior than the other, unless r_0 would be known. In that case, one can take $r = r_0$ and the resulting *pNB-QMLE*, $\hat{\theta}_{r_0}$, would be asymptotically efficient. For instance, consider the *Geometric INGARCH* model which is a special case of the *NB-II-INGARCH* model (4.9) in which $r_0 = 1$, i.e.

$$X_t/\mathcal{F}_{t-1} \sim \mathcal{G} \left(\frac{1}{1 + \lambda_t} \right).$$

For this model, the Geometric *QMLE* (*G-QMLE*), which is a particular case of *pNB-QMLE* corresponding to $r = 1$, reduces to the maximum likelihood estimate and is then asymptotically efficient.

However, whether or not r_0 is known, the *2SNB-QMLE* has the nice property of being asymptotically efficient in the class of all *QMLE*'s belonging to the linear exponential family (cf. Theorem 3.3). Hence, it is more asymptotically efficient than the *P-QMLE*.

Finally, it is worth noting that when $K \notin \{1, 2\}$, the link function (4.7) corresponding to the *NB-K-INGARCH* model is different from both the Poisson *GLM* condition (4.8b)

and the Negative binomial-II assumption (4.11). Therefore, the *2SNB-QMLE* is ill-defined and none of *P-QMLE* and *pNB-QMLE* is asymptotically preferred than the other.

4.1.4. The *INAR*(1) model

A well-known particular case of (2.1) is the first-order integer-valued autoregressive model (*INAR*(1)) proposed by McKenzie (1985) and Al-Osh and Alzaid (1987). This model has the following form

$$X_t = \alpha_0 \circ X_{t-1} + \varepsilon_t, \quad t \in \mathbb{Z}, \quad (4.12)$$

where $\{\varepsilon_t, t \in \mathbb{Z}\}$ is an independent and identically distributed (*iid*) sequence of non-negative integer-valued random variables with mean $E(\varepsilon_t) = \omega_0 > 0$ and variance $Var(\varepsilon_t) = \sigma_0^2 > 0$. The symbol \circ denotes the binomial thinning operator (cf. Steutel and Van Harn, 1979) defined for any non-negative integer-valued random variable X by $\alpha_0 \circ X = \sum_{i=1}^X Y_i$, where $\{Y_i, i \in \mathbb{N}\}$ is an *iid* Bernoulli random sequence such that $P(Y_i = 1) = \alpha_0 \in (0, 1)$. It is well known that

$$E(X_t/\mathcal{F}_{t-1}) = \lambda_t(\theta_0) = \alpha_0 X_{t-1} + \omega_0, \quad \text{with } \theta_0 = (\alpha_0, \omega_0)',$$

and that assumption **A0** reduces in term of α_0 to

$$\alpha_0 < 1,$$

(cf. Al-Osh and Alzaid, 1987). Furthermore, the *INAR*(1) model (4.12) obeys to the following *affine GLM* link function

$$\begin{aligned} Var(X_t/\mathcal{F}_{t-1}) &= \alpha_0(1 - \alpha_0)X_{t-1} + \sigma_0^2 \\ &= (1 - \alpha_0)E(X_t/\mathcal{F}_{t-1}) + \sigma_0^2 - (1 - \alpha_0)\omega_0. \end{aligned} \quad (4.13)$$

Note that if $\frac{\sigma_0^2}{\omega_0} = 1 - \alpha_0 < 1$, so that the innovation term ε_t should be *underdispersed*, then the affine link function (4.13) reduces to the linear Poisson *GLM* condition (4.8b) with proportionality constant $1 - \alpha_0$. Therefore, the *P-QMLE* would be asymptotically efficient in the class of all *QMLE*'s belonging to the linear exponential family and hence it would be

more asymptotically efficient than the $pNB-QMLE$. Specifically,

$$\sqrt{n} \left(\widehat{\theta}_P - \theta_0 \right) \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N \left(0, (1 - \alpha_0) \left(E \left(\frac{1}{\lambda_t(\theta_0)} \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{\partial \lambda_t(\theta_0)}{\partial \theta'} \right) \right)^{-1} \right).$$

If, however, $\frac{\sigma_0^2}{\omega_0} \neq (1 - \alpha_0)$, then none of the two estimates $P-QMLE$ and $pNB-QMLE$ is more asymptotically efficient than the other. Moreover, in all cases the $2SNB-QMLE$ is ill-defined.

4.2. Comparison in finite samples

We now examine the finite-sample performance of the proposed $NB-QMLE$'s on simulated series with sample size $n = 1000$. These series are generated from three instances of (2.1), namely:

i) The Poisson $INGARCH(1, 1)$ model (4.3) with parameter $\theta_0 = (2, 0.3, 0.6)'$ (cf. Table 4.1).

ii) The geometric $INGARCH(1, 1)$ model corresponding to (4.9) with $r_0 = 1$ and $\theta_0 = (2, 0.3, 0.6)'$ (cf. Table 4.2).

iii) The negative binomial-II $INGARCH(1, 1)$ model (4.9) with parameters $r_0 = 3$ and $\theta_0 = (2, 0.3, 0.6)'$ (cf. Table 4.3).

Three $QMLE$'s are compared on these models: *i)* The Poisson $QMLE$ ($\widehat{\theta}_P$, Ahmad and Francq, 2016) given by (4.1), *ii)* the Geometric $QMLE$, $\widehat{\theta}_1$, corresponding to (3.3) with $r = 1$ and *iii)* the profile negative binomial $QMLE$, $\widehat{\theta}_4$, given by (3.3) with $r = 4$. For the $NB-II$ $INGARCH(1, 1)$ model (4.9) we also run the two-stage $NB-QMLE$, $(\widehat{\theta}_{r^*}, \widehat{r}_1, \widehat{\theta}_{\widehat{r}_1}, \widehat{r}_2)$, given by Algorithm 3.1. These estimates are calculated using 500 Monte Carlo replications for the three mentioned models. In implementing the $NB-QMLE$'s we used the same devices: The starting parameter value, $\theta^{(0)} = (\omega^{(0)}, \alpha^{(0)}, \beta^{(0)})'$, of the nonlinear optimization routine (3.3) is set to the value obtained while preliminarily running a $pNB-QMLE$ starting from an initial parameter $\theta^{(-1)} = (2, 0.3, 0.6)'$ and $r^{(-1)} = 3$. The unobservable starting values X_0 and $\lambda_0(\theta)$ of the $INGARCH(1, 1)$ equation are estimated respectively by

$$\widetilde{X}_0 = \overline{X} \text{ and } \widetilde{\lambda}_0(\theta) = \frac{\omega + \alpha \overline{X}}{1 - \beta} \simeq E(\lambda_t(\theta)), \text{ for } \theta = (\omega, \alpha, \beta)' \in \Theta, \quad (4.14)$$

where \bar{X} is the empirical mean of the series X_1, \dots, X_n . Concerning Algorithm 3.1, which is only applied in the case of the *NB-II-INGARCH* model (4.9), we need to estimate the initial dispersion parameter r^* . For this we mime the negative binomial-II *GLM* assumption (4.11), taking r^* to be a solution to the equation,

$$S^2 = \bar{X} \left(1 + \frac{1}{r^*} \bar{X} \right),$$

i.e.

$$r^* = \frac{(\bar{X})^2}{S^2 - \bar{X}}, \quad (4.15)$$

where S^2 is the sample variance of X_1, \dots, X_n . Of course, there is no theoretical justification for this choice. We have just replaced in (4.11) the conditional variance and conditional mean by their unconditional sample counterparts. For that choice, the series X_1, \dots, X_n should be overdispersed (i.e. $S^2 > \bar{X}$), otherwise r^* would be negative, which is not valid.

Mean of estimates, their standard deviation (*StD*) and their empirical Root Minimum Square Error (*RMSE*) over the 500 replications are reported in Tables 4.1-4.3. The *RMSE* of an estimate $\hat{\theta}$ of θ_0 is calculated from the formula $RMSE = \sqrt{bias^2 + StD^2}$, where *bias* is the sample mean of $\hat{\theta} - \theta_0$ over the 500 replications.

| θ_0 | | $\hat{\theta}_P$ | $\hat{\theta}_1$ | $\hat{\theta}_4$ |
|------------------|-------------|------------------|------------------|------------------|
| $\omega = 2$ | <i>Mean</i> | 1.9891 | 2.0111 | 2.0587 |
| | <i>StD</i> | 0.2205 | 0.2977 | 0.3298 |
| | <i>RMSE</i> | 0.2208 | 0.2979 | 0.3350 |
| $\alpha_0 = 0.3$ | <i>Mean</i> | 0.3144 | 0.3322 | 0.3248 |
| | <i>StD</i> | 0.0215 | 0.0290 | 0.0328 |
| | <i>RMSE</i> | 0.0259 | 0.0433 | 0.0411 |
| $\beta_0 = 0.6$ | <i>Mean</i> | 0.5850 | 0.5669 | 0.5713 |
| | <i>StD</i> | 0.0253 | 0.0357 | 0.0372 |
| | <i>RMSE</i> | 0.0294 | 0.0487 | 0.0470 |

Table 4.1. Mean, Standard Deviation and empirical *RMSE* of $\hat{\theta}_r$ ($r = 1, 4$) and $\hat{\theta}_P$ for Poisson *INGARCH*(1, 1) series with $\theta_0 = (2, 0.3, 0.6)'$ and $n = 1000$.

| θ_0 | | $\hat{\theta}_P$ | $\hat{\theta}_1$ | $\hat{\theta}_4$ |
|------------------|-------------|------------------|------------------|------------------|
| $\omega = 2$ | <i>Mean</i> | 2.2428 | 2.0316 | 2.1390 |
| | <i>StD</i> | 0.4957 | 0.3227 | 0.4096 |
| | <i>RMSE</i> | 0.5520 | 0.3242 | 0.4325 |
| $\alpha_0 = 0.3$ | <i>Mean</i> | 0.2965 | 0.2973 | 0.2952 |
| | <i>StD</i> | 0.0422 | 0.0325 | 0.0359 |
| | <i>RMSE</i> | 0.0423 | 0.0326 | 0.0362 |
| $\beta_0 = 0.6$ | <i>Mean</i> | 0.5896 | 0.6006 | 0.5949 |
| | <i>StD</i> | 0.0528 | 0.0296 | 0.0427 |
| | <i>RMSE</i> | 0.0538 | 0.0296 | 0.0430 |

Table 4.2. Mean, Standard Deviation and empirical *RMSE* of $\hat{\theta}_r$ ($r = 1, 4$) and $\hat{\theta}_P$ for geometric *INGARCH*(1, 1) series with $\theta_0 = (2, 0.3, 0.6)'$ and $n = 1000$.

| θ_0 | | $\hat{\theta}_P$ | $\hat{\theta}_1$ | $\hat{\theta}_3$ | $\hat{\theta}_{\hat{r}}$ |
|------------------|-------------|------------------|------------------|------------------|--------------------------|
| $\omega = 2$ | <i>Mean</i> | 2.1271 | 2.0865 | 2.0891 | 2.0812 |
| | <i>StD</i> | 0.4811 | 0.4428 | 0.4336 | 0.4162 |
| | <i>RMSE</i> | 0.4976 | 0.4512 | 0.4427 | 0.4240 |
| $\alpha_0 = 0.3$ | <i>Mean</i> | 0.2962 | 0.2983 | 0.2972 | 0.2953 |
| | <i>StD</i> | 0.0381 | 0.0354 | 0.0312 | 0.0299 |
| | <i>RMSE</i> | 0.0383 | 0.0354 | 0.0314 | 0.0302 |
| $\beta_0 = 0.6$ | <i>Mean</i> | 0.59997 | 0.60003 | 0.59796 | 0.59979 |
| | <i>StD</i> | 0.07434 | 0, 07069 | 0.04309 | 0.03758 |
| | <i>RMSE</i> | 0.07434 | 0, 07069 | 0.04314 | 0.03758 |
| $r_0 = 3$ | <i>Mean</i> | | | | 3.0104 |
| | <i>StD</i> | - | - | - | 0.2250 |
| | <i>RMSE</i> | | | | 0.2252 |

Table 4.3. Mean, Standard Deviation and empirical *RMSE* of $\hat{\theta}_r$ ($r = 1, 4$), $\hat{\theta}_P$, $\hat{\theta}_{\hat{r}}$ and \hat{r}_2 for *NB-II-INGARCH*(1, 1) series with $r_0 = 3$, $\theta_0 = (2, 0.3, 0.6)'$ and $n = 1000$.

From Tables 4.1-4.3 our Monte Carlo analysis broadly reveals that the parameters are well estimated by all accessed methods and the results are consistent with asymptotic theory. More precisely, when the conditional distribution of the *INGARCH* (1, 1) model follows a given distribution, the *QMLE* calculated on that distribution is the best one compared to the others regarding to its smallest *RMSE*. Specifically, in the Poisson *INGARCH* (1, 1) case (cf. Table 4.1) the *P-QMLE* outperforms the *G-QMLE* and the *pNB-QMLE*. Similarly, for the Geometric *INGARCH* (1, 1) model (cf. Table 4.2) the *G-QMLE* has smaller *RMSE* than the *P-QMLE* and the profile *NB-QMLE*, $\hat{\theta}_4$. Finally, for the *NB-II-INGARCH* (1, 1) model with dispersion parameters $r_0 = 3$ (cf. Table 4.3), the four-stage estimate $\hat{\theta}_{\hat{r}}$ outperforms the Poisson *QMLE*, the geometric *QMLE* and the profile *NB-QMLE*, $\hat{\theta}_4$.

5. Real applications

For illustration purposes, we propose to apply the two-stage $NB-QMLE$ given by Algorithm 3.1 to two famous integer-valued time series under the negative binomial-II $INGARCH(1, 1)$ framework. The first one is the *Polio data* (Zeger, 1988) while the second one is the *Transaction data* (Fokianos et al, 2009). The choice of the $NB-II-INGARCH(1, 1)$ model is motivated by the overdispersion of the mentioned series. Moreover, these two real series were considered by Zhu (2011) and Christou and Fokianos (2014) respectively using the $NB-II-INGARCH(1, 1)$ model, but via different estimation methods. This allows us to compare their methods with our proposed $2SNB-QMLE$. All procedures have been applied on a personal computer using R . The optimization (3.3) is carried out using the function `constrOptim()` of R .

5.1. The polio data

The first dataset is the monthly number of poliomyelitis cases in the United States over the sample period from 1970 to 1983 with a total of $n = 168$ observations (cf. Figure 5.1). This series was originally modelled by Zeger (1988) and used later by many authors (see Zeger and Qaqish, 1988; Davis et al, 1999; Benjamin et al, 2003; Heinen, 2003; Davis and Wu, 2009; Zhu, 2011 among others). The Polio series with a sample mean of 1.3333 and a sample variance of 3.5050 is clearly overdispersed. It has a large frequency of zeros, has an asymmetric marginal distribution and is characterized by a locally constant behavior (cf.

Figure 5.1, see also Zeger, 1987; Benjamin et al, 2003; Zhu, 2011).

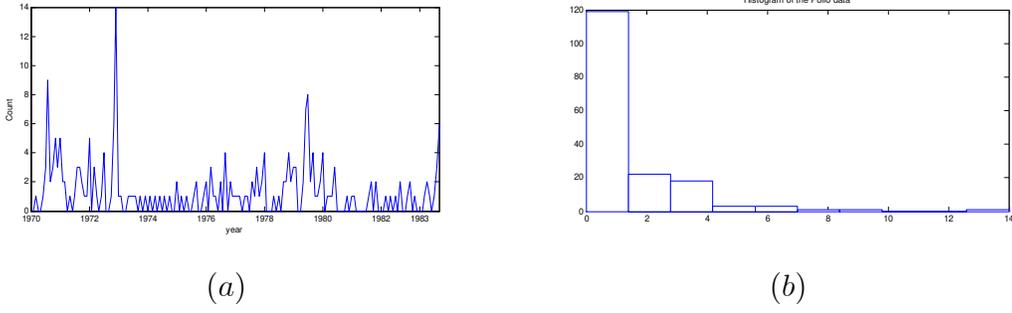


Figure 5.1: Monthly number of poliomyelitis cases in the United States from 1970 to 1983.

(a) Series, (b) Histogram.

Zhu (2011) fitted a *NB-II-INGARCH* (1, 1) model of the form (4.10) to the polio series. As emphasized above, this model is slightly different from the model (4.9). First, the dispersion parameter in (4.10) is taken to be a positive integer, which is somewhat restrictive. Second, the probability parameter is $\frac{1}{1+\mu_t}$ rather than $\frac{r_0}{r_0+\lambda_t}$ in (4.9). So the conditional mean of model (4.10) is not in the form (2.1). However, by taking $\lambda_t = \frac{\mu_t}{r_0}$ we find model (4.9) with a different parametrization. Zhu (2011) estimated model (4.10) using an approximate maximum likelihood estimate. This estimate consists in maximizing the negative binomial likelihood over θ for fixed r and then choosing θ with largest likelihood over all selected values of $r \in \{1, \dots, \bar{r}\}$, for some fixed positive integer \bar{r} . The estimated model of Zhu (2011) is given by

$$\begin{aligned}
 X_t / \mathcal{F}_{t-1} &\sim \mathcal{NB} \left(\hat{r}, \frac{1}{1+\hat{\mu}_t} \right), \\
 \hat{r} &= 2, \\
 \begin{cases} \hat{\mu}_t = 0.31190 + 0.1843X_{t-1} + 0.1815\hat{\mu}_{t-1}, & 2 \leq t \leq 168 \\ \hat{\mu}_1 = \bar{X}, \end{cases}
 \end{aligned} \tag{5.1}$$

from which the estimate of $E(X_t)$ is

$$2 \times \frac{0.3119}{1-(0.1843+0.1815)} = 0.9836,$$

and the persistence (or stability) parameter is $0.1843 + 0.1815 = 0.3658$.

To compare with Zhu's (2011) fit, we estimated a *NB-II-INGARCH* (1, 1) model (4.9) using the *2SNB-QMLE* (Algorithm 3.1). In implementing Algorithm 3.1 we used the same devices as in Section 4.2. More precisely, the initial dispersion parameter r^* is calculated using (4.15) giving

$$r^* = \frac{(1.3333)^2}{3.5050 - 1.3333} = 0.8186,$$

while the starting values of the *INGARCH* (1, 1) equation (4.3b) are taken as in (4.14). The initial conditional mean parameter $\theta^{(0)}$ of the optimization problem (3.3) is obtained while preliminarily running the Geometric *QMLE* on the polio series with initial parameter $(2, 0.3, 0.6)'$. The estimated parameters of the model and their *Asymptotic Standard Errors* (*ASE*) are summarized in Table 5.1. The *ASE*'s are calculated from the asymptotic distribution of the *2SNB-QMLE* given by Theorem 3.3. In particular, the *ASE* of $\hat{\gamma}_2 = (\hat{r}_2)^{-1}$ is computed from (3.14b) and (3.16) while the *ASE* of $\hat{\theta}_{\hat{r}_2}$ is obtained from (3.14d) and (3.15). Note that the *ASE* of \hat{r}_2 is not available since the distribution of \hat{r}_2 has not a usual form.

| <i>NB-II-INGARCH</i> <i>parameters</i> | <i>Estimates :</i> $(\hat{\theta}_{\hat{r}_1}, \hat{\gamma}_2, \hat{r}_2)$ | <i>ASE of</i> $\hat{\theta}_{\hat{r}_1}, \hat{\gamma}_2$ |
|---|---|---|
| ω_0 | 0.6564 | 0.2050 |
| α_0 | 0.3743 | 0.1580 |
| β_0 | 0.1511 | 0.0935 |
| $\gamma_0 = \frac{1}{r_0}$ | 0.3843 | 0.1945 |
| r_0 | 2.6023 | — |

Table 5.1: *2S-NBQML* estimates and their asymptotic standard errors for the *NB-II-INGARCH*(1, 1) model from the Polio data.

The fitted model (4.9) using the *2SNB-QMLE* is given by

$$\begin{aligned}
 X_t / \mathcal{F}_{t-1} &\sim \mathcal{NB} \left(\hat{r}_2, \frac{\hat{r}_2}{\hat{r}_2 + \hat{\lambda}_t} \right), \\
 \hat{r}_2 &= 2.6023, \\
 \begin{cases} \hat{\lambda}_t = 0.6564 + 0.3743X_{t-1} + 0.1511\hat{\lambda}_{t-1}, & 2 \leq t \leq 168 \\ \hat{\lambda}_1 = \bar{X} = 1.3333, \end{cases}
 \end{aligned} \tag{5.2}$$

with persistence parameter $0.3743 + 0.1511 = 0.5254$. Note that our estimate of the mean $E(X_t)$ is

$$\frac{0.6564}{1-(0.3743+0.1511)} = 1.3834,$$

which is closer to the sample mean $\bar{X} = 1.3333$ than the estimated mean, 0.9836, given by Zhu's (2011) model. On the other hand, some properties of the residuals are shown in Figure 5.2. Indeed, from the sample autocorrelation and partial autocorrelation functions in Figure 5.2 (panels (a) and (b)), the residuals look like a white noise. However, a visual inspection (cf. Figure 5.2, panels (c) and (d)) reveals that the normality assumption of the residuals is untenable. In sum, regarding the stability of the estimated model, the significance of its coefficients and the residual analysis in Figure 5.2, it can be concluded that the estimated model is acceptable.

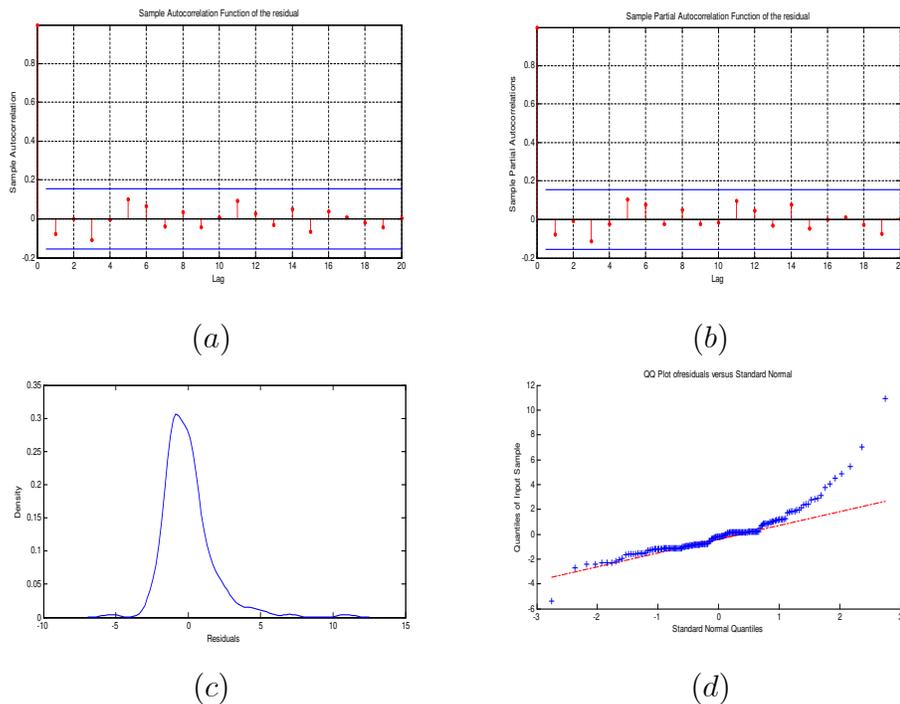


Figure 5.2: Residual analysis for the Polio series. (a) Sample autocorrelations of residuals. (b) Sample partial autocorrelations of residuals. (c) Kernel density of residuals. (d) QQ-plot of the residuals versus the standard normal distribution.

Now we compare in-sample performance of our fit (5.1) with that of Zhu (2011). Table

5.2 provides the *residual sum of squares* (RSS) induced by models (5.1) and (5.2). These RSS 's are given respectively by

$$RSS(\hat{\lambda}_t) = \sum_{t=2}^{168} (X_t - \hat{\lambda}_t)^2,$$

$$RSS(2\hat{\mu}_t) = \sum_{t=2}^{168} (X_t - 2\hat{\mu}_t)^2,$$

starting from initial values $\hat{\lambda}_1 = \hat{\mu}_1 = \bar{X}$. The latter initial value was considered by Zhu (2011).

| Predictors | $\hat{\lambda}_t$ | $2\hat{\mu}_t$ |
|------------|-------------------|----------------|
| RSS | 535.1793 | 540.6634 |

Table 5.2: Residual sum of squares (RSS) of the predictors

$\hat{\lambda}_t$ (5.2) and $2\hat{\mu}_t$ (5.1) for the Polio series.

From Table 5.2 it can be seen that our model estimated by the $2SNB-QMLE$ (Algorithm 3.1) slightly outperforms the model of Zhu (2011) with smaller Residual Sum of Squares (RSS). Since the conditional mean may be influenced by the choice of the initial values, we have calculated several RSS corresponding to models (5.1) and (5.2) starting from several initial values $\hat{\lambda}_1$ and $\hat{\mu}_1$; the unreported results were virtually the same. Finally, Figure 5.3 displays the polio data together with the estimated conditional mean $\hat{\lambda}_t$ and the estimated conditional variance given by $\hat{v}_t = \hat{\lambda}_t \left(1 + \frac{1}{\hat{r}_2} \hat{\lambda}_t\right)$, where the overdispersion phenomenon seems reproduced.

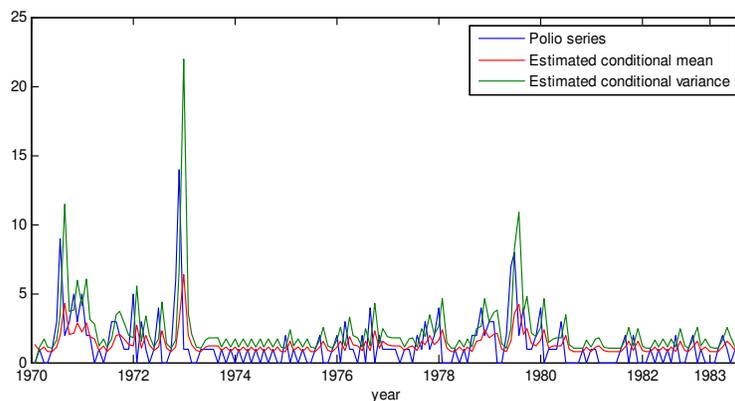


Figure 5.3: Polio series and its estimated conditional mean and conditional variance.

5.2. Transaction data

The second dataset is the number of transactions per minute for the stock Ericsson B during July 05, 2002. This series has a total of $n = 460$ observations representing the transaction of approximately 8 hours (from 09:35 through 17:14, cf. Figure 5.4). It was used by Fokianos et al (2009), Davis and Liu (2009) and Christou and Fokianos (2014) among others. Like the Polio data, the Transaction series is overdispersed viewing its sample mean and sample variance, which are equal to 9.8239 and 23.7532 respectively. It is characterized by small values, an asymmetric marginal distribution and a locally constant behavior (cf. Figure 5.4).

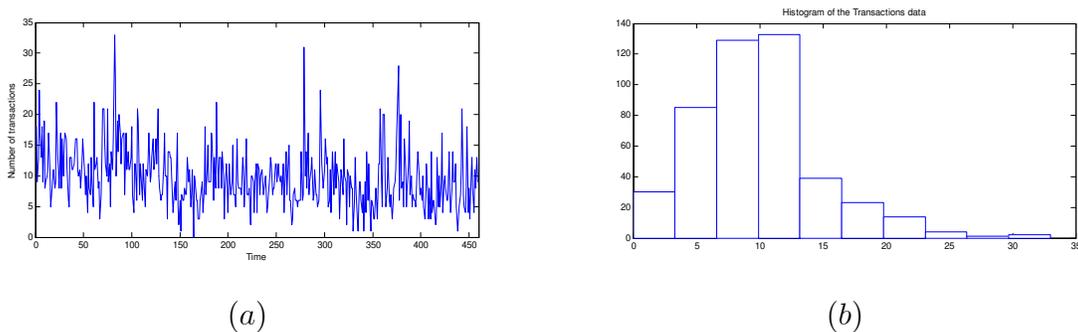


Figure 5.4: Number of transactions per minute for the stock Ericsson B during July 05, 2002.

(a) series, (b) histogram.

Using the Poisson $QMLE$, Christou and Fokianos (2014) fitted a $NB-II-INGARCH(1, 1)$ model (4.9) to the Transaction data. They found the following specification

$$\begin{aligned}
 X_t / \mathcal{F}_{t-1} &\sim \mathcal{NB} \left(\hat{r}, \frac{\hat{r}}{\hat{r} + \hat{\mu}_t} \right), \\
 \hat{r} &= 7.0220, \\
 \begin{cases} \hat{\mu}_t = 0.5808 + 0.1986X_{t-1} + 0.7445\hat{\mu}_{t-1}, & 2 \leq t \leq 460 \\ \hat{\mu}_1 = 0, \end{cases}
 \end{aligned} \tag{5.3}$$

with a strong persistence parameter 0.9431 and an estimated mean $\frac{0.5808}{1-0.9431} = 10.2070$.

Motivated by the fact that the $2SNB-QMLE$ (Algorithm 3.1) is more asymptotically efficient than the $P-QMLE$ in the context of the $NB-II-INGARCH$ model (cf. Section 4.1.3), we applied the former estimate to the Transaction series using the same devices as

for the Polio data. Indeed, from (4.15), the initial dispersion parameter r^* is taken to be

$$r^* = \frac{(9.8239)^2}{23.7532 - 9.8239} = 6.9285,$$

while the starting values of the *INGARCH* (1, 1) equation (4.3b) are set according to (4.14). The parameter estimates and their *Asymptotic Standard Errors* (*ASE*) are summarized in Table 5.3.

| <i>NB-II-INGARCH</i> <i>parameters</i> | <i>Estimates</i> : $(\hat{\theta}_{\hat{r}_1}, \hat{\gamma}_2, \hat{r}_2)$ | <i>ASE</i> of $\hat{\theta}_{\hat{r}_1}, \hat{\gamma}_2$ |
|---|---|---|
| ω_0 | 0.7996 | 0.4034 |
| α_0 | 0.7928 | 0.0650 |
| β_0 | 0.1249 | 0.0340 |
| $\gamma_0 = \frac{1}{r_0}$ | 0.1279 | 0.0241 |
| r_0 | 7.8199 | — |

Table 5.3: *2S-NBQML* estimates and their asymptotic standard errors for the *NB-II-INGARCH*(1, 1) model from the Transaction data.

Thus our fitted *NB-II-INGARCH*(1, 1) model from the Transaction series using the *2SNB-QMLE* is given by

$$\begin{aligned}
 X_t / \mathcal{F}_{t-1} &\sim \mathcal{NB} \left(\hat{r}_2, \frac{\hat{r}_2}{\hat{r}_2 + \hat{\lambda}_t} \right), \\
 \hat{r}_2 &= 7.8199, \\
 \left\{ \begin{array}{l} \hat{\lambda}_t = 0.7996 + 0.7928X_{t-1} + 0.1249\hat{\lambda}_{t-1}, \quad 2 \leq t \leq 460 \\ \hat{\lambda}_1 = \bar{X} = 9.8134, \end{array} \right. & \quad (5.4)
 \end{aligned}$$

with a strong persistence parameter of 0.9177 and an estimated mean, $\frac{0.7996}{1-0.9177} = 9.7157$, which is closer to the sample mean $\bar{X} = 9.8239$ than the estimated mean obtained from the specification of Christou and Fokianos (2014).

Figure 5.5 shows the sample autocorrelation function (panel (a)), the sample partial autocorrelation function (panel (b)), the Kernel density (panel (c)) and the QQ-plot (panel

(*d*) of the residuals of model (5.4). It turns out that the hypothesis that the residuals form a non-Gaussian white noise is strongly tenable.

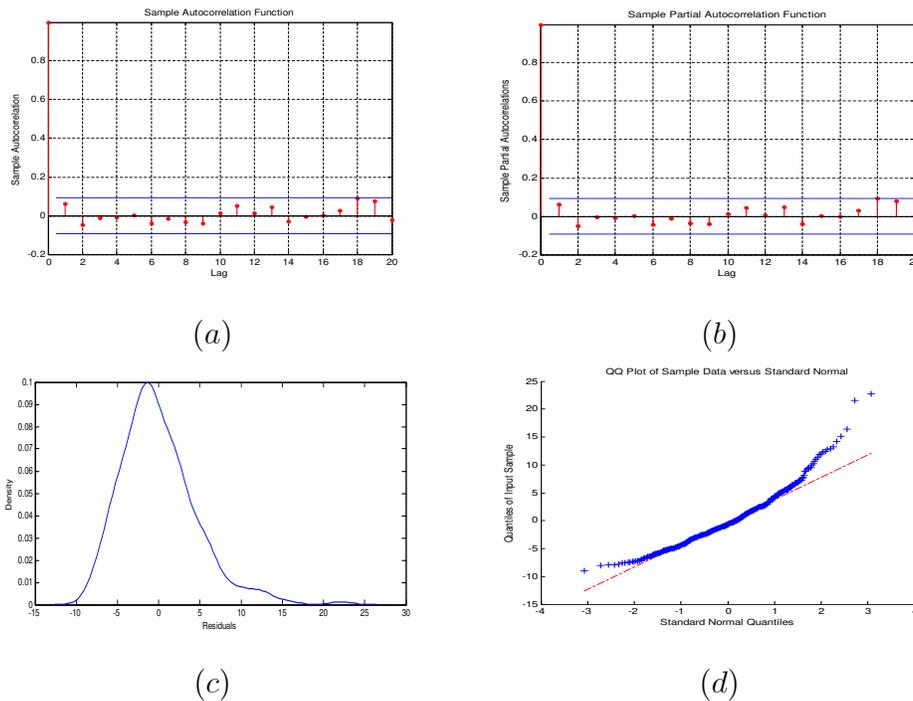


Figure 5.5: Residual analysis for the Transaction series. (*a*) Sample autocorrelations of residuals. (*b*) Sample partial autocorrelations of residuals. (*c*) Kernel density of residuals. (*d*) QQ-plot of the residuals versus the standard normal distribution.

Next we compare the RSS of our fit (5.4) with that of Christou and Fokianos (2014) given by (5.3). Because of the high persistence parameters in both models, the RSS 's may be influenced by the starting values for the moderate sample size of the Transaction series. We therefore started the equations (5.3) and (5.4) from several initial values (cf. Table 5.4)

although Christou and Fokianos (2014) have taken $\hat{\mu}_1 = 0$.

| Predictors | $\hat{\lambda}_t$ | $\hat{\mu}_t$ | $\hat{\lambda}_t$ | $\hat{\mu}_t$ | $\hat{\lambda}_t$ | $\hat{\mu}_t$ |
|--|-------------------|---------------|-------------------|---------------|-------------------|---------------|
| Initial values $\hat{\lambda}_1, \hat{\mu}_1$ | 0 | 0 | 9.8239 | 9.8239 | 10.2070 | 10.2070 |
| <i>RSS</i> | 10400.6733 | 10422.8003 | 9809.6645 | 9943.0150 | 9796.8644 | 9933.0780 |

Table 5.4: Residual sum of squares (*RSS*) of the predictors $\hat{\lambda}_t$ (5.4) and $\hat{\mu}_t$ (5.3) for the Transaction data.

It can be seen from Table 5.4 that model (5.4) estimated by the *2SNB-QMLE* has the smallest *RSS* for all chosen initial values. Figure 5.6 shows the Transaction series together with the estimated conditional mean $\hat{\lambda}_t$ and the estimated conditional variance given by $\hat{v}_t = \hat{\lambda}_t \left(1 + \frac{1}{r_2} \hat{\lambda}_t\right)$, where the overdispersion phenomenon is highlighted.

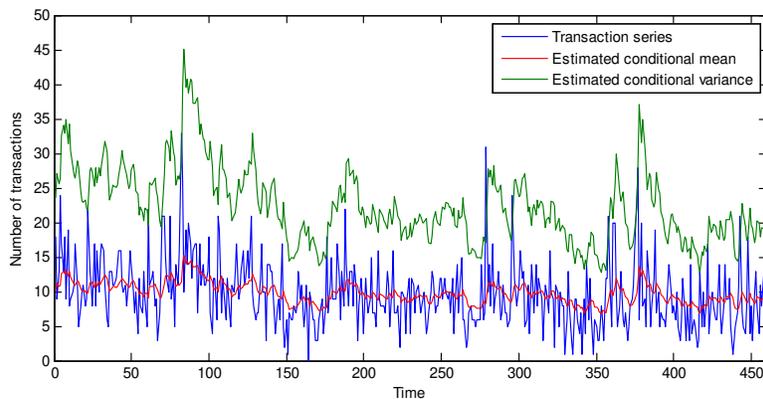


Figure 5.6: Transaction series and its estimated conditional mean and conditional variance.

6. Conclusion

In this paper we proposed two negative binomial *QMLE*'s, namely the profile *NB-QMLE* and the two-stage *NB-QMLE*, for a general class of integer-valued time series models. These estimates are consistent and asymptotically Gaussian under general weak assumptions. In particular, they are robust to misspecification of the true conditional distribution of the model whenever the conditional mean is well specified. Moreover, under the negative

binomial-II *GLM* link function, the two-stage *NB-QMLE* is more asymptotically efficient than the Poisson *QMLE* and is especially well adapted to overdispersed series. Furthermore, it is asymptotically efficient in the class of all *QMLE*'s belonging to the linear exponential family. In fact, the two-stage *NB-QMLE* may be seen as a good alternative to the maximum likelihood estimate (for models with negative binomial-II conditional distributions), which suffers from the non-robustness to misspecification of the true conditional distribution and whose calculation is very tedious. From asymptotics of the *NB-QMLE*'s (Theorems 3.1-3.3), portmanteau tests for goodness-of-fit in the framework of the *INGAR* model are easily derived.

On the other hand, we have seen how the proposed *NB-QMLE*'s can be applied to some specific integer-valued models like the Poisson and negative binomial *INGARCH* models and also to the *INAR* equation. Other famous particular cases of the *INGAR* model like the log-*INGARCH* model (Fokianos and Tjøstheim, 2011), the double Poisson *INGARCH* model (Heinen, 2003; Ahmad and Francq, 2016), the generalized Poisson *INGARCH* model (Zhu, 2012a) and Integer-valued *ARMA* (*INARMA*) models also apply in the framework of our methods. Finally, generalizations of the proposed methods to multivariate versions of the *INGAR* model are appealing.

7. Proofs

7.1. Proof of Theorem 3.1

Following Wald's approach, the proof of Theorem 3.1 is based on the following three lemmas.

Lemma 7.1 *Under A1-A2*

$$\limsup_{n \rightarrow \infty} \sup_{\theta \in \Theta} |L_{n,r}(\theta) - \tilde{L}_{n,r}(\theta)| = 0, \quad a.s.$$

Proof Using the inequality $\log(x) \leq x - 1$, the fact that $\tilde{\lambda}_t(\theta) > 0$, the assumptions

A1-A2 and the Césaro lemma it follows that

$$\begin{aligned}
\sup_{\theta \in \Theta} \left| L_{n,r}(\theta) - \tilde{L}_{n,r}(\theta) \right| &= \frac{1}{n} \sup_{\theta \in \Theta} \left| \sum_{t=1}^n \left(\log \left(\frac{r+\lambda_t(\theta)}{r+\tilde{\lambda}_t(\theta)} \right) + X_t \log \left(\frac{\tilde{\lambda}_t(\theta)(r+\lambda_t(\theta))}{\lambda_t(\theta)(r+\tilde{\lambda}_t(\theta))} \right) \right) \right| \\
&= \frac{1}{n} \sup_{\theta \in \Theta} \left| \sum_{t=1}^n \left(\log \left(\frac{\lambda_t(\theta)-\tilde{\lambda}_t(\theta)}{r+\tilde{\lambda}_t(\theta)} + 1 \right) + X_t \log \left(r \frac{\tilde{\lambda}_t(\theta)-\lambda_t(\theta)}{\lambda_t(\theta)(r+\tilde{\lambda}_t(\theta))} + 1 \right) \right) \right| \\
&\leq \frac{1}{n} \sum_{t=1}^n \left(\frac{1}{r} \sup_{\theta \in \Theta} \left| \lambda_t(\theta) - \tilde{\lambda}_t(\theta) \right| + X_t \sup_{\theta \in \Theta} \left| \tilde{\lambda}_t(\theta) - \lambda_t(\theta) \right| \frac{r}{cr} \right) \\
&= \frac{1}{n} \sum_{t=1}^n \left(\frac{1}{r} a_t + \frac{1}{c} X_t a_t \right) \xrightarrow[n \rightarrow \infty]{a.s.} 0.
\end{aligned}$$

■

Lemma 7.2 Under **A0-A4**,

i) $E(l_{1,r}(\theta_0)) < \infty$.

ii) $E(l_{1,r}(\theta_0)) \geq E(l_{1,r}(\theta))$ for all $\theta \in \Theta$.

iii) $E(l_{1,r}(\theta)) = E(l_{1,r}(\theta_0)) \Rightarrow \theta = \theta_0$.

Proof Under **A1** the random variables $\log \left(\frac{r}{r+\lambda_t(\theta)} \right)$ and $\log \left(\frac{\lambda_t(\theta)}{r+\lambda_t(\theta)} \right)$ are bounded. Hence, they admit finite moments of all order. By the Jensen and Hölder inequalities together with **A3** it follows that

$$\begin{aligned}
|E(l_{1,r}(\theta_0))| &\leq E(|l_{1,r}(\theta_0)|) \leq E \left(\left| \log \left(\frac{r}{r+\lambda_t(\theta_0)} \right) \right| \right) + E \left(\left| X_t \log \left(\frac{\lambda_t(\theta_0)}{r+\lambda_t(\theta_0)} \right) \right| \right) \\
&\leq E \left(\left| \log \left(\frac{r}{r+\lambda_t(\theta_0)} \right) \right| \right) + (E(X_t^\delta))^{1/\delta} \left(E \left(\left| \log \frac{\lambda_t(\theta_0)}{r+\lambda_t(\theta_0)} \right|^{\frac{\delta}{\delta-1}} \right) \right)^{\frac{\delta-1}{\delta}} < \infty.
\end{aligned} \tag{7.1}$$

On the other hand, using again the inequality $\log(x) \leq x - 1$, we have

$$\begin{aligned}
E(l_{1,r}(\theta) - l_{1,r}(\theta_0)) &= E \left(r \log \left(\frac{r+\lambda_t(\theta_0)}{r+\lambda_t(\theta)} \right) + X_t \log \left(\frac{\lambda_t(\theta)(r+\lambda_t(\theta_0))}{\lambda_t(\theta_0)(r+\lambda_t(\theta))} \right) \right) \\
&\leq r E \left(\left(\frac{r+\lambda_t(\theta_0)}{r+\lambda_t(\theta)} - 1 \right) + X_t \left(\frac{\lambda_t(\theta)(r+\lambda_t(\theta_0))}{\lambda_t(\theta_0)(r+\lambda_t(\theta))} - 1 \right) \right) \\
&= r E \left(\frac{\lambda_t(\theta_0)-\lambda_t(\theta)}{r+\lambda_t(\theta)} \right) + E \left(r \frac{X_t}{\lambda_t(\theta_0)} \frac{\lambda_t(\theta)-\lambda_t(\theta_0)}{r+\lambda_t(\theta)} \right) \\
&= r E \left(\frac{\lambda_t(\theta_0)-\lambda_t(\theta)}{r+\lambda_t(\theta)} + \frac{\lambda_t(\theta)-\lambda_t(\theta_0)}{r+\lambda_t(\theta)} \right) = 0,
\end{aligned} \tag{7.2}$$

By (7.1) and (7.2) it follows that $E(l_{1,r}(\theta) - l_{1,r}(\theta_0)) \in [-\infty, 0]$ so $E(l_{1,r}(\theta)) < E(l_{1,r}(\theta_0))$ for all $\theta \neq \theta_0$. Finally, inequality (7.2) reduces to equality if and only if

$$rE\left(\log\left(\frac{r+\lambda_t(\theta_0)}{r+\lambda_t(\theta)}\right) + X_t \log\left(\frac{\lambda_t(\theta)(r+\lambda_t(\theta_0))}{\lambda_t(\theta_0)(r+\lambda_t(\theta))}\right)\right) = 0,$$

which holds if and only if $\lambda_t(\theta) = \lambda_t(\theta_0)$ and then, by the identifiability assumption **A4**, if and only if $\theta = \theta_0$. ■

Lemma 7.3 *Under **A0-A5**, there exists for all $\theta \neq \theta_0$ a neighborhood $V(\theta)$ such that*

$$\limsup_{n \rightarrow \infty} \sup_{\theta^* \in V(\theta)} \tilde{L}_{n,r}(\theta^*) < \limsup_{n \rightarrow \infty} \tilde{L}_{n,r}(\theta_0) \quad a.s. \quad (7.3)$$

Proof For all $\bar{\theta} \in \Theta$ and $k \in \mathbb{N}^*$ let $V_k(\bar{\theta})$ be the open ball of center $\bar{\theta}$ and radius $1/k$. Since $\sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} l_{t,r}(\theta)$ is a measurable function of the terms of $\{X_t, t \in \mathbb{Z}\}$, which is strictly stationary and ergodic under **A0**, then $\left\{ \sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} l_{t,r}(\theta), t \in \mathbb{Z} \right\}$ is also strictly stationary and ergodic where by Lemma 7.2 $E\left(\sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} l_{t,r}(\theta)\right) \in [-\infty, +\infty[$. Therefore, in view of Lemma 7.1 and the ergodic theorem (Billingsley, 2008) it follows that

$$\limsup_{n \rightarrow \infty} \sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} \tilde{L}_{n,r}(\theta) = \limsup_{n \rightarrow \infty} \sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} L_{n,r}(\theta) \leq E\left(\sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} l_{1,r}(\theta)\right).$$

By the Beppo-Levi theorem $E\left(\sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} l_{1,r}(\theta)\right)$ converges while decreasing to $E(l_{1,r}(\bar{\theta}))$ as $k \rightarrow \infty$. Hence, (7.3) follows from Lemma 7.2, ii). ■

In view of Lemmas 7.1-7.3, we have shown that there exists for all $\bar{\theta} \neq \theta_0$ a neighborhood $V(\bar{\theta})$ such that

$$\limsup_{n \rightarrow \infty} \sup_{\theta \in V_k(\bar{\theta}) \cap \Theta} \tilde{L}_{n,r}(\theta) < \limsup_{n \rightarrow \infty} \tilde{L}_{n,r}(\theta_0) = \limsup_{n \rightarrow \infty} L_{n,r}(\theta_0) = E(l_{1,r}(\theta_0)).$$

Thus from standard arguments the proof of Theorem 3.1 is completed while using assumption **A5** of compactness of Θ .

7.2. Proof of Theorem 3.2

By **A7** and Theorem 3.1 we know that $\widehat{\theta}_r$ cannot be at the boundary of Θ for n sufficiently large. Hence, a Taylor expansion of $\frac{\partial L_{n,r}(\widehat{\theta}_r)}{\partial \theta}$ at θ_0 yields

$$\begin{aligned} 0 &= \sqrt{n} \frac{\partial \widetilde{L}_{n,r}(\widehat{\theta}_r)}{\partial \theta} \\ &= \sqrt{n} \frac{\partial L_{n,r}(\widehat{\theta}_r)}{\partial \theta} + \sqrt{n} \left(\frac{\partial \widetilde{L}_{n,r}(\theta)}{\partial \theta} - \frac{\partial L_{n,r}(\theta)}{\partial \theta} \right) \\ &= \sqrt{n} \frac{\partial L_{n,r}(\theta_0)}{\partial \theta} + \sqrt{n} \frac{\partial^2 L_{n,r}(\theta^*)}{\partial \theta \partial \theta'} \left(\widehat{\theta}_r - \theta_0 \right) + \sqrt{n} \left(\frac{\partial \widetilde{L}_{n,r}(\theta)}{\partial \theta} - \frac{\partial L_{n,r}(\theta)}{\partial \theta} \right), \end{aligned} \quad (7.4)$$

for a certain θ^* between $\widehat{\theta}_r$ and θ_0 . In view of (7.4), the proof of Theorem 3.2 is based on the following three lemmas. Lemma 7.4 shows that the last term in (7.4) is *a.s.* negligible as $n \rightarrow \infty$. Lemma 7.5 establishes the convergence in law of the first term of (7.4) using a martingale central limit theorem while Lemma 7.6 shows the convergence of the matrix in the second term of (7.4).

Lemma 7.4 *Under A0-A10*

$$\sqrt{n} \sup_{\theta \in \Theta} \left\| \frac{\partial \widetilde{L}_{n,r}(\theta)}{\partial \theta} - \frac{\partial L_{n,r}(\theta)}{\partial \theta} \right\| \xrightarrow[n \rightarrow \infty]{a.s.} 0.$$

Proof Using **A2** and **A6** it follows that

$$\begin{aligned} \sqrt{n} \sup_{\theta \in \Theta} \left\| \frac{\partial \widetilde{L}_{n,r}(\theta)}{\partial \theta} - \frac{\partial L_{n,r}(\theta)}{\partial \theta} \right\| &= \frac{1}{\sqrt{n}} \sup_{\theta \in \Theta} \left\| \sum_{t=1}^n \left[\frac{\partial}{\partial \theta} \left(\log \left(\frac{r}{r+\lambda_t(\theta)} \right) + X_t \log \left(\frac{\widetilde{\lambda}_t(\theta)}{r+\lambda_t(\theta)} \right) \right) \right. \right. \\ &\quad \left. \left. - \frac{\partial}{\partial \theta} \left(\log \left(\frac{r}{r+\lambda_t(\theta)} \right) + X_t \log \left(\frac{\lambda_t(\theta)}{r+\lambda_t(\theta)} \right) \right) \right] \right\| \\ &\leq \frac{1}{\sqrt{n}} \sum_{t=1}^n \left(c_t + a_t d_t + X_t \left(\frac{c_t}{c r} + \frac{(a_t + b_t) d_t}{c^2 r^2} \right) \right) \xrightarrow[n \rightarrow \infty]{a.s.} 0. \end{aligned}$$

Lemma 7.5 *Under A8-A9,*

$$\sqrt{n} \frac{\partial L_{n,r}(\theta_0)}{\partial \theta} \xrightarrow[n \rightarrow \infty]{\mathcal{L}} N(0, I_r).$$

Proof It is clear that $\left\{ \sqrt{n} \frac{\partial L_{n,r}(\theta_0)}{\partial \theta}, t \in \mathbb{Z} \right\}$ is a martingale with respect to $\{\mathcal{F}_t, t \in \mathbb{Z}\}$ where

$$\begin{aligned} \sqrt{n} \frac{\partial L_{n,r}(\theta_0)}{\partial \theta} &= \sum_{t=1}^n \frac{1}{\sqrt{n}} \frac{\partial l_{t,r}(\theta_0)}{\partial \theta}, \\ \frac{\partial l_{t,r}(\theta_0)}{\partial \theta} &= \frac{\partial \lambda_t(\theta_0)}{\partial \theta} \frac{X_t - \lambda_t(\theta_0)}{\lambda_t(\theta_0)(1 + \lambda_t(\theta_0))}. \end{aligned}$$

By **A8-A9** we have

$$E \left(\frac{\partial l_{t,r}(\theta_0)}{\partial \theta} \frac{\partial l_{t,r}(\theta_0)}{\partial \theta'} \right) = E \left(\frac{v_t(\theta_0)}{\lambda_t^2(\theta_0)(1+\lambda_t(\theta_0))^2} \frac{\partial \lambda_t(\theta_0) \partial \lambda_t(\theta_0)}{\partial \theta \partial \theta'} \right) = I_r.$$

Thus Lemma 7.4 follows from the martingale central limit theorem (e.g. Billingsley, 2008).

■

Lemma 7.6 *Under **A8-A10**,*

$$\frac{\partial^2 L_{n,r}(\theta^*)}{\partial \theta \partial \theta'} \xrightarrow[n \rightarrow \infty]{a.s.} J_r.$$

Proof Let $V_k(\theta_0)$ ($k \in \mathbb{N}^*$) be the open ball with center θ_0 and radius $1/k$ where k is supposed large enough so that $V_k(\theta_0)$ is contained in $V(\theta_0)$ defined by **A10**. Assume that n is large enough so that θ^* belongs to $V_k(\theta_0)$. By stationarity and ergodicity of

$$\left\{ \sup_{\theta \in V_k(\theta_0)} \left| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \right\},$$

we have

$$\begin{aligned} \left| \frac{\partial^2 L_{n,r}(\theta^*)}{\partial \theta_i \partial \theta_j} - J_r(i, j) \right| &= \left| \frac{\partial^2 L_{n,r}(\theta^*)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 L_{n,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \\ &= \frac{1}{n} \left| \sum_{t=1}^n \frac{\partial^2 l_{t,r}(\theta^*)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \\ &\leq \frac{1}{n} \sup_{\theta \in V_k(\theta_0)} \left| \sum_{t=1}^n \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \\ &\leq \frac{1}{n} \sum_{t=1}^n \sup_{\theta \in V_k(\theta_0)} \left| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \\ &\xrightarrow[n \rightarrow \infty]{a.s.} E \left(\sup_{\theta \in V_k(\theta_0)} \left| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \right). \end{aligned}$$

In view of **A10**, the Lebesgue dominated convergence theorem yields

$$\begin{aligned} \lim_{k \rightarrow \infty} E \left(\sup_{\theta \in V_k(\theta_0)} \left| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \right) &= E \left(\lim_{k \rightarrow \infty} \sup_{\theta \in V_k(\theta_0)} \left| \frac{\partial^2 l_{t,r}(\theta)}{\partial \theta_i \partial \theta_j} - E \left(\frac{\partial^2 l_{t,r}(\theta_0)}{\partial \theta_i \partial \theta_j} \right) \right| \right) \\ &= 0, \end{aligned}$$

which completes the proof of the lemma. ■

7.3. Proof of Theorem 3.3

i) **Proof of (3.14a)** It suffices to prove strong consistency of $\widehat{\gamma}$. From (3.12) and (3.13) we have

$$\begin{aligned}\widehat{\gamma} - \gamma_0 &= \frac{1}{n} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2} \\ &= \frac{1}{n} \sum_{t=1}^n \frac{u_t}{\lambda_t^2} + \frac{1}{n} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2} \left(\frac{1}{\widehat{\lambda}_t^2} - \frac{1}{\lambda_t^2} \right).\end{aligned}\quad (7.5)$$

By the ergodic theorem the first term in the right hand side of (7.5) satisfies the following limiting result

$$\frac{1}{n} \sum_{t=1}^n \frac{u_t}{\lambda_t^2} \xrightarrow[n \rightarrow \infty]{a.s.} E \left(\frac{u_t}{\lambda_t^2} \right) = E \left(\frac{1}{\lambda_t^2} E(u_t / \mathcal{F}_{t-1}) \right) = 0.$$

So it remains to show that

$$\frac{1}{n} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2} \left(\frac{1}{\widehat{\lambda}_t^2} - \frac{1}{\lambda_t^2} \right) = o_{a.s.}(1).\quad (7.6)$$

Using a Taylor expansion of $\frac{1}{\lambda_t^2(\theta_r)}$ around θ_0 , we have

$$\begin{aligned}\frac{1}{\widehat{\lambda}_t^2} - \frac{1}{\lambda_t^2} &= \frac{1}{\lambda_t^2(\theta_r)} - \frac{1}{\lambda_t^2(\theta_0)} \\ &= -\frac{2}{\lambda_t^3(\theta^*)} \frac{\partial \lambda_t(\theta^*)}{\partial \theta'} (\widehat{\theta}_r - \theta_0),\end{aligned}$$

where θ^* is between $\widehat{\theta}_r$ and θ_0 . Thus (7.6) follows from **A1**, **A10**, the strong consistency of $\widehat{\theta}_r$ and the ergodic theorem.

ii) **Proof of (3.14b)** Rewrite (7.5) as follows

$$\sqrt{n}(\widehat{\gamma} - \gamma_0) = \frac{1}{\sqrt{n}} \sum_{t=1}^n \frac{u_t}{\lambda_t^2} + \frac{1}{\sqrt{n}} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2} \left(\frac{1}{\widehat{\lambda}_t^2} - \frac{1}{\lambda_t^2} \right).$$

If we show that

$$\frac{1}{\sqrt{n}} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2} \left(\frac{1}{\widehat{\lambda}_t^2} - \frac{1}{\lambda_t^2} \right) = o_p(1),\quad (7.7)$$

then (3.14b) would follow from the martingale central limit theorem applied for the $\{\mathcal{F}_t, t \in \mathbb{Z}\}$ -martingale difference $\left\{ \frac{u_t}{\widehat{\lambda}_t^2}, t \in \mathbb{Z} \right\}$. Now by a Taylor expansion of $\frac{1}{\lambda_t^2(\theta_r)}$ around θ_0 , the left-hand side of (7.7) becomes

$$\frac{-2(\widehat{\theta}_r - \theta_0)'}{\sqrt{n}} \sum_{t=1}^n \frac{u_t}{\widehat{\lambda}_t^2 \lambda_t^3(\theta^*)} \frac{\partial \lambda_t(\theta^*)}{\partial \theta},$$

and (7.7) follows from the assumptions **A1** and **A10**, the asymptotic normality of $\sqrt{n}(\hat{\theta}_r - \theta_0)$, which implies that

$$\hat{\theta}_r - \theta_0 = n^{-1/2}O_p(1),$$

and the ergodic theorem.

iii) Proof of (3.14c) Result (3.14c) is an obvious consequence of the strong consistency of $\hat{\theta}_r$ (cf. (3.4)) for all $r > 0$.

iv) Proof of (3.14d) From the consistency of \hat{r}_1 and the \sqrt{n} -consistency of $\hat{\theta}_r$ for all $r > 0$ we have

$$\begin{aligned} \sqrt{n}(\hat{\theta}_{\hat{r}_1} - \theta_0) &= \sqrt{n}(\hat{\theta}_{r_0} - \theta_0) + \sqrt{n}(\hat{\theta}_{\hat{r}_1} - \hat{\theta}_{r_0}) \\ &= \sqrt{n}(\hat{\theta}_{r_0} - \theta_0) + o_p(1), \end{aligned}$$

so the result follows from Theorem 3.2 while replacing r by r_0 (cf. (3.6)) and using the fact that, under (4.11), $I_{r_0} = J_{r_0}$. ■

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